Note: Within nine months of the publication of the mention of the grant of the European patent in the European Patent Bulletin, any person may give notice to the European Patent Office of opposition to that patent, in accordance with the Implementing Regulations. Notice of opposition shall not be deemed to have been filed until the opposition fee has been paid. (Art. 99(1) European Patent Convention).
The present invention relates to a teat cup shell for a teat cup adapted to be used for milking animals. The invention further relates to a teat cup, and to an arrangement for automatically milking animals comprising a teat cup.

BACKGROUND

A teat cup forms a part of a milking machine, which part is attached to a teat of an animal to be milked. Traditionally a teat cup comprises a resilient liner and a teat cup shell. The teat to be milked is placed in the liner at one end of the liner, and a vacuum is applied to an opposite end of the liner. The teat cup shell is arranged around a portion of the liner.

Between the teat cup shell and the liner a pulsation chamber is formed. The pulsation chamber is alternately connected to a vacuum source and to atmospheric pressure.

Teat cups of a more complex construction are also known. For instance, WO 2013/095290 discloses such a teat cup comprising a connector and a cartridge. The cartridge comprises a sleeve, having a first end and a second end, and a teat cup liner mounted in the sleeve and having an inner space for receiving a teat. A pulsation chamber is formed in the cartridge. The connector is configured to connect a milk conduit to the cartridge.

In an arrangement for automatically milking animals, sometimes called a milking robot, teat cups are automatically attached to the teats of an animal to be milked. Commonly a robot arm of the arrangement handles the teat cups.

WO 2005/122753 discloses a gripper device mountable on a robot arm of a milking robot provided for automatically attaching teat cups to the teats of a milking animal. The gripper device comprises an electromagnet for gripping teat cups made of a magnetic material. The electromagnet includes a coil feedable with a current, a core of a magnetic material arranged at least partly within the coil, and a support structure for holding the electromagnet. The core comprises two end portions in a single face of the electromagnet, wherein the two end portions constitute different poles of the electromagnet, and are shaped to be engagable with a teat cup in a close fit.

In an arrangement for automatically milking animals comprising an electromagnetic device for handling a teat cup, such as the above mentioned gripper device, the holding force between the electromagnetic device and a relevant teat cup sets a limit for the movements to be performed by the robot arm when handling the teat cup. Due to the inertia of the teat cup and the flexible milk tube attached thereto, sudden directional changes of the robot arm may cause the electromagnetic device to lose the teat cup. Moreover, an animal being milked may accidentally knock the teat cup out of the electromagnetic device.

SUMMARY

It is an object of the present invention to provide a strong holding force between a teat cup shell of a teat cup and an electromagnetic device for handling a teat cup.

According to an aspect of the invention, the object is achieved by a teat cup shell adapted to form at least a part of an outer limiting portion of a teat cup and being adapted to be held by an electromagnetic device. The teat cup shell comprises a substantially tubular body having a centre axis. A plane extending along the centre axis defines a first shell portion and a second shell portion on opposite sides of the plane. The first shell portion comprises a magnetic material, and an even outer surface adapted to abut against at least one surface of the electromagnetic device. The first shell portion and the second shell portion differ from each other with respect to material composition and/or material thickness. The amount of magnetic material in the first shell portion is higher than in the second shell portion.

Since the first shell portion comprises a magnetic material and the first shell portion and the second shell portion differ from each other with respect to material composition and/or material thickness, there is provided a teat cup shell for a teat cup, which combines a specific weight of the teat cup shell with a strong magnetic holding force against the electromagnetic device at the first shell portion. As a result, the above mentioned object is achieved.

