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Imaging apparatus comprising a focus-error and/or tilt detection device

Abbildungseinrichtung mit einer Vorrichtung zur Detektion eines Fokussierfehlers und/oder einer Verkantung
Appareil de formation d’images muni d’un dispositif pour détecter une erreur de focalisation et/ou une inclinaison

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Description

The invention relates to an imaging apparatus comprising an imaging system and an opto-electronic focus error detection system for determining a deviation between the image plane of the imaging system and a second plane on which imaging is to take place, said focus detection system comprising a radiation source for supplying a focus detection beam, a radiation-sensitive detector arranged at the same side of the second plane as the radiation source, and optical elements for directing the focus detection beam onto the second plane at a small angle to said plane for changing the vergence, which means convergence or divergence, of said beam and of that of the beam reflected by the second plane and for directing the last-mentioned beam onto the detector.

An imaging apparatus of this type is known from, for example, US Patent 4,866,262. The apparatus described in this previous Patent may be part of what is commonly referred to as "wafer stepper", i.e. a machine for repetitively imaging a mask pattern on a substrate, for example, a silicon substrate by means of optical radiation, which machine is used in the manufacture of, for example, integrated circuits, briefly referred to as ICs. The pattern is imaged on a first sub-area, or field, of the substrate by means of a projection lens system and subsequently the substrate is moved over an accurately defined distance whereafter the pattern is imaged on a second substrate field, whereafter the substrate is moved again, and so forth until the pattern is imaged on all substrate fields.

Due to the fineness of the details which must be imaged, the projection lens system should have a large numerical aperture. However, such a lens system has a small depth of focus so that a deviation between the image plane of the projection lens system and the substrate surface must be accurately measured and possibly corrected. Said measurement is generally referred to as focus detection. Another problem is that the substrate surface may be arranged obliquely due to tilt of the substrate as a whole or thickness variations of this substrate. Moreover, the substrate surface may have local unevennesses. It is therefore necessary to perform a focus detection for each substrate field.

In the apparatus described in US Patent 4,866,262 the focus detection is performed with the aid of a laser beam which is incident on the substrate surface at a large angle, for example, of the order of 80°, to the normal on this surface where it forms a first radiation spot. The substrate surface reflects the beam towards a radiation-sensitive detector comprising two detector cells and forms a second radiation spot in the plane of the detector, which spot is an image of the first radiation spot. If the substrate surface coincides with the image plane of the projection lens system, the second radiation spot is located symmetrically with respect to the detector cells and the difference between the output signals of the detector cells is equal to zero. If the substrate surface does not coincide with said image plane, the second radiation spot is not located symmetrically with respect to the detector cells and said difference signal is unequal to zero. The magnitude and direction of a deviation between the substrate surface and the image plane of the projection lens system can be derived from the amplitude and the sign of this difference signal.

It is an object of the present invention to provide a novel focus detection device which is more accurate and more reliable than existing devices and to provide a more extensive device of this type with which a local tilt of the substrate surface can be detected. This invention has several aspects which are already new of themselves and provide considerable improvements of the focus detection, but, if combined, also result in a novel generation of focus detection devices and local-tilt detection devices.

The different aspects of the invention embodied in different classes of embodiments will now be described with reference to the problems to which they provide a solution.

A first aspect relates to the focus detection beam. In known focus detection devices, such as those described in US Patent 4,866,262, this is a laser beam which is monochromatic and whose wavelength is chosen to be such that the beam does not influence the substrate surface to be exposed. However, this substrate has a varying number of layers in which the focus detection beam can penetrate so as to be subsequently reflected again. Due to interferences caused by the substrate layer packet variations in the focus detection beam, which variations are independent of the distance between the substrate surface and the image field of the projection lens system, so that an erroneous focus detection signal is obtained. Although it is ensured, by causing the focus detection beam to graze the substrate surface, i.e. to be incident on this surface at a small angle, that the reflection on the substrate surface is relatively large and the influence of the substrate layer packet on the focus detection beam is relatively small, the remaining influence of the substrate layer packet on the focus detection beam still plays an important role in the greater focus detection accuracy which is required nowadays.

To reduce this influence, a first class of embodiments of the imaging apparatus in accordance with a first aspect of the invention is characterized in that the focus detection beam has a wide wavelength band and in that a first and a second grating are provided, the first grating being arranged in the radiation path between the radiation source and the second plane and the second grating being arranged between said second plane and the detector, whereby the grating period of the image of the first grating formed in the plane of the second grating is equal to that period of the second grating and the grating lines of said image extend in the same direction as the grating lines of the second grating.
Since the radiation of the focus detection beam has a wide spectrum and since said interference phenomena are different for each wavelength, the interferences are averaged out for the total beam so that the focus detection beam is no longer influenced by the substrate layer packet. Since with the use of radiation having a wide spectrum the dimension of the smallest radiation spot which can be formed on the substrate is larger than this dimension when using monochromatic radiation, and since the sensitivity, or resolving power, of the focus detection device is proportional to said dimension, the resolving power would decrease without any further measures. Still according to the invention, use is made of two gratings to prevent this, of which gratings one is imaged onto the other via reflection on the substrate. A grating displacement system is thereby created, whose sensitivity is proportional to the period of the gratings and with which very accurate measurements can be carried out.

