(45) Date of publication and mention of the grant of the patent:
30.05.2018 Bulletin 2018/22

(21) Application number: 08861584.4

(22) Date of filing: 09.12.2008

(51) Int Cl.:
G03F 7/20 (2006.01)

(86) International application number:
PCT/NL2008/050785

(87) International publication number:
WO 2009/078708 (25.06.2009 Gazette 2009/26)

(54) Diffraction-based method and detection system for determining an overlay error, and corresponding lithographic apparatus
Auf Diffraction basierendes Verfahren und System zur Bestimmung von einem Überlagerungsfehler, und entsprechender lithographischer Apparat
Procédé et système de détection basés sur la diffraction pour déterminer une erreur de recouvrement, et appareil de lithographie correspondant

(84) Designated Contracting States:
AT BE BG CH CY CZ DE DK EE ES FI FR GB GR HR HU IE IS IT LI LT LU LV MC MT NL NO PL PT RO SE SI SK TR


(43) Date of publication of application:
01.09.2010 Bulletin 2010/35

(73) Proprietor: ASML Netherlands B.V.
5504 DR Veldhoven (NL)

(72) Inventor: DEN BOEF, Arie, Jeffrey
NL-5581 NA Waalre (NL)

(74) Representative: Peters, John Antoine et al
ASML Netherlands BV
Corporate Intellectual Property
P.O. Box 324
5500 AH Veldhoven (NL)

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WO-A1-2005/069082
US-A- 4 332 473
US-B1- 6 317 211

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THE PRESENT INVENTION RELATES TO A METHOD OF DETERMINING AN OVERLAY ERROR, TO A DETECTION SYSTEM CONFIGURED TO DETERMINE SAID OVERLAY ERROR, AND TO A LITHOGRAPHIC APPARATUS COMPRISING THE DETECTION SYSTEM.

BACKGROUND

A lithographic apparatus is a machine that applies a desired pattern onto a substrate, usually onto a target portion of the substrate. A lithographic apparatus can be used, for example, in the manufacture of integrated circuits (ICs). In that instance, a patterning device, which is alternatively referred to as a mask or a reticle, may be used to generate a circuit pattern to be formed on an individual layer of the IC. This pattern can be transferred onto a target portion (e.g. including part of, one, or several dies) on a substrate (e.g. a silicon wafer). Transfer of the pattern is typically via imaging onto a layer of radiation-sensitive material (resist) provided on the substrate. In general, a single substrate will contain a network of adjacent target portions that are successively patterned. Known lithographic apparatus include so-called steppers, in which each target portion is irradiated by exposing an entire pattern onto the target portion at one time, and so-called scanners, in which each target portion is irradiated by scanning the pattern through a radiation beam in a given direction (the "scanning"-direction) while synchronously scanning the substrate parallel or anti-parallel to this direction. It is also possible to transfer the pattern from the patterning device to the substrate by imprinting the pattern onto the substrate.

For lithographic processing, the location of patterns in subsequent layers on the substrate should be as precise as possible for a correct definition of device features on the substrate, which features all should have sizes within specified tolerances. The overlay error (i.e., the mismatch between subsequent layers) should be within well-defined tolerances for creating functional devices.

To this end, an overlay measurement module is generally used for determining the overlay error of a pattern on the substrate with a mask pattern as defined in a resist layer on top of the pattern.

The overlay measurement module typically performs the measurement with optics. The position of the mask pattern in the resist layer relative to the position of the pattern on the substrate is determined by measuring an optical response from an optical marker which is illuminated by an optical source. The signal generated by the optical marker is measured by a sensor arrangement. Using the output of the sensors the overlay error can be derived. Typically, the patterns on which overlay error are measured are located within a scribe lane in between target portions.

Two basic concepts are known for overlay metrology.

A first concept relates to measurement of overlay error that is image based. A position of an image of the pattern on the substrate is compared to the position of the mask pattern in the resist layer. From the comparison the overlay error is determined. An example to measure overlay error is the so-called box-in-box structure, in which the position of an inner box within an outer box is measured relative to the position of the outer box.

Image based overlay error measurement may be sensitive to vibrations and also to the quality of focus during measurement. For that reason, image based overlay error measurement may be less accurate in environments that are subjected to vibrations, such as within a track system. Also, image-based overlay measurements may be susceptible to aberrations in the optics that may further reduce the accuracy of the measurement.

A second concept relates to measurement of overlay error that is diffraction based. In the pattern layer on the substrate a first grating is located, and in the resist layer a second grating is located with a pitch that is, substantially identical to the first grating. The second grating is located nominally on top of the first grating. By measuring the intensity of the diffraction pattern as generated by the first and second grating superimposed on each other, a measure for the overlay error may be obtained. If some overlay error is present between the first and second grating, this is detectable from the diffraction pattern.

In diffraction based overlay error measurement, only the first and second gratings may be illuminated, since light that reflects from adjacent regions around the gratings interferes with the intensity level of the diffraction pattern. However, a trend emerges to have overlay error measurements close to critical structures within a die (and not necessarily within the scribe lane). Also, there is a demand to reduce the size of gratings so as to have a larger area available for circuitry. To some extent, such demands can be accommodated by a reduction of the cross section of the illumination beam that impinges on the first and second gratings so as to avoid illumination of the region outside the gratings. However, the minimal cross-section of the illumination beam is fundamentally limited by the laws of physics (i.e. limitation due to diffraction). Below, the cross-sectional size in which diffraction of the beam occurs will be referred as the diffraction limit. Document US-B 1-6317211 discloses a metrology apparatus for determining bias and overlay errors in a substrate.
formed by a lithographic process, the apparatus including an aperture between the objective lens and the image plane adapted to set the effective numerical aperture of the apparatus. Document WO-A1-2005/069082 discloses a method and an apparatus for measuring a dimension on a substrate, wherein a target pattern is provided. The target pattern is illuminated so that at least one non-zero diffracted order is detected. The response of the non-zero diffracted order to variation in the printed characteristic dimension relative to nominal is used to determine the dimension of interest, such as critical dimension or overlay, on the substrate.

SUMMARY

[0011] It is desirable to have an improved diffraction based overlay error measurement system and method.
[0012] According to an aspect of the invention, there is provided a method of determining an overlay error, as defined in claim 1. Further aspects of the method are defined in dependent claims 2-5.
[0013] According to an aspect of the invention, there is provided a detection system configured to determine an overlay error, as defined in claim 6. Further aspects of the detection system are defined in dependent claim 7.
[0014] According to an aspect of the invention, there is provided a lithographic apparatus including the aforementioned detection system, as defined in claim 8. Further aspects of the lithography apparatus are defined in dependent claim 9.

BRIEF DESCRIPTION OF THE DRAWINGS

[0015] Embodiments, including embodiments of the invention, will now be described, by way of example only, with reference to the accompanying schematic drawings in which corresponding reference symbols indicate corresponding parts, and in which:

Figure 1 depicts a lithographic apparatus according to an embodiment of the invention; Figures 2a, 2b, 2c illustrate overlay error metrology based on diffraction according to an embodiment; Figures 3a, 3b depict a diffraction based overlay error detection system in accordance with an embodiment of the present invention, during a first measurement and a second measurement respectively; Figure 4a illustrates exemplary measurements of intensity of a minus first order and first order diffracted beams as function of overlay error; Figure 4b illustrates a difference of intensity between the minus first order and first order diffracted beams as function of overlay error; and Figure 5 depicts a correlation between image based overlay error and the diffraction based overlay error as determined according to the present invention.