It has been realized by the inventor that the holding force of an electromagnetic device may only be increased to a certain extent within the physically available space at an end of a robot arm, and while remaining within desired upper electric power limits. It has further been realized by the inventor that an asymmetrical teat cup shell permits the weight of the teat cup shell to be kept within a desired range while providing enough magnetic material in the portion of the teat cup shell abutting against the electromagnetic device to ensure a strong holding force within the above mentioned constraints of the electromagnetic device. That is, the amount of magnetic material in the teat cup shell in the first shell portion is higher than in the second shell portion. It is to be understood that this encompasses embodiments without any magnetic material in the second shell portion.

The teat cup may form a part of a milking machine and be adapted to be attached to a teat of an animal to be milked. A teat cup liner is arranged inside the teat cup shell. The teat to be milked is placed in the liner at one end of the liner, and a vacuum is applied to an opposite end of the liner by the milking machine. The milking machine may form part of an arrangement for automatically milking animals. The arrangement for automatically milking animals may comprise at least one robot arm with
an electromagnetic device for handling the teat cup.

[0013] The term "teat cup shell" encompasses a part adapted to form an outer portion of a teat cup and adapted to be held by an electromagnetic device, or by a human operator should so be required. A teat cup shell may form a part which is removable from other parts of a teat cup. Alternatively, a teat cup shell may form an integrated part of a teat cup, which integrated part may not be removed from other parts of a teat cup without rupturing the teat cup. The term "teat cup liner", or simply "liner", encompasses a resilient part of a teat cup adapted to receive a teat of an animal. A teat cup liner may be removable from other parts of a teat cup. Alternatively, the teat cup liner may form an integrated part of a teat cup, which integrated part may not be removed from other parts of a teat cup without rupturing the teat cup. The term magnetic material refers to a material which is attracted to a magnet.

[0014] According to embodiments, the first shell portion may have a higher weight than the second shell portion. In this manner a larger amount of a total desired weight of the teat cup shell may emanate from the first shell portion than from the second shell portion. Accordingly, the first shell portion may comprise a larger amount of magnetic material than the second shell portion to ensure a strong magnetic holding force within the desired weight constraints. These embodiments encompass in particular a teat cup shell comprising a circumferential layer made from magnetic material, and encompass also a teat cup shell comprising magnetic material homogeneously mixed with a plastic material.

[0015] According to embodiments, the teat cup shell may comprise a substantially circular outer cross section seen along the centre axis. The electromagnetic device may have a corresponding concave contact surface adapted to abut closely with the teat cup shell. In this manner, the contact between the teat cup shell and the electromagnetic device may be the same irrespective of the angular position of the teat cup shell around its centre axis. Small angular differences in the position of the teat cup shell, when held by the electromagnetic device, will not affect the magnetic holding force to any substantial extent.

[0016] According to embodiments, the second shell portion comprises a magnetic material, and at least a portion of the first shell portion has a thicker material thickness than the second shell portion. In this manner, a strong magnetic force between the electromagnetic device and the first shell portion may be ensured within the weight constraints of the teat cup shell. These embodiments encompass a teat cup shell comprising a circumferential layer made from magnetic material, as well as e.g. a teat cup shell comprising magnetic material homogeneously mixed with a plastic material.

[0017] According to embodiments, at least a portion of the first shell portion may have a material thickness of 2-6 mm, and the second shell portion may have a material thickness of 1-3 mm. In this manner, a strong teat cup shell within a desired weight range may be provided.

[0018] According to embodiments, the second shell portion may comprise a plastic material, such as a polymer.

[0019] According to embodiments, the first shell portion may comprise a plastic material, such as a polymer.

[0020] According to embodiments, the magnetic material of the first shell portion may comprise a ferritic stainless steel material. In this manner, a stainless first shell portion having magnetic properties may be provided. Similarly, the second shell portion may comprise a ferritic stainless steel material. The entire teat cup shell may be made form a ferritic stainless steel material.

[0021] According to a further aspect of the invention, there is provided a teat cup comprising a teat cup shell and a teat cup liner. The teat cup shell is a teat cup shell according to aspects and/or embodiments disclosed herein. In this manner, a teat cup providing a strong magnetic holding force against an electromagnetic device at the first shell portion is provided.