It is to be noted that US Patent 4,650,963 describes an embodiment of a focus detection device for an IC projection apparatus in which a grating onto-grating image is used. However, this device comprises two independently operating parts each individually supplying focus information. The first part operates with a beam extending outside the projection lens system and being obliquely incident on the substrate surface, which beam is not referred to as a wideband beam, and does not comprise any gratings. The second part of the focus detection device is intended for visual observation, through a television camera and a television monitor, of the state of the focus and operates with a beam which enters the projection lens system via a mask grating mark. The mask mark is imaged onto the substrate surface and subsequently re-imaged onto itself via reflection on the substrate surface. Since said beam has the same wavelength as the beam which is used for projecting the mask pattern on the substrate and should not cause any variations in the substrate surface, it must have a low intensity so that the quality of the focus error detection is influenced detrimentally.

The embodiment of the first class is preferably characterized in that means are provided for periodically moving, with respect to each other, the image of the first grating and the second grating perceived by the detector. The detector signals are now periodic signals and a dynamic and hence more reliable focus error signal is obtained.

Said periodic movement can be realized by periodically varying the height of the substrate or by periodically moving one of the gratings or another optical element. However, an embodiment of the first class of the apparatus is preferably further characterized in that an optical element controlled by a periodical electric signal is arranged in the path of the focus detection beam, an optical property of said element varying periodically under the influence of the electric signal.

It is then unnecessary to perform extra mechanical movements for obtaining a dynamic focus error signal. It is to be noted that US Patent 4,614,664 describes a focus detection device for an IC projection apparatus in which an image, formed via the projection lens system and reflection on the substrate, of a pattern on a second, complementary pattern is oscillated for obtaining a dynamic focus error signal. In this device the focus detection beam traverses the projection lens system and is perpendicularly incident on the substrate. However, the first and second patterns are not separate gratings but the mask pattern and a pattern which is complementary thereto.

The preferred embodiment of the first class may be further characterized in that a polarization-sensitive element is arranged in front of the second grating for splitting the focus detection beam into two sub-beams which form images of the first grating in the plane of the second grating, said images being shifted with respect to each other over a distance which is equal to half the grating period of the second grating, in that a polarization rotator is arranged between the second grating and the detector, which rotator is controlled by a periodical signal for periodically varying the direction of polarization of the sub-beams, and in that a polarization analyser is arranged between the polarization rotator and the detector, the periodical signal being also applied to an electronic circuit for processing the output signal of the detector to a focus control signal.

Instead of this electro-optical modulator, other optical modulators such as a magneto-optical or an acousto-optical modulator can be used.

A special embodiment of the first class is characterized in that a retroreflector is arranged in the path of the focus detection beam reflected a first time by the second plane, which retroreflector reflects said beam along itself, and in that a beam-separating element is arranged between the second plane and the radiation source in the path of the focus detection beam reflected a second time by the second plane, said beam-separating element coupling out the twice-reflected beam towards the second grating and the detector arranged behind it.

Due to the double reflection of the focus detection beam at the same position of the second plane, or substrate, it is achieved that local differences in the reflection of the substrate do not have any influence on the focus error signal, while moreover the sensitivity of the focus detection device is increased by a factor of two.

In the known imaging apparatuses, known, inter alia, from US Patent 4,866,262, the position of the height of the second plane, or substrate surface, is determined with respect to a mounting part in which the radiation source, the detector and other components of the focus detection device are secured. This mounting part is connected to the holder of the projection lens system. By moving the holder with respect to the mounting part or by moving optical elements in the mounting part, the radiation spot formed by the focus detection beam can move with respect to the image field of the projection.
lens system. A second aspect of the invention relates to the method in which an erroneous focus error signal produced as a result of said instabilities can be prevented.

A second class of embodiments of the image projection apparatus relating thereto has the common characteristic feature that a reference beam is provided which is directed onto a surface of the imaging system located opposite the second plane and extends at a small angle to this surface, and a second detector arranged in the path of the reference beam reflected by the surface, a first and a second grating being arranged in the path of the reference beam, and the optical means arranged between the first grating and the second grating for directing and changing the vergence, which means convergence or divergence, being common for the two beams whereby the grating period of the image of the first grating formed in the plane of the second grating is equal to that period of the second grating and the grating lines of said image extend in the same direction as the grating lines of the second grating.

By defining the difference between the output signals of the two detectors, a signal is obtained which is only dependent on the distance between said lens surface and the second plane, which signal is not influenced by instabilities of the detection device because the focus detection beam and the reference beam traverse the same elements of the detection device.

It is to be noted that the article *"Chip Levelling and Focusing with Laser Interferometry"* in SPIE, Vol. 1284, Optical/Laser Microlithography III (1990), pp. 244-251 describes a device for local focus detection and tilt detection of a substrate in which a reference beam is used in addition to a focus detection beam reflected by the substrate. However, the first-mentioned beam is not reflected by a surface of the projection lens system so that it is not the distance between this lens surface and the substrate which is measured.

The second class of embodiments is preferably further characterized in that means are provided for the focus detection beam and the reference beam for periodically moving, with respect to each other, the image of the first and the second grating which are perceived by the detector for the relevant beam.

The advantages stated with reference to the first class of embodiments can then be obtained again. Said means may be constructed in the way as described in claims 8 and 9.

A first embodiment of the second class is further characterized in that a separate radiation source for supplying the reference beam is provided, in that a first beam-deflecting element is arranged between the radiation sources and the second plane in the path of the focus detection beam as well as of the reference beam for directing said beams onto the second plane and the surface of the imaging system, respectively, and in that a second beam-deflecting element is arranged between the second surface and the two detectors in the path of the focus detection beam as well as of the reference beam for directing said beams onto the first and the second detector, respectively.