DETAILED DESCRIPTION

[0016] Figure 1 schematically depicts a lithographic apparatus according to one embodiment of the invention. The apparatus includes an illumination system (illuminator) IL configured to condition a radiation beam B (e.g. UV radiation or EUV radiation); a patterning device support or a support structure (e.g. a mask table) MT constructed to support a patterning device (e.g. a mask) MA and connected to a first positioner PM configured to accurately position the patterning device in accordance with certain parameters; a substrate table (e.g. a wafer table) WT connected to a second positioner PW configured to accurately position the substrate in accordance with certain parameters; and a projection system (e.g. a refractive projection lens system) PS configured to project a pattern imparted to the radiation beam B by patterning device MA onto a target portion C (e.g. including one or more dies) of the substrate W.

[0017] The illumination system may include various types of optical components, such as refractive, reflective, magnetic, electromagnetic, electrostatic or other types of optical components, or any combination thereof, for directing, shaping, or controlling radiation.

[0018] The patterning device support or support structure holds the patterning device in a manner that depends on the orientation of the patterning device, the design of the lithographic apparatus, and other conditions, such as for example whether or not the patterning device is held in a vacuum environment. The patterning device support or support structure can use mechanical, vacuum, electrostatic or other clamping techniques to hold the patterning device. The support structure may be a frame or a table, for example, which may be fixed or movable as required. The support structure may ensure that the patterning device is at a desired position, for example with respect to the projection system.

Any use of the terms "reticle" or "mask" herein may be considered synonymous with the more general term "patterning device."

[0019] The term "patterning device" used herein should be broadly interpreted as referring to any device that can be used to impart a radiation beam with a pattern in its cross-section such as to create a pattern in a target portion of the
substrate. It should be noted that the pattern imparted to the radiation beam may not exactly correspond to the desired pattern in the target portion of the substrate, for example if the pattern includes phase-shifting features or so called assist features. Generally, the pattern imparted to the radiation beam will correspond to a particular functional layer in a device being created in the target portion, such as an integrated circuit.

[0020] The patterning device may be transmissive or reflective. Examples of patterning devices include masks, programmable mirror arrays, and programmable LCD panels. Masks are well known in lithography, and include mask types such as binary, alternating phase-shift, and attenuated phase-shift, as well as various hybrid mask types. An example of a programmable mirror array employs a matrix arrangement of small mirrors, each of which can be individually tilted so as to reflect an incoming radiation beam in different directions. The tilted mirrors impart a pattern in a radiation beam which is reflected by the mirror matrix.

[0021] The term "projection system" used herein should be broadly interpreted as encompassing any type of projection system, including refractive, reflective, catadioptric, magnetic, electromagnetic and electrostatic optical systems, or any combination thereof, as appropriate for the exposure radiation being used, or for other factors such as the use of an immersion liquid or the use of a vacuum. Any use of the term "projection lens" herein may be considered as synonymous with the more general term "projection system".

[0022] As here depicted, the apparatus is of a transmissive type (e.g. employing a transmissive mask). Alternatively, the apparatus may be of a reflective type (e.g. employing a programmable mirror array of a type as referred to above, or employing a reflective mask).

[0023] The lithographic apparatus may be of a type having two (dual stage) or more substrate tables (and/or two or more mask tables). In such "multiple stage" machines the additional tables may be used in parallel, or preparatory steps may be carried out on one or more tables while one or more other tables are being used for exposure.

[0024] The lithographic apparatus may also be of a type wherein at least a portion of the substrate may be covered by a liquid having a relatively high refractive index, e.g. water, so as to fill a space between the projection system and the substrate. An immersion liquid may also be applied to other spaces in the lithographic apparatus, for example, between the patterning device (e.g. mask) and the projection system. Immersion techniques are well known in the art for increasing the numerical aperture of projection systems. The term "immersion" as used herein does not mean that a structure, such as a substrate, must be submerged in liquid, but rather only means that liquid is located between the projection system and the substrate during exposure.

[0025] Referring to Figure 1, the illuminator IL receives a radiation beam from a radiation source SO. The source and the lithographic apparatus may be separate entities, for example when the source is an excimer laser. In such cases, the source is not considered to form part of the lithographic apparatus and the radiation beam is passed from the source SO to the illuminator IL with the aid of a beam delivery system BD including, for example, suitable directing mirrors and/or a beam expander. In other cases the source may be an integral part of the lithographic apparatus, for example when the source is a mercury lamp. The source SO and the illuminator IL, together with the beam delivery system BD if required, may be referred to as a radiation system.

[0026] The illuminator IL may include an adjuster AD for adjusting the angular intensity distribution of the radiation beam. Generally, at least the outer and/or inner radial extent (commonly referred to as r-outter and r-inner, respectively) of the intensity distribution in a pupil plane of the illuminator can be adjusted. In addition, the illuminator IL may include various other components, such as an integrator IN and a condenser CO. The illuminator may be used to condition the radiation beam, to have a desired uniformity and intensity distribution in its cross-section.

[0027] The radiation beam B is incident on the patterning device (e.g., mask) MA, which is held on the patterning device support or support structure (e.g., mask table MT), and is patterned by the patterning device. Having traversed the patterning device (e.g. mask) MA, the radiation beam B passes through the projection system PS, which focuses the beam onto a target portion C of the substrate W. With the aid of the second positioner PW and position sensor IF (e.g. an interferometric device, linear encoder or capacitive sensor), the substrate table WT can be moved accurately, e.g. so as to position different target portions C in the path of the radiation beam B. Similarly, the first positioner PM and another position sensor (which is not explicitly depicted in Figure 1) can be used to accurately position the patterning device (e.g. mask) MA with respect to the path of the radiation beam B, e.g. after mechanical retrieval from a mask library, or during a scan. In general, movement of the patterning device support (e.g. mask table) MT may be realized with the aid of a long-stroke module (coarse positioning) and a short-stroke module (fine positioning), which form part of the first positioner PM. Similarly, movement of the substrate table WT may be realized using a long-stroke module and a short-stroke module, which form part of the second positioner PW. In the case of a stepper (as opposed to a scanner) the patterning device support (e.g. mask table) MT may be connected to a short-stroke actuator only, or may be fixed. Patterning device (e.g. mask) MA and substrate W may be aligned using mask alignment marks M1, M2 and substrate alignment marks P1, P2. Although the substrate alignment marks as illustrated occupy dedicated target portions, they may be located in spaces between target portions (these are known as scribe-lane alignment marks). Similarly, in situations in which more than one die is provided on the patterning device (e.g. mask) MA, the mask alignment marks may be located between the dies.
The depicted apparatus could be used in at least one of the following modes:

1. In step mode, the patterning device support (e.g. mask table) MT and the substrate table WT are kept essentially stationary, while an entire pattern imparted to the radiation beam is projected onto a target portion C at one time (i.e. a single static exposure). The substrate table WT is then shifted in the X and/or Y direction so that a different target portion C can be exposed. In step mode, the maximum size of the exposure field limits the size of the target portion C imaged in a single static exposure.

