A method for monitoring and diagnosing an air charger system (10) for use in an engine assembly (29) having pre-existing sensors, having the steps of providing an air charger (42) having a turbine (46) and a compressor (48) operatively coupled to one another. Providing a control unit (41) for monitoring a plurality of operating conditions (12) of the engine assembly (29). The control unit (41) calculates an expected value of a selected operating condition based upon at least another of the plurality of operating conditions (14). Comparing the expected value and at least another of the plurality of operating conditions (16). Diagnosing a fault condition (20), if present, based upon the expected value and said at least another of said plurality of operating conditions being outside a predetermined tolerance (18).

**Figure 1**

- Monitor operating conditions of the engine assembly
- Calculate expected values based upon operating conditions
- Compare calculated expected values and other operating conditions
- Are the other operating conditions outside a predetermined tolerance of the calculated expected values?
- Yes
- No
- Diagnose a fault condition
- Clear fault condition
The present invention relates to the monitoring and diagnostics of an air charger system. Emission control devices are used in the automotive industry for limiting the amount of emissions discharged by the automobile, and to monitor and run diagnostics on the emission control devices. Emission control devices can utilize an electric air pump or a secondary air charger, which inject air into an engine’s exhaust system to reduce emissions. It is important to have some way to test the functioning of such a system to ensure the emission reduction is in compliance with the regulations.

In order to monitor or run diagnostics on the emission control device utilizing the electric air pump, the air pump has to be turned on under predetermined conditions. When the air pump is turned on, the engine’s oxygen sensors should detect the increase in oxygen in the engine. However, the oxygen sensors may not be able to detect the minimal increase in oxygen in the system, and thus an inaccurate result can be obtained. Therefore, it is desirable to develop a method for monitoring and diagnosing the air charger system that uses sensors and/or known conditions that are otherwise in the air charger system.

Therefore, it is desirable to develop a method for monitoring and diagnosing the air charger system that uses sensors and/or known conditions that are otherwise in the air charger system.

SUMMARY OF THE INVENTION

The present invention relates to a method for monitoring and diagnosing an air charger system for use in an engine assembly having pre-existing sensors having the steps of first providing an air charger having a turbine and a compressor operatively coupled to one another. Providing a control unit for monitoring a plurality of operating conditions of the engine assembly. The control unit calculates an expected value of a selected operating condition based upon at least one of the plurality of operating conditions. Comparing the expected value and at least another of the plurality of operating conditions. Diagnosing a fault condition, if present, based upon the expected value and the at least another of the plurality of operating conditions being outside a predetermined tolerance.

Further areas of applicability of the present invention will become apparent from the detailed description provided hereinafter. It should be understood that the detailed description and specific examples, while indicating the preferred embodiment of the invention, are intended for purposes of illustration only and are not intended to limit the scope of the invention.

BRIEF DESCRIPTION OF THE DRAWINGS

The present invention will become more fully understood from the detailed description and the accompanying drawings, wherein:

Figure 1 is a flow chart for a method for monitoring and diagnosing an air charger system in accordance with an embodiment of the present invention; and

Figure 2 is a schematic diagram of an engine assembly.

DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENTS

The following description of the preferred embodiment(s) is merely exemplary in nature and is in no way intended to limit the invention, its application, or uses.

Referring to Figure 1, a method for monitoring and diagnosing an air charger system is generally shown at 10. Typically, the air charger system is for an engine assembly having pre-existing sensors, described in greater detail below. At decision box 12, the operating conditions of the engine assembly are monitored. At least one sensor, at least one known condition, or a combination thereof can be used for monitoring or determining the operating conditions of the air charger system. After decision box 12, expected values are calculated by a control unit based upon the monitored operating conditions at decision box 14. Preferably, the expected values of decision box 14 are values for other operating conditions which were not monitored or known and used to calculate the expected values.