The device can be given a compact form by using the deflection elements.

A second embodiment of the second class is further characterized in that a separate radiation source is provided for supplying the reference beam, in that a beam-deflecting element is arranged between the radiation sources and the second plane in the path of the focus detection beam as well as of the reference beam, in that a retroreflector is arranged in the path of the focus detection beam reflected a first time by the second plane and of the reference beam reflected a first time by the surface of the imaging system, and in that a first beam-separating element for coupling out the focus detection beam towards the first detector is arranged in the path of said beam reflected a second time by the second plane, while a second beam-separating element for coupling out the reference beam towards the second detector is arranged in the path of said beam reflected a second time by the surface of the imaging system.

Due to the double reflections on the second plane and on the surface of the imaging system the focus detection accuracy is increased by a factor of two, independently of local reflection differences of both the second plane and the surface of the imaging system.

The detection device may alternatively have only one radiation source.

A third embodiment of the second class, in which this is the case, is characterized in that a first birefringent element is arranged in the path of the beam supplied by the radiation source for splitting said beam into a focus detection beam having a first direction of polarization and a reference beam having a second direction of polarization and for directing said beams onto the second plane and the surface of the imaging system, respectively, and in that a second birefringent element is arranged in the paths of the beams reflected by the second plane and the surface of the imaging system, respectively, for deflecting the two beams towards each other and for directing the beams onto the first detector and the second detector, respectively.

As two birefringent elements are used, it is sufficient to use only one radiation source and, moreover, the device can be given a compact form.

A fourth embodiment of the second class is characterized in that a composite reflector is arranged in the path of the focus detection beam reflected by the second plane, in that the reference beam is formed by the beam reflected by the reflector and directed onto the surface of the imaging system and in that the first and the second detector are combined in one detector.

Since the beam incident on this detector has been in contact with the second plane as well as with the outer lens surface, this beam comprises information about the mutual distance between these planes. Instead of an electronic differentiation as in the previous embodiments an optical differentiation is now performed. More-
over, local refractive index differences due to, for example, turbulences of the medium in which the dual function beam propagates do not have any influence on the measuring signal.

The fourth embodiment may be further characterized in that a beam-deflecting element is arranged in the common path of the beam supplied by the radiation source and the beam reflected by the surface of the imaging system for deflecting the first-mentioned beam towards the second plane and for deflecting the last-mentioned beam towards the detector.

The device can be given a compact form by using the beam-deflecting element.

A fifth embodiment of the second class is characterized in that a first birefringent element is arranged in the path of the beam supplied by the radiation source, which element passes said beam as a focus detection beam towards the second plane, in that a second birefringent element is arranged in the path of the beam reflected by said plane, which element passes the reflected beam, in that a retroreflector reflecting the beam towards the second birefringent element is arranged in the path of the passed beam, which element deflects the beam as a reference beam towards the surface of the imaging system, and in that the first birefringent element deflects the beam reflected by said surface into the direction of the beam supplied by the radiation source.

A very attractive focus detection device according to the invention is obtained if characteristic features of the first class of embodiments are combined with characteristic features of the second class.

Such a device, which is based on the second class of embodiments, is characterized in that the focus detection beam has a wide wavelength band, in that a first grating is arranged in the radiation path of the focus detection beam as well as of the reference beam between the source supplying the relevant beam and the plane on which said beam is reflected for the first time, and in that a second grating is arranged between the detector for the relevant beam and a plane reflecting said beam towards the detector.

There are various embodiments of this device, which embodiments are analogous to the five embodiments of the second class, having as extra elements a plurality of gratings at different positions as described in claims 17 to 21.

The embodiments of the focus detection device according to the invention are preferably further characterized in that an adjustable optical element is arranged in front of the second plane in the radiation path of the focus detection beam for displacing, independently of a focus error, the radiation spot formed in the second plane for changing the zero of the generated focus error signal.

The adjustable element, which may be, for example, a tiltable plane-parallel plate or a movable auxiliary lens, can compensate for a displacement of the image plane of the imaging system resulting from a variation of an ambient parameter such as air pressure. Moreover, the operator of the imaging apparatus is enabled to set the zero of the focus error signal manually with reference to the results of experiments. The use of the adjustable element is known per se and described in detail in US Patent 4,266,262.

A third aspect of the present invention relates to a tilt detection device for detecting a tilt of the second plane with respect to the image plane of the imaging lens system, in which device use is made of the above-described aspects of the invention.

A tilt detection device using only the first aspect of the invention is characterized in that it comprises a first and a second detection unit each comprising a radiation source, a first and a second grating and a detector, the optical axis of the first unit being located in the XZ plane and the optical axis of the second unit being located in the YZ plane, and in that in each unit a first lens system is arranged in each unit between the first grating and the second plane for converting the beam from the grating into a parallel beam, while a second lens system is arranged between the second plane and the second grating for converting the parallel beam into a converging beam.

Since the beam is a parallel beam at the area of the second plane, a displacement of the second plane along the Z axis results in a displacement of the reflected beam parallel to itself. As a result, the image of the first grating shifts with respect to the second grating so that the detector signal changes.

This tilt detection device is preferably further characterized in that each detection unit comprises means for forming a reference beam which is directed onto a surface of the imaging system located opposite the second plane and extends at a small angle to said surface, and a second detector which is arranged in the path of the reference beam reflected by the surface of the imaging system.

The tilt of said surface of the imaging system can then also be determined. The means for forming the reference beam may be formed again by a separate radiation source or by a beam splitter, analogously as described with reference to the second class of embodiments.