2. In scan mode, the patterning device support (e.g. mask table) MT and the substrate table WT are scanned synchronously while a pattern imparted to the radiation beam is projected onto a target portion C (i.e. a single dynamic exposure). The velocity and direction of the substrate table WT relative to the patterning device support (e.g. mask table) MT may be determined by the (de-)magnification and image reversal characteristics of the projection system PS. In scan mode, the maximum size of the exposure field limits the width (in the non-scanning direction) of the target portion in a single dynamic exposure, whereas the length of the scanning motion determines the height (in the scanning direction) of the target portion.

3. In another mode, the patterning device support (e.g. mask table) MT is kept essentially stationary holding a programmable patterning device, and the substrate table WT is moved or scanned while a pattern imparted to the radiation beam is projected onto a target portion C. In this mode, generally a pulsed radiation source is employed and the programmable patterning device is updated as required after each movement of the substrate table WT or in between successive radiation pulses during a scan. This mode of operation can be readily applied to maskless lithography that utilizes programmable patterning device, such as a programmable mirror array of a type as referred to above.

Combinations and/or variations on the above described modes of use or entirely different modes of use may also be employed.

Figures 2a, 2b, 2c illustrate the interaction between an illumination beam and 2 overlapping gratings that may be used for diffractive overlay metrology according to an embodiment. In Figure 2a a cross section of a composite grating 110, 120 is shown which exhibits a zero overlay error. On a substrate 100 a composite grating is constructed which includes of a first grating 110 and a second grating 120. The first grating 110 is patterned in the substrate material and includes a first periodic structure along a grating direction XI. In an embodiment, the periodic structure of the first grating includes a plurality of primary lines 111 with secondary lines 112 interposed. The periodic structure is formed in layer 115. For reason of clarity, only one primary line 111 and one adjacent secondary line 112 have been indicated by reference numbers in Figure 2a.

The pitch P of the grating 110 is equal to the width of one line 111 and one secondary line 112. As will be appreciated by the person skilled in the art, the secondary lines 112 may be created from trenches in between the substrate lines 111 that are filled by a material different from the substrate material. For example, the substrate material is silicon and the trench material is a dielectric like silicon dioxide, or a metal like tungsten or copper.

On top of the first grating 110, a second grating 120 is present. The second grating consists of a second periodic structure. In the embodiment shown, the second periodic structure includes plurality of lines 121 with trenches 122 interposed along the grating direction XI.

In this example, lines 121 are positioned on top of the secondary lines 112 of the first grating 110. The second grating 120 has a pitch P' in direction XI equal to the width of one line 121 and one trench 122. The pitch P' of the second grating 120 is chosen to be substantially equal to the pitch P of the first grating 110. In an embodiment, lines 121 of the second grating 120 may have substantially the same width as the secondary lines 112 of the first grating 110.

Alternatively, lines 121 of the second grating 120 may be located on top of the primary lines 111 of the first grating 110.

The second grating may be a pattern formed in a resist layer 125.

In the case of Figure 2a, the alignment of the first and second gratings 110 and 120 is perfect, the mismatch is ideally zero (which will be referred to as a zero overlay error). The lines 121 of the second grating 120 are aligned fully with the secondary lines 112 of the first grating 110.

In Figure 2a, an embodiment for the interaction between an illumination beam IB and the composite grating 110, 120 is schematically shown.

In this embodiment, the illumination beam IB impinges under a first oblique incidence angle \( \beta \) on the grating structure in grating direction XI. The angle of incidence \( \beta \) is taken relative to the surface normal \( n \). The illumination beam IB is scattered by the composite grating 110, 120 and forms (at least) two diffracted beams B+ and B0 of first order and zeroth order respectively. The first order diffracted beam B+ leaves the substrate under an angle \( \theta \) (relative to the surface
normal n) and the zeroth order diffracted beam leaves under specular reflection, respectively. It is noted that the pitch  
P  
5  of the composite grating 110, 120 and the wavelength of the illumination beam IB are chosen so as to fulfill the  
diffraction condition. In Figure 2a, the diffraction orders and illumination beam are shown in one plane but this is just for  
convenience. An embodiment of the invention is also applicable in case of conical diffraction where the diffractions  
may not be in the same plane as the illumination beam.

[0045] Depending on the ratio of the grating’s pitch P (with P=P') and the wavelength of the illumination beam IB also  
higher order diffracted beams may be present but these are ignored here.

[0046] In Figure 2b, the same cross section of the composite grating 110, 120 of Figure 2a for a second oblique  
incidence of the illumination beam IB.

[0047] In Figure 2b, the illumination beam IB impinges under a second oblique incidence angle -β on the grating  
structure. Second incidence angle -β has substantially the same magnitude as the first incidence angle  
β, but is, in  
comparison, directed in an opposite direction along grating direction XI. The second angle of incidence -β is taken relative  
to the surface normal n.

[0048] The illumination beam IB is scattered by the composite grating 110, 120 and forms (at least) two diffracted  
beams B+ and B0 of first (negative) order and zeroth order respectively, which leave the substrate under an angle -θ  
and under specular reflection, respectively.

[0049] Diffractions B+ depicts the first diffraction order, diffracted beam B- depicts the minus first diffraction order.  
Due to the fact that the first and second gratings are fully aligned, the composite grating is symmetrical, i.e. the  
secondary lines 112 of the first grating 110 coincide with the lines 121 of the second grating 120 as composite lines 112, 121. As  
a result of the symmetry of the composite grating, the diffraction pattern is also symmetrical: i.e., an intensity  
I+ of the  
first order diffracted beam B+ is substantially equal to an intensity I- of the minus first order diffracted beam B-.

\[ I_+ = I_- = I_{+0} \]  

wherein I+0 denotes the intensity of first order diffracted beam for the symmetric composite grating.

[0050] In Figure 2c, a cross section of a composite grating 110, 120 is shown which exhibits a non-zero overlay error.  
The lines 121 of the second grating 120 display an overlay error (misalignment) ε relative to the secondary lines 112 of  
the first grating. As a result, the composite grating as shown in Figure 2c is asymmetrical: the lines 121 of the second  
grating 120 are shifted over a distance ε in comparison with the secondary lines 112 in the first grating 110.

[0051] Due to the asymmetry, the intensity I+ of the first order diffracted beam B+ measured under first oblique incidence  
angle  
θ  
is in this case not equal to the intensity I- of the minus first order diffracted beam B-, measured under second  
oblique angle -θ.

[0052] For small overlay errors, the change of intensity of a diffracted beam is linearly proportional to the overlay error.  
The intensity I+ of the first order diffracted beam B+ as a function of overlay error ε is in good approximation:

\[ I_+ = I_{+0} + K \times \varepsilon \]  

wherein K is a proportionality factor.

The intensity I- of the minus first order diffracted beam B- is approximated by:

\[ I_- = I_{-0} - K \times \varepsilon \]  

By taking the difference \( \Delta I = I_+ - I_- \), a signal is obtained that scales linearly with the overlay error ε.

\[ \Delta I = 2K \times \varepsilon \]  

The proportionality factor K will be discussed in more detail below.