[0022] According to a further aspect of the invention there is provided an arrangement for automatically milking animals comprising at least one robot arm adapted to attach at least one teat cup to a teat of an animal. The robot arm comprises an electromagnetic device adapted to handle the at least one teat cup. The arrangement comprises a least one teat cup according to aspects and/or embodiments disclosed herein. In this manner, an arrangement for automatically milking animals providing a strong magnetic holding force between the electromagnetic device and the at least one teat cup may be provided.

[0023] According to embodiments, the arrangement comprises a teat cup magazine adapted to store the at least one teat cup during non-milking periods. The teat cup magazine may be adapted to always store the at least one teat cup with the first shell portion facing in one and the same direction to ensure the electromagnetic device abutting against the first shell portion. In this manner, a reliable picking up of the teat cup may be ensured.

[0024] According to embodiments, the teat cup magazine may comprise a first roller and a second roller extending substantially in parallel. The at least one teat cup may comprise a first surface and a second surface extending substantially perpendicularly to the centre axis of the teat cup shell. The first surface may be adapted to abut against the first roller and the second surface may be adapted to abut against the second roller. In this manner, it may be ensured that the at least one teat cup is always stored with the first shell portion facing in one and the same direction.

[0025] Further features of, and advantages with, the present invention will become apparent when studying the appended claims and the following detailed description.
Various aspects of the invention, including its particular features and advantages, will be readily understood from the example embodiments discussed in the following detailed description and the accompanying drawings, in which:

Fig. 1 illustrates a teat cup shell according to embodiments,
Fig. 2 illustrates a cross section through the teat cup shell in Fig. 1,
Fig. 3 illustrates a cross section through a teat cup shell according to embodiments,
Fig. 4 illustrates a teat cup according to embodiments,
Fig. 5 illustrates a cross section through the teat cup shell in Fig. 4,
Fig. 6 illustrates an arrangement for automatically milking animals according to embodiments,
Fig. 7 illustrates a teat cup magazine of the arrangement of Fig. 6,
Fig. 8 illustrates a portion of the teat cup magazine of Fig. 7, and
Fig. 9 illustrates a teat cup of the teat cup magazine of Figs. 7 and 8.

DETAILED DESCRIPTION

Aspects of the present invention will now be described more fully. Like numbers refer to like elements throughout. Well-known functions or constructions will not necessarily be described in detail for brevity and/or clarity.

Fig. 1 illustrates a teat cup shell 2 according to embodiments. Fig. 2 illustrates a cross section through the teat cup shell 2 in Fig. 1 along line II-II. The teat cup shell 2 is adapted to form at least part of an outer limiting portion of a teat cup, such as the teat cup illustrated in Fig. 3. The teat cup shell 2 comprises a substantially tubular body 5 having a centre axis 4. A plane 6 extends along the centre axis 4 and defines a first shell portion 8 and a second shell portion 10, on opposite sides of the plane 6. In Fig. 2 the plane extends perpendicularly to the centre axis 4, into and out of the cross section illustrated in Fig. 3, i.e. the first and the second shell portions 8, 10 are arranged on opposite sides of the line indicating the centre axis 4. The first shell portion 8 comprises an even outer surface 12 adapted to abut against at least one surface of an electromagnetic device. The first shell portion 8 and the second shell portion 10 differ from each other with respect to material thickness. The first shell portion 8 is thinner than the second shell portion 10. Thus, the first shell portion 8 has a higher weight than the second shell portion 10. In total the teat cup shell 2 has a weight similar to that of a teat cup shell with an even shell thickness lying between the thicknesses of the first and second shell portions 8, 10.