A second main embodiment of the tilt detection device operating with beams focused on the second plane is characterized in that means for supplying at least two extra focus detection beams similar to said focus detection beam are provided for detecting tilts of the second plane about two mutually perpendicular X and Y axes of the image plane, in that each focus detection beam is directed onto a separate point of the second plane, at least two points taking up different X positions and at least two points taking up different Y positions.

The tilt detection can be performed very accurately by using a number of accurate focus detection devices for measuring at different points of the second plane.

It is to be noted that US Patent 4,504,144 describes
a projection apparatus for repetitively imaging a mask pattern on a substrate, in which the tilt of the substrate is measured by performing a focus error detection at three points on the substrate and by comparing the results of the three measurements. The focus detection itself of the known apparatus with the aid of an image of a mask via the substrate on a detector by means of a beam through the projection lens system is, however, different from that according to the present invention.

In the last-mentioned embodiment of the apparatus according to the invention it is possible to use three separate focus error detection systems for defining the tilt of the substrate, or the second plane. However, this apparatus is preferably characterized by two separate focus detection units with two focus detection beams each, the detector signals of the two focus detection units jointly comprising information about the tilt of the second plane about the X axis and the Y axis.

An optimum state can then be achieved as regards the number of measuring points vs. the complexity of the device.

When using wideband focus detection beams in combination with gratings, the range within which focus errors can be detected is defined by the periods of the gratings, which periods should preferably as small as possible so as to be able to measure the focus error with great accuracy.

A first possibility of increasing said range is realised in an embodiment which is characterized in that each grating is divided into two sub-gratings which have different grating periods.

The grating period of a sub-grating is, for example, 10% larger than that of the other sub-grating. As described in the article "Automatic Alignment System for Optical Projection Printing" in IEEE Transactions on Electron Devices Vol. ED-26, No. 4, 1979, pp. 723-8, a signal is obtained by means of the two gratings, which signal has a period which is, for example, ten times larger than that of the signal obtained with a single grating.

A second embodiment of the device providing a larger measuring range and with which also tests and calibrations can be performed is characterized in that an additional, bright radiation source is provided for supplying an extra, monochromatic, focus detection beam for forming an extra radiation spot in the second plane. The extra radiation spot is located, for example, between and symmetrically relative to the other radiation spots. A small radiation spot with which the high resolution required for testing can be achieved can be formed with the monochromatic beam.

The device providing the bright, extra beam is preferably characterized by an additional, bright, monochromatic, reference beam for forming an extra radiation spot on the surface of the imaging system.

The distance between the imaging system and the second plane is then also measured by means of the extra beams and the influence of instabilities on the focus error signal generated by means of the monochromatic beam is minimized.

To limit the number of optical elements between the imaging lens system and the second plane, this device is characterized in that in each detection unit the optical elements in the radiation path between the gratings are common for all focus detection beams and reference beams.

Due to the wide wavelength bands of the focus detection and reference beams these elements must be corrected for chromatic aberrations. To limit the number of correction requirements imposed on these elements, the focus and tilt detection device is further characterized in that the wavelength of the monochromatic focus detection beam and reference beam is located in the wavelength band of the other focus detection beams and reference beams.

The focus and tilt detection device with four wideband and one monochromatic focus detection beam and reference beams may have a number of specific characteristic features as described in claims 32 and 33.

The invention also relates to a projection apparatus for repetitively imaging a mask pattern on a substrate, which apparatus comprises an imaging apparatus as described hereinbefore and in which the imaging lens system is formed by an optical projection lens system with which the pattern is projected onto the substrate, and the second plane is formed by the surface of a substrate layer to be exposed, the signals of the focus detection system being used for setting the distance between the substrate and the projection lens system and/or the angle between the image plane of said lens system and said surface.

Embodiments of the invention will now be described in greater detail with reference to the accompanying drawings in which

Fig. 1 shows an embodiment of an apparatus for repetitively imaging a mask pattern on a substrate, and including a focus detection device.

Fig. 2 shows diagrammatically a first embodiment of a focus detection device according to the invention, with gratings and wideband beams.

Fig. 3 shows this embodiment in greater detail, with means for generating a dynamic focus error signal.

Figs. 4, 5a, 5b, 6a and 6b show the principle of the system used in this embodiment for generating a dynamic focus error signal.

Fig. 7 shows an embodiment of the focus detection device with gratings in which a retroreflector is used.

Figs. 8, 9, 9a, 10, 11, 12, 13 and 14 show embodiments of the focus detection device with a reference beam and including or not including gratings and reflectors.

Fig. 15 shows the principle of a tilt detection device making use of a grating-onto-grating image.

Figs. 16a and 16b show the principle of a tilt detection method based on multiple focus error detection.
Fig. 17 shows the principle of a device for performing said method.

Figs. 18a, 18b, 19a, 19b, 20a and 20b show, in a combination, an embodiment of such a tilt detection device.

Fig. 21 shows an embodiment of a grating plate used in this device.

Fig. 22 shows an embodiment of a radiation-sensitive detector used in this device.

Fig. 23 shows the combination of apertures imaged onto each other and the associated detector of a laser detection system for larger focus errors.

Fig. 24 shows the mechanical construction of a part of a pattern projection apparatus including a focus-error and tilt detection device, and

Fig. 25 shows a part of this apparatus with a stream of air for conditioning the space between the projection lens system and the substrate.