[0054] In a further embodiment, overlay metrology may include a use of the first illumination beam IB1 and the second  
ilumination beam IB2 each under substantially normal incidence on the composite grating 110, 120. It will be appreciated  
by the skilled person that in such an embodiment, the first illumination beam IB1 and the second illumination beam IB2  
coincide and are provided as a single illumination beam. The first illumination beam can be used as second illumination  
beam. Under normal incidence of the illumination beam also, first and minus first order diffracted beams B+, B- will  
occur. Of these beams B+, B-, the intensity will show the same relationship as described above with reference to Figures  
2a - 2c and equations 1 - 4. In this embodiment, the intensity difference \( \Delta I \) of the first and minus first order diffracted
beams may be measured by using the first illumination beam and consecutively measuring the intensity of the first and
minus first order diffracted beam, respectively.

Figure 3a depicts schematically a diffraction based overlay error detection system (hereafter referred to as
detection system) 200 in accordance with an embodiment of the present invention, in a first measurement of the substrate
holding the composite grating 110, 120. The detection system may include a support configured to support the substrate
in an embodiment of the invention. The support may also be a substrate table of the lithographic apparatus of Figure 1
in an embodiment of the invention.

The detection system 200 includes a plurality of lenses, in this embodiment, a first, second, third and fourth
positive lenses L1, L2, L3, L4, an aperture stop DF, and an image detector ID.

Within the detection system 200, an optical axis OP is arranged that extends from a substrate position where a
composite grating 110, 120 can be illuminated by the illumination beam IB under oblique incidence angle to a position
where an image of the composite grating can be projected on the image detector ID.

For example, the image detector ID may be a CCD camera. The illuminated area is larger than the area of the
grating. In other words, the surrounding environment is also illuminated. This is also referred to as “overfill”.

Along the optical axis OP, the first, second, third and fourth positive lenses L1, L2, L3, L4 are arranged with
their respective centers on the optical axis in such a way that the image of the composite grating 110, 120 can be
projected on the image detector ID of the detection system 200.

The first lens L1 is positioned above the substrate position where the composite grating 110, 120 on the substrate
100 can be located. The distance between the first lens and the substrate position is substantially equal to a focal distance
F1 of the first lens L1. At some distance from the first lens L1, the second and third lenses L2, L3 are arranged in a pair
along the optical axis OP. The fourth lens L4 is arranged as projection lens of the image detector ID. Between the third
and the fourth lenses L3, L4, the aperture stop DF is located.

During measurement, the substrate with composite grating 110, 120 is located at the substrate position. The
composite grating 110, 120 is in a predetermined position (indicated Q). A first illumination beam IB1 is used in an
asymmetric illumination mode under oblique incidence in a first horizontal direction (indicated by arrow D1) along the
surface of the substrate. For example, the first illumination beam propagates along a direction that has a component
along a first horizontal direction along the surface of the substrate. The first illumination beam IB1 enters the first lens
L1, in such way that the first illumination beam IB1 after passing the first lens impinges on the composite grating under
an angle that creates a first diffraction order beam B+ under diffraction angle θ. As a result, the first order diffracted
beam B+ is now diffracted at the surface of the substrate and a zeroth order diffracted beam B0 is diffracted under
specular reflection (in this example under angle 2θ).

Both first order diffracted beam B+ and zeroth order beam B0 pass through the first lens L1. Since the composite
grating is at a focal distance F1 of the first lens L1, the first order and zeroth order diffracted beams B+, B0 are directed
in parallel after passing the first lens L1.

Next, the first order and zeroth order diffracted beams B+, B0 pass the second lens L2. The first order diffracted
beam B+ substantially coincides with the optical axis and passes through the center of the second lens L2. The zeroth
order diffracted beam B0 passes the second lens L2 off-axis and after passing is directed through the focal point of the
second lens L2.

The third lens L3 is arranged with a focal point F3 coinciding with a focal point F2 of the second lens L2.

The first order diffracted beam B+ coincides with the optical axis of the third lens and passes through the center
of the third lens L3 and continues to be on the optical axis. The zeroth order diffracted beam B0 passes the third lens
off-axis. Due to the fact that the focal points F2, F3 of the second and third lenses coincide, the zeroth order diffracted
beam is substantially parallel to the optical axis after passing the third lens L3.

After the third lens L3 the aperture stop DF is positioned on the optical axis and is arranged to block the zeroth
diffraction order. The aperture stop DF allows the first order diffracted beam B+ on the optical axis OP to pass and blocks
the zeroth order diffracted beam B0. In this way, the image on the camera is only formed by first diffraction order and
not by the zeroth order. This imaging mode is normally called “dark-field” imaging. The aperture stop DF is arranged to
have a width that allows to block the zeroth order diffracted beam B0 and allows to let the first order diffracted beam B+
pass.

As a result, an image of the composite grating is formed on the CCD camera using only the first or minus first
diffraction order. Suitable image processing and pattern recognition algorithms known to the skilled artisan may then be
used to identify the composite grating from the product structures around the composite grating. Application of the
aperture stop allows to use an illumination beam with a cross-sectional size larger than the diffraction limit, while the
size of the grating may be smaller than indicated by the diffraction limit.

Finally, the first order diffracted beam B+ passes the fourth lens L4 which is arranged for imaging the first order
diffracted beam B+ on the image detector ID.

In this manner, an image of the composite grating 110, 120 originated from the first order diffracted beam B+
is projected on the image detector ID. Since the image is only formed by one higher (first) diffraction order, the image
will show no modulation of the individual grating lines.

[0070] It is noted that the first diffracted order may not necessarily be exactly normal to the surface. The first diffracted order may make any angle with the wafer surface, as long as it is transmitted by the aperture stop (without any other orders passing the aperture stop).

[0071] From the image of the composite grating 110, 120 registered on the image detector, the intensity $I^+$ may be determined. The precise location of the image of the grating is determined with pattern recognition algorithms, for example edge detection.

[0072] Figure 3b depicts schematically a diffraction based overlay error detection system in accordance with an embodiment of the present invention, in a second measurement of the substrate holding the composite grating 110, 120.

[0073] In Figure 3b entities with the same reference number as shown in the preceding figures refer to the corresponding entities.

[0074] In the second measurement, the composite grating 110, 120 is illuminated asymmetrically by a second illumination beam IB2 in a second horizontal direction (indicated by arrow D2) opposite to the first horizontal direction D1 as used during the first measurement as shown in Figure 3a. For example, the second illumination beam propagates along a direction that has a component along a first horizontal direction along the surface of the substrate. The composite grating is maintained in the same predetermined position Q as during the first measurement.

[0075] Under these conditions, the minus first order diffracted beam $B^-$ is now diffracted normal to the surface of the substrate and the zeroth order diffracted beam $B^0$ is diffracted under angle $2\theta$. The aperture stop DF is arranged to have a width that allows to block the zeroth order diffracted beam $B^0$ and allows to let the minus first order diffracted beam $B^-$ pass.