At decision box 16, the calculated expected values, of decision box 14, are compared to the other operating conditions indicative of proper air charger functions, which are monitored or known but were not used to calculate the expected values, of decision box 14. In decision box 18, it is then determined if the other operating conditions of decision
box 16 are outside a predetermined tolerance of the calculated expected values. If the other operating conditions of decision box 16 are not outside a predetermined tolerance of the calculated values, then the method 10 clears or resets the fault condition at decision box 17, and returns to decision box 12. However, if it is determined that the other operating conditions of decision box 16 are outside a predetermined tolerance of the calculated expected values of decision box 14, then the method 10 proceeds to decision box 20 where a fault condition is diagnosed. After diagnosing fault conditions the method 10 returns to decision box 12.

[0014] Referring to Figure 2, an engine assembly is generally shown at 29, having an air charger system generally indicated at 30. Air enters the air charger system 30 through an intake 32 and the air preferably passes through an air cleaner or filter 34. After the air passes through the filter 34, the air is separated into two paths. The air either passes through a first or turbine path generally indicated at 36 or a second or compressor path generally indicated at 38.

[0015] In an embodiment, when the air passes through the turbine path 36, the air can pass by a sensor 40 that is interfaced with a control unit 41. Preferably, the sensor 40 is a mass airflow sensor or a pre-existing sensor in the engine assembly 29 which performs other functions, but it is within the scope of the invention that the sensor 40 can be other types of sensors, as described below. After the air passes by the sensor 40, the air is again separated so that the air either passes through a secondary air charger generally indicated at 42 or a throttle 44. The air that passes through the secondary air charger 42 passes through a turbine 46 which is operatively coupled to a compressor 48 by a shaft 50. Thus, as the air rotates the turbine 46, the compressor 48 also rotates since the compressor 48 is connected to the turbine 46 by the shaft 50. A turbine valve 52 is downstream of the turbine 46, in order to control the amount of flow exiting the turbine 46.

[0016] The air that does not pass through the turbine 46, passes through the throttle 44, which is in parallel with the turbine 46. The position of throttle 44 can be actuated by any suitable actuation device that can be interfaced with a control unit, such as but not limited to, the control unit 41, in order to control the amount of air flowing by the throttle 44 or the turbine 46. Downstream of the throttle 44, the air that passed through the throttle 44 and the air that passed through the turbine 46 are reconnected and enter an intake 54 of an engine generally indicated at 56. Preferably, the engine 56 is a gasoline combustible engine.

[0017] The air that passes through the compressor path 38, passes through the compressor 48, passes through a backpressure valve 57, and is injected into an exhaust 58 of the engine 56. The backpressure valve 57 prevents any air from flowing back towards the compressor 48 from the engine 56, which can result from pressure differences between the compressor 48 and engine 56. Thus, the secondary air charger 42 is emitting compressed air that is injected into the exhaust 58 of the engine 56 for emission control purposes.

[0018] In reference to Figures 1 and 2, in operation the air charger system 30 is monitored in order for diagnosing a fault condition, if present, (decision box 20). As the air is flowing through the air charger system 30 as described above, the operating conditions of the engine assembly 29 are monitored (decision box 12). These operating conditions are either determined based upon sensors 40 monitoring the engine assembly 29, known values known by the control unit 41, or a combination thereof, described in greater detail below.

[0019] By way of explanation but not limitation, the operating conditions monitored and known are the commanded throttle 44 position known by control unit 41, the pressure at the intake 54 monitored by a pressure sensor 60 (shown in phantom) interfaced with the control unit 41, the ambient air pressure monitored by a pressure sensor 62 (shown in phantom) interfaced with the control unit 41, and the temperature of the intake 54 monitored by a temperature sensor 64 (shown in phantom) interfaced with the control unit 41. The calculated expected value of the mass air flow in the air charger system 30 (decision box 14) is then calculated by using the equation:

\[
MAF(A, MAP, AAP, IMT) = \frac{(A \times AAP) \times (k \times R \times IMT)^{\frac{k}{k+1}}}{(R \times IMT)^{\frac{2}{(k+1)}}}
\]

where A is the known commanded position of the throttle 44, MAP is the pressure at the intake 54, AAP is the ambient air pressure, and IMT is the intake 54 temperature.