The teat cup shell 2 comprises a magnetic material, and is thus adapted to be held by an electromagnetic device. That is, the first shell portion 8 comprises a magnetic material. Also the second shell portion 10 comprises a magnetic material. The entire teat cup shell 2 may be made from a magnetic material. Thus, the teat cup shell 2 forms a circumferential layer made from magnetic material. The magnetic material may for instance be a ferritic stainless steel. An alternative material may be carbon steel, in which case the surface of the teat cup shell 2 may be coated with a non-corroding material, e.g. chromium or a carbide.

The teat cup shell 2 comprises a substantially circular outer cross section seen along the centre axis 4. Similarly, the teat cup shell 2 comprises a substantially circular inner cross section seen along the centre axis 4. The substantially circular inner cross section is offset in relation to the substantially circular outer cross section. In this manner the thicker thickness of the first shell portion 8 in relation to the thickness of the second shell portion 10 is achieved. As illustrated in Fig. 2, the substantially circular inner cross section is offset to the right in relation to the substantially circular outer cross section.

Fig. 3 illustrates a cross section through a teat cup shell 2 according to embodiments. Again, the teat cup shell 2 is adapted to form at least part of an outer limiting portion of a teat cup. The teat cup shell 2 comprises a substantially tubular body having a centre axis 4. A plane extends along the centre axis 4 and defines a first shell portion 8 and a second shell portion 10, on opposite sides of the plane 6. In Fig. 3 the plane extends perpendicularly to the centre axis 4, into and out of the cross section illustrated in Fig. 3, i.e. the first and the second shell portions 8, 10 are arranged on opposite sides of the line indicating the centre axis 4. The first shell portion 8 comprises an even outer surface 12 adapted to abut against at least one surface of an electromagnetic device.

The first shell portion 8 comprises a plastic material. The second shell portion 10 comprises a plastic material. The plastic material may comprise a polymer with low elasticity, such as polyethylene, polypropylene, etc. The first shell portion 8 comprises a bar 14 of a magnetic material embedded in the plastic material of the first shell portion 8. Thus, the teat cup shell 2 is adapted to be held by an electromagnetic device. Also, in this manner the first shell portion 8 and the second shell portion 10 differ from each other with respect to material composition.

Fig. 4 illustrates a teat cup 16 according to embodiments. Fig. 5 illustrates a cross section through the teat cup shell 2 in Fig. 4 along line V-V. The teat cup 16 comprises a teat cup shell 2 and a teat cup liner 18. The teat cup shell 2 is a teat cup shell 2 as disclosed in connection with Figs. 1 and 2. Alternatively, the teat cup shell 2 may be a teat cup shell 2 as disclosed in connection with Fig. 3.

Inside the liner 18 a teat space 20 is formed. A
An inner layer 24 is formed inside the teat cup shell 2. The inner layer 24 may comprise a plastic material and abuts against the magnetic material of the teat cup shell 2. Accordingly, an outer portion of the teat cup shell 2 forms a circumferential layer made from magnetic material. The inner layer 24 may form part of the teat cup shell 2. The inner layer 24 may form an integrated unit with the teat cup liner 18. The teat cup liner 18 may comprise a resilient material such as rubber, black rubber, silicone rubber, elastic polymers, such as thermoplastic elastomers, TPE, or any other suitable elastic material. The plastic material of the inner layer 24 may comprise a polymer with low elasticity, such as polyethylene, polypropylene, etc.

Fig. 6 illustrates an arrangement 26 for automatically milking animals according to embodiments. In these embodiments the arrangement comprises a rotary platform 28 upon which the animals 30 stand while being milked. The arrangement 26 for automatically milking animals comprises at least one robot arm 32 adapted to attach at least one teat cup to a teat of an animal 30. The robot arm 32 comprises an electromagnetic device 34 adapted to handle the at least one teat cup. A teat cup magazine is arranged next to each milking position on the rotary platform 28.