[0076] As a result, during the second measurement an image of the composite grating 110, 120 originated from the minus first order diffracted beam $B^-$ is projected on the image detector ID. From the image of the composite grating 110, 120 registered on the image detector ID, the intensity $I^-$ may be determined. Again, pattern recognition techniques may be used to identify the region on the CCD where the measurement of the intensity must be carried out.

[0077] It is noted that in a different embodiment, the illumination beam has substantially normal incidence. As will be appreciated by the person skilled in the art, this embodiment may use a different but functionally equivalent illumination/detection layout in which the function of the aperture stop to allow in a first instance only the first order diffracted beam and in a second instance only the minus first order diffracted beam to pass, would be the same.

[0078] Moreover it is noted that oblique incidence is not required but may be preferred since it allows the use of gratings with a smaller pitch.

[0079] As described above, the difference of the intensity $I^+$ of the first order diffracted beam $B^+$ and the intensity $I^-$ of the minus first order diffracted beam $B^-$ is proportional to the overlay error $\varepsilon$ according to eq. 4. The proportionality factor K is dependent on processing conditions, wavelength of the illumination beam, diffraction angle and polarization. For a given combination of process, wavelength, diffraction angle and polarization, it is desirable to carry out a calibration of the proportionality factor, as will be appreciated by the person skilled in the art.

[0080] In an embodiment of the invention, the proportionality factor K is calibrated by determining the overlay error $\varepsilon$ on two biased composite gratings on a substrate. Each biased composite grating has a respective predetermined built-in shift between the first grating 110 and the second grating 120. The two biased gratings are on the substrate in a fixed position relative to each other.

[0081] The first biased composite grating has a first built-in shift $+d$ in a shift direction along the grating direction XI. The second biased composite grating has a second built-in shift $-d$, which is equal to but with opposite sign than the first built-in shift, along the grating direction XI.

[0082] In case of an overlay error $\varepsilon$, the first biased composite grating exhibits a total overlay error $\varepsilon + d$ and the second biased composite grating exhibits a total overlay error $\varepsilon - d$.

[0083] An intensity difference $\Delta I1$ between the first and minus first diffraction orders on the first biased composite grating and an intensity difference $\Delta I2$ between the first and minus first diffraction orders on the second biased composite grating is given by:

$$\Delta I1 = K \times (\varepsilon + d)$$  \hspace{1cm} \text{eq. (5)}$$

for the first biased composite grating and

$$\Delta I2 = K \times (\varepsilon - d)$$  \hspace{1cm} \text{eq. (6)}$$
for the second biased composite grating.

Elimination of $K$ results in:

$$\varepsilon = d \frac{\Delta I_1 + \Delta I_2}{\Delta I_1 - \Delta I_2}$$

eq (7)

In an embodiment, both first and second biased composite gratings can be measured at the same time by the detection system as shown in Figures 3a, 3b. In that case the image detector ID registers an image from the first biased composite grating and an image of the second biased composite grating at the same time. By using image processing software the intensity of the image of the first biased composite grating and the intensity of the second biased composite grating can be determined separately. The overlay error $\varepsilon$ can be calculated using equations (5) - (7).

Since the first and second illumination beams $IB_1$, $IB_2$ are each under grazing incidence, light that would reflect off surface regions outside of the composite grating(s) (i.e., product area), will not likely reach the image detector ID through the system of first, second, third and fourth lenses $L_1$, $L_2$, $L_3$, $L_4$. In an embodiment of the present invention, the first and/or second illumination beam $IB_1$, $IB_2$ may have a larger cross-section than the composite grating 110, 120 on the substrate without causing interference between light reflected off the surface outside the grating and light diffracted by the composite grating.

A large value of the numerical aperture of the aperture stop $DF$ is preferred since it allows a sharp transition between the composite grating and the surrounding product area in which the composite grating is embedded. Since at the same time, the aperture stop $DF$ is arranged to block the zeroth order diffracted beam $B_0$, the numerical aperture of the aperture stop $DF$ has an upper limit in which a compromise is obtained between sufficient zeroth order diffracted beam suppression and a sufficiently low cross-talk due to reflections from the product area. It is feasible that this approach allows the use of composite gratings of a size of about $10 \times 10 \mu$m$^2$.

It is noted that modeling software may allow to compute a layout of product area and embedded composite grating(s) for which the cross-talk can be minimized further. This approach may allow to design embedded composite gratings with a size of about $4 \times 4 \mu$m$^2$.

In an embodiment, the numerical aperture of the aperture stop $DF$ is about 0.7, while the numerical aperture of the first lens is about 0.95.

Figure 4a illustrates exemplary measurements of intensity of minus first order and first order diffracted beams as function of shift $d$ on a biased grating.

In Figure 4a, the variation of the intensity $I_-$ of the minus first order diffracted beam $B_-$ and the intensity $I_+$ of the first order diffracted beam $B_+$ with the shift $d$ are shown for a composite grating with pitch $P = 660$ nm and a wavelength $\lambda = 700$ nm of the illumination beam. It is observed that the change of the intensity $I_+$, $I_-$ for shifts close to 0 nm is substantially linear.

Figure 4b illustrates the difference of intensity between the minus first order and first order diffracted beams as function of shift $d$ on the biased grating as shown in Figure 4b. It is observed that the change of the intensity difference $\Delta I$ for shifts close to 0 nm is substantially linear.

Figure 5 depicts a correlation between image based overlay error and the diffraction based overlay error as determined according to the present invention.

For a number of samples, the shift $d$ of the biased composite gratings as measured by diffraction based overlay error metrology is also measured by image based overlay error metrology. In Figure 5, a correlation is shown of the overlay measured by diffraction (along the vertical axis) and the overlay as measured by an image based method (along the horizontal axis). A linear fit of the data is illustrated by the solid line. Within the error of the methods, the coefficient of the solid line is unity. The correlation coefficient is over 0.99.

It is noted that the illumination beam $IB$ as described above may be a single beam. Alternatively, the illumination beam may have a shape of half an annulus as its cross-section. In that case, the asymmetric illumination in Figure 3a may be done by one half of the annular beam, while the asymmetric illumination from the opposite direction as shown in Figure 3b is done by the other half of the annular beam.

The illumination beam $IB$ may be created by a light source such as a monochromatic lamp, or a laser source. A laser source with relatively high intensity may be used in case a short time is available for measurements.

Although specific reference may be made in this text to the use of lithographic apparatus in the manufacture of ICs, it should be understood that the lithographic apparatus described herein may have other applications, such as the manufacture of integrated optical systems, guidance and detection patterns for magnetic domain memories, flat-panel displays, liquid-crystal displays (LCDs), thin-film magnetic heads, etc. The skilled artisan will appreciate that, in the context of such alternative applications, any use of the terms "wafer" or "die" herein may be considered as synonymous with the more general terms "substrate" or "target portion", respectively. The substrate referred to herein may be proc-
essed, before or after exposure, in for example a track (a tool that typically applies a layer of resist to a substrate and develops the exposed resist), a metrology tool and/or an inspection tool. Where applicable, the disclosure herein may be applied to such and other substrate processing tools. Further, the substrate may be processed more than once, for example in order to create a multi-layer IC, so that the term substrate used herein may also refer to a substrate that already contains multiple processed layers.