Fig. 1 shows the optical elements of an embodiment of an apparatus for repetitively imaging a mask pattern on a substrate. The main components of this apparatus are a projection column in which a mask pattern C is to be imaged and a movable substrate table WT with which the substrate can be positioned with respect to the mask pattern C. The apparatus further has an illumination system which comprises a radiation source LA, for example, a Krypton-Fluoride Excimer Laser, a lens system LS, a mirror RE and a condenser lens CO. The projection beam illuminates the mask pattern C which is present in the mask MA, which mask is arranged on a mask table MT.

The beam PB passing through the mask pattern C traverses a projection lens system PL arranged in the projection column and shown only diagrammatically, which system forms an image of the pattern C on the substrate W. The projection lens system has a magnification of, for example, $M = 1/5$, a numerical aperture $NA = 0.48$ and a diffraction-limited field having a diameter of 21.2 mm. The substrate is held by a substrate support WC which forms part of a substrate table WT which is only shown diagrammatically.

The apparatus further comprises a plurality of measuring devices, namely a device for aligning the mask MA with respect to the substrate W in the XY plane, an interferometer system for determining the position and orientation of the substrate holder and hence of the substrate, and a focus error detection device for determining a deviation between the focal or image plane of the projection lens system PL and the surface of the substrate W. These measuring devices are parts of servosystems which comprise electronic signal-processing and control circuits and drivers or actuators with which the position and orientation of the substrate and the focusing can be corrected with reference to the signals supplied by the measuring devices.

The alignment device uses two alignment marks $M_1$ and $M_2$ in the mask MA, indicated in the top right corner of Fig. 1. These marks preferably consist of diffraction gratings, but they may be alternatively formed by other marks such as squares or strips which are optically different from their surroundings. The alignment marks are preferably two-dimensional, i.e. they extend in two mutually perpendicular directions, the X and Y directions in Fig. 1. The substrate W, for example, a semiconductor substrate on which the pattern C must be imaged side by side several times, has a plurality of alignment marks, preferably also two-dimensional diffraction gratings, two of which, $P_1$ and $P_2$ are shown in Fig. 1. The marks $P_1$ and $P_2$ are located outside the areas on the substrate W where the images of the pattern C must be formed. The grating marks $P_1$ and $P_2$ are preferably phase gratings and the grating marks $M_1$ and $M_2$ are preferably amplitude gratings.

Fig. 1 shows a special embodiment of an alignment device, namely a double alignment device in which two alignment beams b and b' are used for aligning the substrate alignment mark $P_1$, the mask alignment mark $M_1$, and the substrate alignment mark $P_2$, the mask alignment mark $M_2$, respectively. The beam b is reflected by a reflecting element 30, for example, a mirror to the reflecting surface 27 of a prism 26. The surface 27 reflects the beam b to the substrate alignment mark $P_2$ which passes a part of the radiation as beam b₁ to the associated mask alignment mark $M_2$ where an image of the mark $P_2$ is formed. A reflecting element 11, for example, a prism is arranged above the mark $M_2$, which prism directs the radiation passed by the mark $M_2$ to a radiation-sensitive detector 13.

The second alignment beam b' is reflected by a mirror 31 to a reflector 29 in the projection lens system PL. This reflector 29 passes the beam b' to a second reflecting surface 28 of the prism 26, which surface directs the beam b' onto the substrate alignment mark $P_1$. This mark reflects a part of the radiation of the beam b' as beam b₁' to the mask alignment mark $M_1$ where an image of the mark $P_1$ is formed. The radiation of the beam b₁' passing through the mark $M_1$ is directed towards a radiation-sensitive detector 13'.
No. 4,778,275, is particularly suitable for an apparatus in which an illumination beam having a short wavelength, for example, 248 nm and an alignment beam having a considerably longer wavelength, for example, 633 nm are used. This is due to the correction lens 25 which during alignment ensures that by the projection lens system, which is designed for the wavelength of the projection beam PB, the alignment marks P1, P2 and M1, M2 are imaged onto each other by the alignment beams without any focus errors or magnification errors.

For accurately determining the X and Y positions of the substrate table WT, known projection apparatuses comprise a multi-axis interferometer system. US Patent 4,251,160 describes a two-axis system and US Patent 4,737,823 describes a three-axis system. In Fig. 1 such an interferometer system is diagrammatically illustrated by means of the elements 50, 51, 52 and 53, the Figure showing only one measuring axis. A beam b2 emitted by a radiation source 50 in the form of a laser is split into a measuring beam b2,m and a reference beam b2,r by a beam splitter 51. The measuring beam reaches a reflecting side face of the substrate support WC and the reflected measuring beam is combined by the beam splitter with the reference beam reflected by a stationary retroreflector 52, for example, a "corner cube". The intensity of the combined beam is measured with the aid of a detector 53 and the displacement, in this case in the X direction, of the substrate support WC can be derived from the output signal of this detector, and also an instantaneous position of this support can be established.

As is diagrammatically shown in Fig. 1, the interferometer signals represented by one signal S3 for the sake of simplicity, and the signals S13 and S12, of the alignment detection device are applied to a signal processing unit SPU, for example, a microcomputer which processes said signals to control signals SAC for an actuator AC with which the substrate support is moved in the X-Y plane via the substrate holder WH.

By using an X-Y interferometer system the positions of and the mutual distances between the alignment marks P1, P2 and M1, M2 can be established in a system of coordinates defined by the stationary interferometer system during the alignment procedure.