Fig. 7 illustrates a teat cup magazine 36 of the arrangement 26 of Fig. 6. The teat cup magazine 36 is adapted to store at least one teat cup 16 during non-milking periods. The at least one teat cup 16 is a teat cup 16 according to aspects and/or embodiments disclosed herein. In these embodiments the teat cup magazine 36 is adapted to store four teat cups 16. Flexible milk tubes 37 are connected to the teat cups 16. In Fig. 7 a robot arm 32 comprising an electromagnetic device 34 is about to pick a teat cup 16 from the magazine 36. Each flexible milk tube 37 comprises two conduits in a side-by-side arrangement. Thus, the flexible milk tube 37 will twist about its longitudinal direction only to a limited degree, in particular in the teat cup magazine 36 where the flexible milk tube 37 abuts against one or more supporting elements.

Fig. 8 illustrates a portion of the teat cup magazine 36 of Fig. 7. The teat cup magazine 36 is adapted to always store the teat cups 16 with the first shell portion 8 facing in one and the same direction to ensure that the magnetic device 34 abuts against the first shell portion 8. For this purpose the teat cup magazine 36 comprises a first roller 38 and a second roller 40 extending substantially in parallel.

Fig. 9 illustrates a teat cup 16 of the teat cup magazine 36 of Figs. 7 and 8. The teat cup 16 comprises a first surface 42 and a second surface 44, both extending substantially perpendicularly to a centre axis 4 of a teat cup shell 2 of the teat cup 16. The first surface 42 is adapted to abut against the first roller 38 and the second surface 44 is adapted to abut against the second roller 40 when the teat cup 16 is stored in the teat cup magazine 36, see Fig. 8.

Fig. 10 illustrates a teat cup 16 of the teat cup magazine 36 of Figs. 7 and 8. The teat cup 16 comprises a first surface 42 and a second surface 44, both extending substantially perpendicularly to a centre axis 4 of a teat cup shell 2 of the teat cup 16. The first surface 42 is adapted to abut against the first roller 38 and the second surface 44 is adapted to abut against the second roller 40 when the teat cup 16 is stored in the teat cup magazine 36, see Fig. 8.

As illustrated in Fig. 7, a teat cup 16 is collected from the magazine 36 by the robot arm 32. The teat cup 16 is connected to a teat of an animal. After milking has been completed, the teat cup 16 is retracted by its flexible milk tube 37 into the teat cup magazine 36 to abut with its first and second surfaces 42, 44 against the first and second rollers 38, 40, to store the teat cup 16 with the first shell portion 8 accessible for renewed abuttal against the electromagnetic device 34 of the robot arm 32 during attachment of the teat cup 16 to a subsequent teat.

This invention should not be construed as limited to the embodiments set forth herein. A person skilled in the art will realize that different features of the embodiments disclosed herein may be combined to create embodiments other than those described herein, without departing from the scope of the present invention, as defined by the appended claims. For instance, the teat cup shell may have a different cross-section shape than round, e.g. square or oval. Although the invention has been described with reference to example embodiments, many different alterations, modifications and the like will become apparent for those skilled in the art. For instance, the arrangement for automatically milking animals may be an arrangement for milking only one animal at a time comprising a milking stall housing one animal. Therefore, it is to be understood that the foregoing is illustrative of various example embodiments and that the invention is defined only by the appended claims.

As used herein, the term “comprising” or “comprises” is open-ended, and includes one or more stated features, elements, steps, components or functions but does not preclude the presence or addition of one or more other features, elements, steps, components, functions or groups thereof.

Claims

1. A teat cup shell (2) adapted to form at least a part of an outer limiting portion of a teat cup and being adapted to be held by an electromagnetic device, the teat cup shell (2) comprising a substantially tubular body (5) having a centre axis (4), wherein a plane (6) extending along the centre axis (4) defines a first shell portion (8) and a second shell portion (10) on opposite sides of the plane (6), wherein the first shell portion (8) comprises a magnetic material, and an even outer surface (12) adapted to abut against at least one surface of the electromagnetic device, characterised in that the first shell portion
The teat cup shell (2) according to claim 4, wherein at least a portion of the first shell portion (8) has a thicker material thickness than the second shell portion (10).