The calculated mass airflow is then compared to the monitored mass airflow of the air charger system 30 using the mass airflow sensor 40 (decision box 16). It is then determined if the monitored or actual mass airflow is outside a predetermined tolerance of the calculated expected operating conditions (decision box 18). If the monitored mass airflow is within the predetermined tolerance then the method 10 clears the fault condition (decision box 17) and begins monitoring the operations conditions again (decision box 12). However, if the actual mass airflow is outside a predetermined tolerance,
then the fault is diagnosed (decision box 20), and the method 10 returns to decision box 12.

[0020] It should be appreciated that other sensors can be used to monitor the operating conditions of the air charger system 30, such as but not limited to, pressure sensors, temperature sensors, oxygen sensors, or the like. Depending upon which type of sensor 40, 60, 62, 64 is used in the engine assembly 29, the monitored operating conditions that are used to calculate expected values are likewise adapted or selected. Preferably, the sensors 40, 60, 62, 64 are pre-existing in the engine assembly 29 in that they are used to diagnose the air charger system 30 and have other uses in functioning of the engine assembly 29. Thus, additional components are not needed to implement the diagnostic method 10. This results in a more economical and cost efficient air charger system 30 and diagnostic method 10 than a system that requires additional components which have the sole use of diagnosing the air charger system 30.

[0021] Operating conditions that are known and/or monitored to calculate the expected value and the operating conditions known or monitored for comparing to the calculated expected values can be varied depending on available sensors or desired monitoring goals. For example, operating conditions can be monitored (decision box 12) and an expected throttle position can be calculated (decision box 14). The known or commanded throttle position can then be compared to the calculated throttle position (decision box 16) to determine if the commanded throttle position is outside a predetermined tolerance (decision box 18). Thus, the operating conditions that are monitored can be used in a predetermined equation to calculate an expected value of other operating conditions (decision box 16), which are compared to determine if the air charger system 30 is functioning properly (decision box 18), and if not, then diagnose a fault condition (decision box 20).

[0022] The description of the invention is merely exemplary in nature and, thus, variations that do not depart from the gist of the invention are intended to be within the scope of the invention. Such variations are not to be regarded as a departure from the spirit and scope of the invention.

Claims

1. A method for monitoring and diagnosing an air charger system (10) for an engine assembly (29) having pre-existing sensors, said method (10) comprising the steps of:

- providing an air charger system (30) having a turbine (46) and a compressor (48) operatively coupled to one another;
- providing a control unit (41) for monitoring a plurality of operating conditions (12) of said engine assembly (29);
- said control unit (41) calculating an expected value of a selected operating condition based upon at least one of said plurality of operating conditions (14);
- comparing said expected value and at least another of said plurality of operating conditions (16); and
- diagnosing a fault condition (20), if present, based upon said expected value and said at least another of said plurality of operating conditions being outside a predetermined tolerance (18).

2. The method for monitoring and diagnosing an air charger system (10) of claim 1 further comprising the step of monitoring said operating conditions (12) after diagnosing said fault condition (20).

3. The method for monitoring and diagnosing an air charger system (10) of claim 1 or 2 further comprising the step of clearing the fault condition (20) and monitoring said operating conditions (12) if said expected value is within said predetermined tolerance of said at least another of said plurality of operating conditions (16).

4. The method for monitoring and diagnosing an air charger system (10) of any preceding claim, wherein at least one of at least one sensor (40, 60, 62, 64), at least one known condition, and a combustion thereof, are used for said monitoring of said operating conditions (12).

5. The method for monitoring and diagnosing an air charger system (10) of claim 4 further comprising the step of providing a throttle (44) in operative fluid communication with said turbine (46) for controlling the flow through said turbine (46), wherein said known condition is a known commanded position of said throttle (44).

6. The method for monitoring and diagnosing an air charger system (10) of claim 5 further comprising the step of said control unit (41) calculating an expected throttle position (44) based upon said operating conditions (16).

7. The method for monitoring and diagnosing an air charger system (10) of claim 6 further comprising the step of comparing said commanded throttle (44) position to said calculated expected throttle (44) position (18) and diagnosing a fault condition (20) based upon said commanded throttle (44) position and said calculated expected throttle
8. The method monitoring and diagnosing an air charger system (10) of any preceding claim further comprising the step of providing a turbine valve (52) in operative fluid communication with said turbine (46) for controlling the flow of gaseous fluid exiting said turbine (46).