The terms "radiation" and "beam" used herein encompass all types of electromagnetic radiation, including ultraviolet (UV) radiation (e.g. having a wavelength of or about 365, 355, 248, 193, 157 or 126 nm) and extreme ultraviolet (EUV) radiation (e.g. having a wavelength in the range of 5-20 nm), as well as particle beams, such as ion beams or electron beams.

The term "lens", where the context allows, may refer to any one or combination of various types of optical components, including refractive, reflective, magnetic, electromagnetic and electrostatic optical components.

The descriptions above are intended to be illustrative, not limiting. Thus, it will be apparent to one skilled in the art that modifications may be made to the invention as described without departing from the scope of the claims set out below. The invention is defined by the claims.

Claims

1. A method of determining an overlay error between a first pattern on a surface of a substrate (100) and a second pattern superimposed on the first pattern, the first pattern comprising a first grating (110) and the second pattern comprising a second grating (120) on top of the first grating, the second grating having substantially identical pitch (P') as the first grating, the second and first gratings forming a composite grating, the method comprising:

   either: (i) providing a first illumination beam (IB1) for illuminating at least the composite grating on the substrate under an angle of incidence (β) such that the first illumination beam propagates along a direction that has a component along a first horizontal direction (D1) along the surface of the substrate, the substrate being in a fixed position, and

   providing a second illumination beam (IB2) for illuminating at least the composite grating on the substrate under the angle of incidence (-β) such that the second illumination beam has a component along a second horizontal direction (D2) along the surface of the substrate, wherein the second horizontal direction is opposite the first direction, the substrate being in the fixed position; or

   (ii) providing a first illumination beam and a second illumination beam for illuminating at least the composite grating on the substrate, each beam being provided under substantially normal incidence to the composite grating, the substrate being in the fixed position;

   characterized by blocking beams diffracted from the composite grating of diffraction order other than the first diffraction order (B+) when providing the first illumination beam, and blocking beams diffracted from the composite grating of diffraction order other than the minus first diffraction order (B-) when providing the second illumination beam; the method further comprising measuring a first intensity (I+) of the first order diffracted beam from the composite grating, the measuring of the first intensity comprising detecting an image of the composite grating obtained by only the first order diffracted beam by a pattern recognition method, and

   measuring a second intensity (I-) of the minus first order diffracted beam from the composite grating, the measuring of the second intensity comprising detecting an image of the composite grating obtained by only the minus first order diffracted beam by a pattern recognition method.

2. The method according to claim 1, further comprising:

determining an intensity difference between the first intensity and the second intensity, the intensity difference being proportional to the overlay error between the first grating and the second grating.

3. The method according to claim 1, wherein the first and second illumination beams are portions of a common illumination beam.

4. The method according to claim 1, wherein the angle of incidence is oblique relative to the surface of the substrate, a diffraction angle of the first and the minus first diffracted beam relative to the normal of the surface being smaller than the angle of incidence.

5. The method according to claim 1, wherein, when the angle of incidence is substantially normal to the composite
6. A detection system (200) configured to determine an overlay error between a first pattern on a surface of a substrate (100) and a second pattern superimposed on the first pattern, the first pattern comprising a first grating (110) and the second pattern comprising a second grating (120) on top of the first grating, the second grating having substantially identical pitch (P') as the first grating, the second and first gratings forming a composite grating, the detection system comprising:

- an illumination source configured to either:
  
  (i) form a first illumination beam (IB1) for illuminating at least the composite grating on the substrate under an angle of incidence (β) such that the first illumination beam propagates along a direction that has a component along a first horizontal direction (D1) along the surface of the substrate, the substrate being in a fixed position, and to form a second illumination beam (IB2) for illuminating at least the composite grating on the substrate under the angle of incidence (-β) such that the second illumination beam propagates along a direction that has a component along a second horizontal direction (D2) along the surface of the substrate, wherein the second horizontal direction is opposite the first direction, the substrate being in the fixed position; or
  
  (ii) form a first illumination beam and a second illumination beam for illuminating at least the composite grating on the substrate, each beam being formed under substantially normal incidence to the composite grating, the substrate being in the fixed position; the detection system further comprising an image detector (ID) configured to receive a first order diffracted beam and a minus first order diffracted beam from the composite grating;

- a plurality of lenses (L1,L2,L3,L4) arranged along an optical path between the substrate position and the image detector; an aperture stop (DF); characterized in that the aperture stop is configured to block beams diffracted from the composite grating of diffraction order other than the first diffraction order when forming the first illumination beam, and to block beams diffracted from the composite grating of diffraction order other than the minus first diffraction order when forming the second illumination beam; and

- the image detector is configured to detect an image of the composite grating using only the first order diffracted beam and the minus first order diffracted beam by a pattern recognition method.

7. The detection system according to claim 6, wherein the plurality of lenses comprises at least an objective lens adjacent to the surface of the substrate and a projection lens adjacent to the image detector, the aperture stop arranged along the optical path between the objective lens and the projection lens, and wherein the objective lens has a first numerical aperture value and the aperture stop has a second numerical aperture value, the second numerical aperture value smaller than the first numerical aperture value.

8. A lithographic apparatus comprising a detection system of claims 6 or 7.

9. The lithographic apparatus according to claim 8, further comprising an illumination system (IL) configured to condition a beam of radiation; a patterning device support (MT) configured to hold a patterning device (MA), the patterning device configured to pattern the beam of radiation to form a patterned beam of radiation; a substrate table (WT) configured to hold the substrate (W,100); and a projection system (PS) configured to project the patterned beam of radiation onto the substrate.

**Patentansprüche**

1. Ein Verfahren zum Bestimmen eines Überdeckungsfehlers zwischen einem ersten Muster auf einer Oberfläche eines Substrats (100) und einem zweiten Muster, welches dem ersten Muster aufgelagert ist, wobei das erste Muster ein erstes Gitter (110) beinhaltet und das zweite Muster ein zweites Gitter (120) über dem ersten Gitter beinhaltet, wobei das zweite Gitter ein im Wesentlichen identisches Abstandsmaß (P') wie das erste Gitter aufweist, wobei das zweite und das erste Gitter ein zusammengesetztes Gitter formen, wobei das Verfahren Folgendes beinhaltet: entweder: (i) Bereitstellen eines ersten Beleuchtungsstrahls (IB1) zum Beleuchten mindestens des zusammengesetzten Gitters auf dem Substrat unter einem Einfallswinkel (β), sodass sich der erste Beleuchtungsstrahl entlang einer Richtung ausbreitet, die eine Komponente entlang einer ersten horizontalen Richtung (D1) entlang der Ober-
flache des Substrats aufweist, wobei sich das Substrat an einer festen Position befindet, und Bereitstellen eines zweiten Beleuchtungsstrahls (IB2) zum Beleuchten mindestens des zusammengesetzten Gitters auf dem Substrat unter dem Einfallswinkel (-β), sodass der zweite Beleuchtungsstrahl eine Komponente entlang einer zweiten horizontalen Richtung (D2) entlang der Oberfläche des Substrats aufweist, wobei die zweite horizontale Richtung der ersten Richtung entgegengesetzt ist, wobei sich das Substrat an der festen Position befindet; oder