6. The teat cup shell (2) according to any one of claims 1 - 3, wherein the second shell portion (10) comprises a plastic material, such as a polymer.

7. The teat cup shell (2) according to claim 6, wherein the first shell portion (8) comprises a plastic material, such as a polymer.

8. The teat cup shell (2) according to any one of the preceding claims, wherein the magnetic material of the first shell portion (8) comprises a ferritic stainless steel material.

9. A teat cup (16) comprising a teat cup shell (2) and a teat cup liner (18), characterised in that the teat cup shell (2) is a teat cup shell (2) according to any one of the preceding claims.

10. An arrangement (26) for automatically milking animals comprising at least one robot arm (32) adapted to attach at least one teat cup (16) to a teat of an animal, the at least one robot arm (32) comprising an electromagnetic device (34) adapted to handle the at least one teat cup (16), characterised in that the arrangement (26) comprises at least one teat cup (16) according to claim 9.

11. The arrangement (26) according to claim 10, comprising a teat cup magazine (36) adapted to store the at least one teat cup (16) during non-milking periods, wherein in the teat cup magazine (36) is adapted to always store the at least one teat cup (16) with the first shell portion (8) facing in one and the same direction to ensure the electromagnetic device (34) abutting against the first shell portion (8).

12. The arrangement (26) according to claim 11, wherein the teat cup magazine (36) comprises a first roller (38) and a second roller (40) extending substantially in parallel, wherein the at least one teat cup (16) comprises a first surface (42) and a second surface (44) extending substantially perpendicularly to the centre axis (4) of the teat cup shell (2), and wherein the first surface (42) is adapted to abut against the first roller (38) and the second surface (44) is adapted to abut against the second roller (40) when the at least one teat cup (16) is stored in the teat cup magazine (36).

Patentansprüche

1. Melkbecherschale (2), die zum Bilden mindestens eines Teils eines äußeren Abgrenzungsabschnitts eines Melkbechers ausgelegt ist und ausgelegt ist, um durch eine elektromagnetische Vorrichtung ge-halten zu werden, wobei die Melkbecherschale (2) einen im Wesentlichen röhrenförmigen Körper (5) umfasst, der eine Mittelachse (4) aufweist, wobei eine Ebene (6), die sich entlang der Mittelachse (4) erstreckt, einen ersten Schalenabschnitt (8) und einen zweiten Schalenabschnitt (10) auf gegenüberliegenden Seiten der Ebene (6) aufweist, wobei der erste Schalenabschnitt (8) ein magnetisches Material umfasst, und einen flache äußere Oberfläche (12), die zum Angrenzen an mindestens eine Oberfläche der elektromagnetischen Vorrichtung ausgelegt ist, dadurch gekennzeichnet, dass sich der erste Schalenabschnitt (8) und der zweite Schalenabschnitt (10) voneinander in Bezug auf die Materialzusammensetzung und/oder Materialdicke unterscheiden, sodass die Menge an magnetischem Material im ersten Schalenabschnitt (8) höher ist als im zweiten Schalenabschnitt (10).

2. Melkbecherschale (2) nach Anspruch 1, wobei der erste Schalenabschnitt (8) ein höheres Gewicht als der zweite Schalenabschnitt (10) aufweist.

3. Melkbecherschale (2) nach Anspruch 1 oder 2, umfassend einen im Wesentlichen kreisförmigen äußeren Querschnitt, wenn entlang der Mittelachse (4) betrachtet.