An interferometer system with five measuring axes, as described in Netherlands Patent Application No. 9100215 (PHQ 91.001) is preferably used. With such a system it is not only possible to measure the X and Y positions and the rotation about the Z axis of the substrate, but also tilts of the substrate about the X and Y axes. This interferometer system may be extended with a reference measuring axis so as to be able to correct for refractive index variations in the medium in which the interferometer beams propagate.

The projection apparatus further comprises a focus error detection system FDS shown diagrammatically in Fig. 1 for determining a deviation between the image plane of the projection lens system PL and the surface of the substrate W so that this deviation can be corrected by moving the substrate with respect to the projection lens system along the Z axis. The output signal, or focus error signal S, the system FDS is also applied to the signal processing unit SPU, so that one of the signals SAC is a control signal with which the distance between the lens system PL and the substrate W can be set via height actuators.

Fig. 2 shows diagrammatically a first embodiment of the focus detection system according to the invention, together with the lower part of the projection lens system PL. Only the last lens element PLE of this system is shown. The focus detection system comprises a radiation source S which supplies a focus detection beam b2. This beam is focused by a lens system diagrammatically represented by means of the lens element L1 in a radiation spot S on the substrate W. The angle of incidence α of the beam b2 on the substrate is relatively large, for example, of the order of 80°. The substrate reflects the beam b2 and the reflected beam b2′ is converted by a second lens system L2 into a converging beam which is captured by a radiation-sensitive detector DE which supplies an electric signal S.

According to the invention, the beam b2 has a relatively wide spectrum of wavelengths. It is thereby achieved that interferences which may be produced by multiple reflections on the different layers of the substrate are averaged out so that such interferences cannot influence the detector signal S. The wideband radiation source S is, for example, a halogen lamp, another incandescent lamp or a combination of a number of light-emitting diodes emitting different wavelengths. Such sources are, however, less intensive than the laser hitherto used. Consequently, the focus error signal obtained would have a reduced signal-to-noise ratio. Moreover, the dimension of the smallest radiation spot which can be formed on the substrate is larger when using radiation having a wide spectrum as compared with the use of a laser beam. Consequently, the sensitivity of the focus detection device, i.e. the smallest focus error which can still be detected, which sensitivity is proportional to the size of the radiation spot, would decrease. To obtain the desired sensitivity and the required signal-to-noise ratio with the novel device, a grating is arranged, according to the invention, in the beam, which grating is imaged on the substrate surface WS. This grating whose grating lines extend, for example, in the Y direction, i.e. perpendicular to the plane of the drawing in Fig. 2, is denoted G1. A second grating G2 having the same grating period as that of the grating G1 is arranged at the image side. The grating G1 is imaged on the grating G2 by means of the lens system L1 via reflection on the substrate surface and by means of the lens system L2. It has been ensured that the light and dark strips of the image of the grating G1 exactly coincide with those of the grating G2 if the substrate surface is located at the correct distance from the projection lens system PL. Then the detector DE receives a maximum quantity of
radiation and the output signal of the detector is maximal. When moving the substrate surface with respect to the system PL into the Z direction, the dark strips of the imaged grating will move and more cover the light strips of the other grating and the detector signal will become increasingly smaller. Thus, the magnitude of the focus error can be derived from the detector signal.

In principle, the accuracy with which the focus error can be determined is now determined by the period of the grating. This period is, for example, 40 μm with which focus errors of the order of 0.1 μm can still be measured if interpolation techniques are used when processing the detector signal. Since a larger area of the substrate surface is used for the focus detection, local reflection differences or unevennesses of this surface will have a smaller influence on the focus error signal obtained.

A dynamic focus error signal is preferably generated, i.e. a periodically varying signal in which the focus error introduces a variation into one of the signal parameters such as the amplitude or the ratio between the period halves. Such a signal is independent of possible offsets in the electronic signal processing device and enables a more accurate detection. Moreover, the sign of a focus error can then be determined.

A dynamic focus error signal can be generated by periodically displacing one of the elements in the radiation path of the focus detection beam. For example, the substrate itself can be moved periodically over small distances into the Z direction. However, for practical reasons it is preferred to use electro-optical means for generating a dynamic focus error signal. Fig. 3 shows an embodiment of the detection device provided with such means. This Figure also shows the optical system in greater detail.

This system comprises five lenses L3-L7 at the object side and four lenses L8-L11 at the image side. Fig. 3 shows two beams. The radiation source S is illustrated by means of the filament of a lamp. This lamp supplies a beam b5 shown by means of solid lines and single arrows, which beam passes through the pupil ST3 located between the lenses L4 and L5. This pupil is re-imaged between the lenses L6 and L7 and the beam b6 is incident as a parallel beam on the substrate surface. The reflected beam b6′ forms an image of the pupil between the lenses L8 and L9 and a second image between the lenses L10 and L11. At the area of the gratings G1 and G2 the beam b2 and the beam b6′ respectively, is a parallel beam.

The beam b2 shown by means of broken lines and double arrows illustrates how the source S is imaged on the first grating G1, and how this grating is imaged on the substrate. The figure further shows how the reflected beam b6′ forms an image of the first grating on the second grating and how this image and the grating G2 are imaged on the detector DE.