(ii) Bereitstellen eines ersten Beleuchtungsstrahls und eines zweiten Beleuchtungsstrahls zum Beleuchten mindestens des zusammengesetzten Gitters auf dem Substrat, wobei jeder Strahl unter im Wesentlichen senkrechtinem Einfall auf das zusammengesetzte Gitter bereitgestellt wird, wobei sich das Substrat an der festen Position befindet;

dadurch gekennzeichnet, dass von dem zusammengesetzten Gitter gebeugte Strahlen, die eine andere Beugungsordnung als die erste Beugungsordnung (B+) aufweisen, blockiert werden, wenn der erste Beleuchtungsstrahl bereitgestellt wird, und dass von dem zusammengesetzten Gitter gebeugte Strahlen, die eine andere Beugungsordnung als die minus erste Beugungsordnung (B-) aufweisen, blockiert werden, wenn der zweite Beleuchtungsstrahl bereitgestellt wird; wobei das Verfahren ferner Folgendes beinhaltet:


2. Verfahren gemäß Anspruch 1, das ferner Folgendes beinhaltet:

Bestimmen eines Intensitätsunterschieds zwischen der ersten Intensität und der zweiten Intensität, wobei der Intensitätsunterschied zu dem Überdeckungsfehler zwischen dem ersten Gitter und dem zweiten Gitter proportional ist.

3. Verfahren gemäß Anspruch 1, wobei der erste und der zweite Beleuchtungsstrahl Teile eines gemeinsamen Beleuchtungsstrahls sind.

4. Verfahren gemäß Anspruch 1, wobei der Einfallswinkel relativ zu der Oberfläche des Substrats schräg ist, wobei ein Beugungswinkel des ersten und des minus ersten gebeugten Strahls relativ zu der Senkrechten der Oberfläche kleiner als der Einfallswinkel ist.

5. Verfahren gemäß Anspruch 1, wobei, wenn der Einfallswinkel zu dem zusammengesetzten Gitter im Wesentlichen senkrecht ist, das Verfahren Folgendes beinhaltet:

Verwenden des ersten Beleuchtungsstrahls als den zweiten Beleuchtungsstrahl.

6. Ein Erfassungssystem (200), das konfiguriert ist, um einen Überdeckungsfehler zwischen einem ersten Muster auf einer Oberfläche eines Substrats (100) und einem zweiten Muster, welches dem ersten Muster aufgelagert ist, zu bestimmen, wobei das erste Muster ein erstes Gitter (110) beinhaltet und das zweite Muster ein zweites Gitter (120) über dem ersten Gitter beinhaltet, wobei das zweite Gitter ein im Wesentlichen identisches Abstandsmaß (P') wie das erste Gitter aufweist, wobei das zweite und das erste Gitter ein zusammengesetztes Gitter formen, wobei das Erfassungssystem Folgendes beinhaltet:

eine Beleuchtungsquelle, die für eines der folgenden konfiguriert ist:

(i) Formen eines ersten Beleuchtungsstrahls (IB1) zum Beleuchten mindestens des zusammengesetzten Gitters auf dem Substrat unter einem Einfallswinkel (β), sodass sich der erste Beleuchtungsstrahl entlang einer Richtung ausbreitet, die eine Komponente entlang einer ersten horizontalen Richtung (D1) entlang der Oberfläche des Substrats aufweist, wobei sich das Substrat an einer festen Position befindet, und Formen eines zweiten Beleuchtungsstrahls (IB2) zum Beleuchten mindestens des zusammengesetzten Gitters auf dem Substrat unter dem Einfallswinkel (-β), sodass sich der zweite Beleuchtungsstrahl entlang einer Richtung ausbreitet, die eine Komponente entlang einer zweiten horizontalen Richtung (D2) entlang der Oberfläche des Substrats aufweist, wobei die zweite horizontale Richtung der ersten Richtung entgegengesetzt ist, wobei sich das Substrat an der festen Position befindet; oder

(ii) Formen eines ersten Beleuchtungsstrahls und eines zweiten Beleuchtungsstrahls zum Beleuchten mindest-
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tens des zusammengesetzten Gitters auf dem Substrat, wobei jeder Strahl unter im Wesentlichen senkrechtem Einfall auf das zusammengesetzte Gitter geformt wird, wobei sich das Substrat an der festen Position befindet;

wobei das Erfassungssystem ferner Folgendes beinhaltet: einen Bilddetektor (ID), der konfiguriert ist, um einen gebeugten Strahl erster Ordnung und einen gebeugten Strahl minus erster Ordnung von dem zusammengesetzten Gitter zu empfangen;
eine Vielzahl von Linsen (L1, L2, L3, L4), die entlang einem optischen Weg zwischen der Substratposition und dem Bilddetektor angeordnet sind;
eine Aperturblende (DF);
dadurch gekennzeichnet, dass die Aperturblende konfiguriert ist, um von dem zusammengesetzten Gitter gebeugte Strahlen, die eine andere Beugungsordnung als die erste Beugungsordnung aufweisen, zu blockieren, wenn der erste Beleuchtungsstrahl geformt wird, und um von dem zusammengesetzten Gitter gebeugte Strahlen, die eine andere Beugungsordnung als die minus erste Beugungsordnung aufweisen, zu blockieren, wenn der zweite Beleuchtungsstrahl geformt wird; und
der Bilddetektor konfiguriert ist, um ein Bild des zusammengesetzten Gitters unter Verwendung nur des gebeugten Strahls erster Ordnung und des gebeugten Strahls minus erster Ordnung durch ein Mustererkennungsverfahren zu erfassen.

7. Erfassungssystem gemäß Anspruch 6, wobei die Vielzahl von Linsen mindestens eine der Oberfläche des Substrats benachbarte Objektivlinse und eine dem Bilddetektor benachbarte Projektionslinse beinhaltet, wobei die Aperturblende entlang dem optischen Weg zwischen der Objektivlinse und der Projektionslinse angeordnet ist, und wobei die Objektivlinse einen ersten Wert der numerischen Apertur aufweist und die Aperturblende einen zweiten Wert der numerischen Apertur aufweist, wobei der zweite Wert der numerischen Apertur kleiner als der erste Wert der numerischen Apertur ist.

8. Ein lithographisches Gerät, das ein Erfassungssystem gemäß Anspruch 6 oder 7 beinhaltet.

9. Lithographisches Gerät gemäß Anspruch 8, das ferner Folgendes beinhaltet: ein Beleuchtungssystem (IL), welches konfiguriert ist, um einen Strahl aus Strahlung zu konditionieren; eine Musteraufbringungsvorrichtungsmastle (MT), die konfiguriert ist, um eine Musteraufbringungsvorrichtungsmastle (MA) zu halten, wobei die Musteraufbringungsvorrichtungsmastle konfiguriert ist, um den Strahl aus Strahlung zum Formen eines gemusterten Strahls aus Strahlung zu mustern; einen Substrattisch (WT), der konfiguriert ist, um das Substrat (W, 100) zu halten; und ein Projektionssystem (PS), das konfiguriert ist, um den gemusterten Strahl aus Strahlung auf das Substrat zu projizieren.