4. Melkbecherschale (2) nach einem der vorhergehenden Ansprüche, wobei der zweite Schalenabschnitt (10) ein magnetisches Material umfasst, und wobei mindestens ein Abschnitt des ersten Schalenabschnitts (8) eine dickere Materialdicke als der zweite Schalenabschnitt (10) aufweist.
5. Melkbecherschale (2) nach Anspruch 4, wobei mindestens ein Abschnitt des ersten Schalenabschnitts (8) eine Materialdicke von 2 bis 6 mm aufweist, und der zweite Schalenabschnitt (10) eine Materialdicke von 1 bis 3 mm aufweist.

6. Melkbecherschale (2) nach einem der Ansprüche von 1 bis 3, wobei der zweite Schalenabschnitt (10) ein Kunststoffmaterial wie ein Polymer umfasst.

7. Melkbecherschale (2) nach Anspruch 6, wobei der erste Schalenabschnitt (8) ein Kunststoffmaterial wie ein Polymer umfasst.

8. Melkbecherschale (2) nach einem der vorhergehenden Ansprüche, wobei das magnetische Material des ersten Schalenabschnitts (8) ein ferritisches rostfreies Stahlmaterial umfasst.

9. Melbecher (16), umfassend eine Melkbecherschale (2) und eine Melkbecherauskleidung (18), dadurch gekennzeichnet, dass die Melkbecherschale (2) eine Melkbecherschale (2) nach einem der vorhergehenden Ansprüche ist.

10. Anordnung (26) zum automatischen Melken von Tieren, umfassend mindestens einen Roboterarm (32), der zum Anbringen mindestens eines Melkbechers (16) an einer Zitze eines Tiers ausgelegt ist, wobei der mindestens eine Roboterarm (32) eine elektromagnetische Vorrichtung (34) umfasst, die zum Handhaben des mindestens einen Melkbechers (16) ausgelegt ist, dadurch gekennzeichnet, dass die Melkbecherschale (2) nach Anspruch 9 umfasst.

11. Anordnung (26) nach Anspruch 10, umfassend ein Melkbechermagazin (36), das zum Lagern mindestens eines Melkbechers (16) während Nicht-Melkzeiträumen ausgelegt ist, wobei das Melkbechermagazin (36) ausgelegt ist, um mindestens einen Melkbecher (16) zu lagern, dessen erster Schalenabschnitt (8) in ein- und dieselbe Richtung weist, um sicherzustellen, dass die elektromagnetische Vorrichtung (34) an den ersten Schalenabschnitt (8) angrenzt.

12. Anordnung (26) nach Anspruch 11, wobei das Melkbechermagazin (36) eine erste Walze (38) und eine zweite Walze (40), die sich im Wesentlichen parallel erstrecken, umfasst, wobei der mindestens eine Melkbecher (16) eine erste Oberfläche (42) und eine zweite Oberfläche (44) umfasst, die sich im Wesentlichen senkrecht zur Mittelachse (4) der Melkbecherschale (2) erstrecken, und wobei die erste Oberfläche (42) zum Angrenzen an die erste Walze (38) ausgelegt ist und die zweite Oberfläche (44) zum Angrenzen an die zweite Walze (40) ausgelegt ist, wenn der mindestens eine Melkbecher (16) in dem Melkbechermagazin (36) gelagert ist.

**Revendications**

1. Enveloppe de gobelet trayeur (2) conçue pour former au moins une partie d’une partie limitante externe d’un gobelet trayeur et étant conçue pour être maintenue par un dispositif électromagnétique, l’enveloppe de gobelet trayeur (2) comprenant un corps sémiblement tubulaire (5) possédant un axe central (4), dans laquelle un plan (6) s’étendant le long de l’axe central (4) définit une première partie d’enveloppe (8) et une seconde partie d’enveloppe (10) sur des côtés opposés du plan (6), dans laquelle la première partie d’enveloppe (8) comprend un matériau magnétique, et une surface externe régulière (12) conçue pour venir en butée contre au moins une surface du dispositif électromagnétique, caractérisée en ce que la première partie d’enveloppe (8) et la seconde partie d’enveloppe (10) diffèrent l’une de l’autre en ce qui concerne la composition de matériau et/ou l’épaisseur de matériau, de telle sorte que la quantité de matériau magnétique dans la première partie d’enveloppe (8) est plus élevée que dans la seconde partie d’enveloppe (10).