The means for generating a dynamic focus detection signal are constituted by a polarizer 60, a birefringent element 61, an electro-optical modulator 66 and an analyser 67. The operation of these means will be described in greater detail with reference to Figs. 4, 5 and 6. Fig. 4 shows said elements in a perspective elevation, as well as some rays of the oncoming beam b5 which is modulated by the grating structure G1, as is indicated by means of broken lines. The birefringent element 61 may be a Savart plate. This plate is composed of two equally thick plane-parallel quartz plates 62 and 63 whose optical axes 64 and 65 extend at an angle of 45° to the plane-parallel planes and which are mutually crossed. The polarizer 60 ensures that of the oncoming beam b5′= only the radiation having a direction of polarization at an angle of 45° to the optical axes of the Savart plate is passed towards this plate. The beam b5′ perpendicularly incident on the plane-parallel planes of the Savart plate is split in the first quartz plate 62 into an ordinary beam and an extraordinary beam which are converted into an extraordinary beam and an ordinary beam, respectively, at the interface of the first and the second quartz plate. In fact, the optical axes of the two plates are perpendicular to each other. Two mutually perpendicularly polarized sub-beams which are shifted with respect to each other exit from the Savart plate 26, as is shown diagrammatically in Fig. 4.

A polarization modulator 66 and an analyser 67 are arranged in front of the radiation-sensitive detector DE. The modulator is controlled by a voltage V4 which is supplied by a generator 68. The direction of polarization of a radiation beam passing through the modulator is thereby switched in an alternating manner. The direction of passage of the analyser is parallel to one of the directions of polarization of the ordinary and extraordinary beams from the Savart plate. As a result, either the ordinary or the extraordinary beam will be passed at any moment to the detector. This detector "sees" at a given moment either an ordinary beam G1 or an extraordinary beam of the grating G1 formed by the ordinary beam or an extraordinary image of this grating formed by the extraordinary beam, the ordinary and the extraordinary image being superimposed with the grating G2. The refractive indices of the Savart plate and the thicknesses of the composite plane-parallel plates have been chosen to be such that the ordinary and the extraordinary image are mutually shifted over half a period of the grating. If the grating G2 is arranged exactly between the ordinary and the extraordinary image of the grating G1, the intensity of the radiation captured by the detector DE will be constant with respect to time.

Fig. 5a shows this situation. The strips of the grating G2 of the ordinary image G1,o and of the extraordinary image G1,e of the grating G1 are perpendicular to the plane of the drawing. During a time interval t1 the detector receives the radiation intensity passed by G1,o and G2 (cf. Fig. 5b) and during a subsequent time interval t2 it receives the radiation intensity passed by G1,e and G2. These intensities are equal so that the detector signal S4 remains constant with respect to time.

If the grating G2 is not located exactly between G1,o and
and \( G'_{1,\text{e}} \), cf. Fig. 6a, the detector signal is not constant with respect to time, as is shown in Fig. 6b. The differences in the signal \( S_Q \) can be detected very accurately. This makes it possible to measure the displacement of the grating image \( G'_1 \) with respect to the grating \( G_2 \), which displacement is caused by a focus error, very accurately. If use is made of interpolation techniques in signal processing, focus errors of the order of 1/200 of the grating period can still be measured.

In the case of Fig. 6b, in which the grating image \( G'_1 \) is moved to the left with respect to the grating \( G_2 \), the detector signal in the time interval \( t_1 \) is larger than the detector signal in the time interval \( t_2 \). If the grating image \( G'_1 \) is moved to the right with respect to the grating \( G_2 \), the detector signal in the time interval \( t_1 \) will be smaller than in the time interval \( t_2 \).

As shown in Fig. 3, the signal of the detector DE is applied to the electronic processing circuit 70. The signal of the generator 68 is also applied to the circuit 70. By comparing in which time interval \( t_1 \) and \( t_2 \) the detector signal is largest, the direction of a possible focus error can be detected. The focus error signal obtained is applied via a high-voltage amplifier to an actuator 73, for example, one or more piezoelectric elements which displace the substrate support and hence the substrate over the desired distance and into the desired direction along the Z axis so that a focus error no longer occurs.

Instead of a Savart plate it is also possible to use a Wollaston prism as is denoted by 61 in Fig. 3. Such a prism comprises two congruent sub-prisms of single-axis birefringent crystals which are formed to one plane-parallel plate. The optical axes of the sub-prisms are mutually perpendicular. A radiation beam incident on one of the plane-parallel large faces of the prism 61 is split in the prism into two sub-beams having mutually perpendicular directions of polarization. By suitable choice of the parameters of the prism 61 it can be ensured that the images, formed by the sub-beams, of the grating \( G_1 \) at the location of the grating \( G_2 \) are shifted over half a grating period.

Fig. 7 shows an embodiment of the focus detection device in which a retroreflector RR is arranged in the path of the focus detection beam reflected once by the substrate surface. This reflector may be a hollow mirror, a corner cube prism or, as is shown in Fig. 7, a combination of a lens \( L_{12} \) and a reflector RE in the focal plane of this lens. This retroreflector reflects the beam along itself, i.e. the principal axis of the beam incident on the reflector coincides with that of the reflected beam \( b_{2}^{\prime} \).

The beam halves of the beams are then interchanged. As described in US Patent 4,356,392, this has the advantage that local reflection differences of the substrate cannot influence the intensity distribution within the radiation spot which is ultimately formed on the detector DE. The beam \( b_{2}^{\prime} \), which is reflected a second time by the substrate surface is coupled out to the second grating \( G_2 \) and the detector DE arranged behind it by a beam-separating element BS. Due to the double reflection on the substrate surface the sensitivity of the focus detection device is increased by a factor of two. Also in the embodiment of Fig. 7 a dynamic focus error signal can be generated in the ways as described with reference to Fig. 3. This also applies to the embodiments to be described hereinafter.