9. A method for monitoring and diagnosing an air charger system (10) for use in an engine assembly having pre-existing sensors, said method (10) comprising the steps of:

- providing an air charger (42) having a turbine (46) and a compressor (48) operatively coupled to one another;
- providing a control unit (41) interfaced with a plurality of sensors (40, 60, 62, 64);
- monitoring operating conditions of said engine assembly (29) by way of inputs from said plurality of sensors (40, 60, 62, 64);
- said control unit (41) calculating an expected value of a selected operating condition based upon data collected from at least one of a first set of sensors of said plurality of sensors (40, 60, 62, 64), at least one known value, and a combination thereof (14);
- comparing said expected value and data collected from a second set of sensors of said plurality of sensors (40, 60, 62, 64) (12);
- diagnosing a fault condition (20), if present, based upon said expected value and said data collected from said second set of sensors of said plurality of sensors (40, 60, 62, 64) being outside a predetermined tolerance (18); and
- clearing said fault condition (17) if said expected value is within said predetermined tolerance (18) of said data collected from said second set of sensors of said plurality of sensors (40, 60, 62, 64).

10. The method for monitoring and diagnosing an air charger system (10) of claim 9, wherein said first set of sensors is at least one of a pressure sensor (60, 62), a temperature sensor (64), an oxygen sensor, and a combination thereof.

11. The method for monitoring and diagnosing an air charger system (10) of claim 9 or 10, wherein said second set of sensors is a mass airflow sensor (40).

12. The method for monitoring and diagnosing an air charger system (10) of any preceding claim further comprising the step of determining an air pressure in an intake (54) of said engine (56).

13. The method for monitoring and diagnosing an air charger system (10) of any preceding claim further comprising the step of determining an ambient air pressure.

14. The method for monitoring and diagnosing an air charger system (10) of any preceding claim further comprising the step of determining a temperature in an intake (54) of said engine (56).

15. An air charger system (30) for use in an engine assembly (29) having at least an engine (56), said air charger system (30) comprising:

- a turbine (46) in fluid communication with an intake (54) of said engine (56);
- an intake (32) into said air charger system (30) in fluid communication with said turbine (46);
- a throttle (44) in operative fluid communication with said intake (32), wherein said throttle (44) is in parallel with said turbine (46) and controls the flow from said intake (32) through said turbine (46);
- a compressor (48) in fluid communication with said intake (32), wherein said compressor (48) is operatively coupled to said turbine (46), and compressed air is emitted from said compressor (48) and enters an exhaust (58) of said engine (56); and
- at least one sensor (40, 60, 62, 64) for monitoring operating conditions of said air charger system (30) and diagnosing a fault condition (20) upon failure of emitting compressed air from said compressor (48).

16. The air charger system (30) of claim 19, or the method of claim 4, wherein said at least one sensor is a mass airflow sensor (40), a pressure sensor (60, 62), a temperature sensor (64), an oxygen sensor, and a combination thereof.

17. The air charger system (30) of claim 15 or 16 further comprising a turbine valve (52) in operative fluid communication between said engine (56) and said turbine (46) for controlling the flow exiting said turbine (46).

18. The air charger system (30) of any one of claims 15 to 17 further comprising a control unit (41) interfaced with said
at least one sensor (40, 60, 62, 64), wherein the data collected from said at least one sensor by said control unit is
compared to a predetermined value based upon said operating conditions of said engine assembly (29) to determine
if said air charger system (30) is functioning properly.
**FIGURE 1**

1. Monitor operating conditions of the engine assembly
2. Calculate expected values based upon operating conditions
3. Compare calculated expected values and other operating conditions
4. Are the other operating conditions outside a predetermined tolerance of the calculated expected values?
   - No, go back to step 12
   - Yes, Diagnose a fault condition
5. Clear fault condition
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F02D

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The present search report has been drawn up for all claims.

**Place of search**: Munich

**Date of completion of the search**: 14 November 2006

**Examiner**: Jackson, Stephen

**CATEGORY OF CITED DOCUMENTS**

- **X**: particularly relevant if taken alone
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