2. Enveloppe de gobelet trayeur (2) selon la revendication 1, dans laquelle la première partie d’enveloppe (8) a un poids plus élevé que la seconde partie d’enveloppe (10).

3. Enveloppe de gobelet trayeur (2) selon la revendication 1 ou 2, comprenant une coupe transversale externe sensiblement circulaire observée le long de l’axe central (4).

4. Enveloppe de gobelet trayeur (2) selon l’une quelconque des revendications précédentes, dans laquelle la seconde partie d’enveloppe (10) comprend un matériau magnétique, et dans laquelle au moins une partie de la première partie d’enveloppe (8) a une épaisseur de matériau plus grande que la seconde partie d’enveloppe (10).

5. Enveloppe de gobelet trayeur (2) selon la revendication 4, dans laquelle au moins une partie de la première partie d’enveloppe (8) a une épaisseur de matériau de 2 à 6 mm, et la seconde partie d’enveloppe (10) a une épaisseur de matériau de 1 à 3 mm.

6. Enveloppe de gobelet trayeur (2) selon l’une quelconque des revendications 1 à 3, dans laquelle la seconde partie d’enveloppe (10) comprend une matière plastique, telle qu’un polymère.

7. Enveloppe de gobelet trayeur (2) selon la revend-
cation 6, dans laquelle la première partie d’enveloppe (8) comprend une matière plastique, telle qu’un polymère.

8. Enveloppe de gobelet trayeur (2) selon l’une quelconque des revendications précédentes, dans laquelle le matériau magnétique de la première partie d’enveloppe (8) comprend un matériau de tôle d’acier inoxydable ferritique.

9. Gobelet trayeur (16) comprenant une enveloppe de gobelet trayeur (2) et un revêtement de gobelet trayeur (18), caractérisé en ce que l’enveloppe de gobelet trayeur (2) est une enveloppe de gobelet trayeur (2) selon l’une quelconque des revendications précédentes.

10. Agencement (26) pour la traite automatique d’animaux comprenant au moins un bras robotisé (32) conçu pour fixer au moins un gobelet trayeur (16) à un trayon d’un animal, ledit au moins un bras robotisé (32) comprenant un dispositif électromagnétique (34) conçu pour manipuler ledit au moins un gobelet trayeur (16), caractérisé en ce que l’agencement (26) comprend au moins un gobelet trayeur (16) selon la revendication 9.

11. Agencement (26) selon la revendication 10, comprenant un chargeur à gobelet trayeur (36) conçu pour stocker ledit au moins un gobelet trayeur (16) pendant les périodes hors traite, dans lequel le chargeur à gobelet trayeur (36) est conçu pour stocker toujours ledit au moins un gobelet trayeur (16) avec la première partie d’enveloppe (8) faisant face dans une même direction pour garantir que le dispositif électromagnétique (34) vienne en butée contre la première partie d’enveloppe (8).

12. Agencement (26) selon la revendication 11, dans lequel le chargeur à gobelet trayeur (36) comprend un premier rouleau (38) et un second rouleau (40) s’étendant sensiblement en parallèle, dans lequel ledit au moins un gobelet trayeur (16) comprend une première surface (42) et une seconde surface (44) s’étendant de manière essentiellement perpendiculaire par rapport à l’axe central (4) de l’enveloppe de gobelet trayeur (2), et dans lequel la première surface (42) est conçue pour venir en butée contre le premier rouleau (38) et la seconde surface (44) est conçue pour venir en butée contre le second rouleau (40) lorsque ledit au moins un gobelet trayeur (16) est stocké dans le chargeur à gobelet trayeur (36).
REFERENCES CITED IN THE DESCRIPTION

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