Revendications

1. Une méthode pour déterminer une erreur d’overlay entre un premier motif sur une surface d’un substrat (100) et un deuxième motif superposé sur le premier motif, le premier motif comprenant un premier réseau (110) et le deuxième motif comprenant un deuxième réseau (120) sur le dessus du premier réseau, le deuxième réseau ayant un pas (P’) substantiellement identique au premier réseau, les deuxième et premier réseaux formant un réseau composite, la méthode comprenant le fait :

soit : (i) de fournir un premier faisceau d’illumination (IB1) pour illuminer au moins le réseau composite sur le substrat sous un angle d’incidence (j) de telle sorte que le premier faisceau d’illumination se propage dans une direction qui a une composante suivant une première direction horizontale (D1) le long de la surface du substrat, le substrat étant dans une position fixe, et de fournir un deuxième faisceau d’illumination (IB2) pour illuminer au moins le réseau composite sur le substrat sous l’angle d’incidence (-j) de telle sorte que le deuxième faisceau d’illumination ait une composante suivant une deuxième direction horizontale (D2) le long de la surface du substrat, où la deuxième direction horizontale est opposée à la première direction, le substrat étant dans la position fixe ;
soit : (ii) de fournir un premier faisceau d’illumination et un deuxième faisceau d’illumination pour illuminer au moins le réseau composite sur le substrat, chaque faisceau étant fourni sous une incidence substantiellement normale au réseau composite, le substrat étant dans la position fixe ;

caractérisée par le fait de bloquer des faisceaux diffractés par le réseau composite dont l’ordre de diffraction est autre que le premier ordre de diffraction (B+) au moment de fournir le premier faisceau d’illumination, et de bloquer des faisceaux diffractés par le réseau composite dont l’ordre de diffraction est autre que le premier ordre de diffraction
négatif (B-) au moment de fournir le deuxième faisceau d’illumination ; la méthode comprenant en sus le fait de mesurer une première intensité (+) du faisceau diffracté au premier ordre par le réseau composite, le fait de mesurer la première intensité comprenant le fait de détecter une image du réseau composite obtenue uniquement grâce au faisceau diffracté au premier ordre grâce à une méthode de reconnaissance de motifs, et de mesurer une deuxième intensité (-) du faisceau diffracté au premier ordre négatif par le réseau composite, le fait de mesurer la deuxième intensité comprenant le fait de détecter une image du réseau composite obtenue uniquement grâce au faisceau diffracté au premier ordre négatif grâce à une méthode de reconnaissance de motifs.

2. La méthode selon la revendication 1, comprenant en sus :
   le fait de déterminer une différence d’intensité entre la première intensité et la deuxième intensité, la différence d’intensité étant proportionnelle à l’erreur d’overlay entre le premier réseau et le deuxième réseau.

3. La méthode selon la revendication 1, où les premier et deuxième faisceaux d’illumination sont des portions d’un faisceau d’illumination commun.

4. La méthode selon la revendication 1, où l’angle d’incidence est oblique relativement à la surface du substrat, un angle de diffraction du premier faisceau diffracté et premier faisceau diffracté négatif relativement à la normale de la surface étant plus petit que l’angle d’incidence.

5. La méthode selon la revendication 1, où, lorsque l’angle d’incidence est substantiellement normal au réseau composite, la méthode comprend le fait :
   d’utiliser le premier faisceau d’illumination comme deuxième faisceau d’illumination.

6. Un système de détection (200) configuré afin de déterminer une erreur d’overlay entre un premier motif sur une surface d’un substrat (100) et un deuxième motif superposé sur le premier motif, le premier motif comprenant un premier réseau (110) et le deuxième motif comprenant un deuxième réseau (120) sur le dessus du premier réseau, le deuxième réseau ayant un pas (P’) substantiellement identique au premier réseau, les deuxième et premier réseaux formant un réseau composite, le système de détection comprenant :
   une source d’illumination configurée afin
   soit : (i) de former un premier faisceau d’illumination (IB1) pour illuminer au moins le réseau composite sur le substrat sous un angle d’incidence (β) de telle sorte que le premier faisceau d’illumination se propage dans une direction qui a une composante suivant une première direction horizontale (D1) le long de la surface du substrat, le substrat étant dans une position fixe, et de former un deuxième faisceau d’illumination (IB2) pour illuminer au moins le réseau composite sur le substrat sous l’angle d’incidence (−β) de telle sorte que le deuxième faisceau d’illumination se propage dans une direction qui a une composante suivant une deuxième direction horizontale (D2) le long de la surface du substrat, où la deuxième direction horizontale est opposée à la première direction, le substrat étant dans la position fixe ;
   soit : (ii) de former un premier faisceau d’illumination et un deuxième faisceau d’illumination pour illuminer au moins le réseau composite sur le substrat, chaque faisceau étant formé sous une incidence substantiellement normale au réseau composite, le substrat étant dans la position fixe ;
   le système de détection comprenant en sus un détecteur d’image (ID) configuré afin de recevoir un faisceau diffracté au premier ordre et un faisceau diffracté au premier ordre négatif par le réseau composite ;
   une pluralité de lentilles (L1, L2, L3, L4) agencées le long d’un chemin optique entre la position du substrat et le détecteur d’image ;
   un diaphragme d’ouverture (DF) ;
   caractérisé en ce que le diaphragme d’ouverture est configuré afin de bloquer des faisceaux diffractés par le réseau composite dont l’ordre de diffraction est autre que le premier ordre de diffraction au moment de former le premier faisceau d’illumination, et de bloquer des faisceaux diffractés par le réseau composite dont l’ordre de diffraction est autre que le premier ordre de diffraction négatif au moment de former le deuxième faisceau d’illumination ; et le détecteur d’image est configuré afin de détecter une image du réseau composite en utilisant uniquement le faisceau diffracté au premier ordre et le faisceau diffracté au premier ordre négatif grâce à une méthode de reconnaissance de motifs.

7. Le système de détection selon la revendication 6, où la pluralité de lentilles comprend au moins une lentille d’objectif adjacente à la surface du substrat et une lentille de projection adjacente au détecteur d’image, le diaphragme d’ouverture étant agencé le long du chemin optique entre la lentille d’objectif et la lentille de projection, et où la
lentille d’objectif à une première valeur d’ouverture numérique et le diaphragme d’ouverture à une deuxième valeur d’ouverture numérique, la deuxième valeur d’ouverture numérique étant plus petite que la première valeur d’ouverture numérique.


9. L’appareil lithographique selon la revendication 8, comprenant en sus un système d’illumination (IL) configuré afin de conditionner un faisceau de rayonnement ; un support de dispositif servant à conformer selon un motif (MT) configuré afin de porter un dispositif servant à conformer selon un motif (MA), le dispositif servant à conformer selon un motif étant configuré afin de conformer le faisceau de rayonnement selon un motif pour former un faisceau de rayonnement à motif ; une table porte-substrat (WT) configurée afin de porter le substrat (W, 100) ; et un système de projection (PS) configuré afin de projeter le faisceau de rayonnement à motif sur le substrat.
Fig 1
Fig 4a

![Graph showing intensity vs. d [nm]]

Fig 4b

![Graph showing intensity vs. d [nm]]
Fig 5
REFERENCES CITED IN THE DESCRIPTION

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Patent documents cited in the description

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