In the embodiments of Figs. 2, 3 and 7 focus errors are measured in an indirect way, i.e. only the Z position of the substrate is measured, assuming that the substrate is the only moving element so that also the distance between the substrate and the projection lens system is known. To achieve the required stability in the focus detection device and the stability of this device with respect to the projection lens system to a certain extent, the optical elements in the radiation path of the focus detection beam, from the radiation source to the detector, may be fixed in a holder, analogously as described in US Patent 4,356,392, or in a mounting plate, which holder or plate is connected to the projection lens system. Notably if smaller details must be imaged and if the focusing must thus be detected and adjusted more accurately, the extent of stability to be achieved may be too small. The remaining instabilities are caused by remaining clearances of the optical elements in their fittings and of these fittings in the holder or mounting plate and by clearance in the connection of the holder or mounting plate to the holder of the projection lens system.

In accordance with a second aspect of the present invention the above-mentioned problem can be prevented by making use of a reference beam which is directed onto a plane at the lower side of the projection lens system which is parallel to the substrate, for example, the outer surface of a transparent reference plate which is especially arranged in the projection lens system for reflecting the reference beam. Said plane reflects the reference beam towards a second detector. The actual distance between the substrate and the projection lens system can then be measured from the difference of the signals of this second detector and of the first detector receiving the focus detection beam. The use of the reference beam is not limited to the embodiments with gratings in the focus detection beam. The use of the reference beam may also yield considerable advantages in more conventional focus detection devices without gratings.

Fig. 8 shows a first embodiment of a focus detection device with a reference beam \( b_{2}^{\prime} \). A reference plate \( RP \) is now arranged underneath the last lens element PLE of the projection lens system. The reference beam grazes this plate, i.e. the angle of incidence \( \beta_3 \) is large, for example, equally large as the angle of incidence \( \alpha_3 \) on the substrate W. The reference beam is reflected by the plate \( RP \) and the reflected beam \( b_{2}^{\prime} \) is captured by a detector \( DE_3 \), for example, a photodiode. A second photodiode \( DE_1 \) which captures the focus detection beam \( b_{1}^{\prime} \) reflected by the substrate may be arranged in series with this photodiode. As is denoted symbolically by means
of the meter ME, the difference of the output signals of the photodiodes is measured. This difference signal is a measure of the distance between the plate RP and the substrate W. Actually, the difference signal is compared with a reference signal in an electronic signal processing circuit and a control signal is generated for an actuator with which, for example, the substrate is moved into the Z direction. The radiation source S comprises two radiation-emitting elements, for example, LEDs S1 and S2.

A first grating is preferably arranged at the object side and a second grating is preferably arranged at the image side in the radiation path of both the focus detection beam and the reference beam, which gratings are imaged onto each other by means of the lens systems L1 and L2 and reflections on the substrate and the reference plate, respectively. The radiation passed by the gratings at the image side is captured by the detectors DE1 and DE2. The gratings in the focus detection beam and the reference beam may be separate elements, similarly as the elements of the lens systems L1 and L2. However, the grating G1 at the object side and the grating G2 at the image side and the lens systems are preferably common for the two beams.

In the embodiment of Fig. 8 it is also possible to generate a dynamic focus error signal by arranging a polarizer and a birefringent element in front of the grating G2 and a polarization modulator behind this grating, as is described with reference to Figs. 3, 4, 5 and 6.

Fig. 9 shows diagrammatically an embodiment of the focus detection device which is compact because of the use of special optical systems which are represented, for the sake of simplicity, by single wedge-shaped elements WO1 and WO2 on which lens elements are arranged. The system WO1 deflects the focus detection beam b2 and the reference beam b2 in such a way that these beams graze the substrate and the reference plate, respectively and also converts the diverging beams into converging beams. The optical system WO2 converts the diverging reflected beams b2 and b2 into converging beams and deflects these beams towards the detector DE1 and the detector DE2, respectively. The device of Fig. 9 may be formed with or without gratings G1, G2.

The embodiment of Fig. 9a is based on the principle of that of Fig. 9. Now only one special optical system WO with a wedge and lenses is used. A retroreflector RE, for example, in the form of a hollow mirror is arranged in the paths of the focus detection beam b1 and the reference beam b1 reflected by the substrate W and the reference plate RP, respectively. This mirror reflects the beams along themselves so that they are reflected a second time by the substrate and the reference plate, respectively. The focus detection beam is incident on a beam separator 77 which reflects the beam towards a first detection grating G2,1 and a detector DE1 arranged behind it. The reference beam is incident on a beam separator 78 which reflects the beam towards a second detection grating G2,2 and a detector DE2 arranged behind it.

Figs. 10 and 11 show embodiments of the focus detection device in which use is made of beams having different directions of polarization. In Fig. 10 the reference numeral 80 denotes a composite prism having a polarization-sensitive interface 81. This face reflects a beam component having a first direction of polarization, for example, perpendicularly to the plane of the drawing, as a focus detection beam towards the substrate W. The second beam component, whose direction of polarization is parallel to the plane of the drawing, is passed by the interface 81 and subsequently reflected as reference beam b2 by the rear face 82 of the prism towards the reference plate RP of the projection lens system PL.

Since the beam b2 is incident at a different angle on the interface 81, this beam is passed. A second composite prism 85 which is analogous to prism 80 is arranged in the path of the reflected beams b1 and b1. The polarization-sensitive face 86 of the prism 85 reflects the beam b1 as beam b1 towards the detector DE2, while the rear face 87 of this prism reflects the beam b1, as beam b1, towards the detector DE2. The geometry of the prism 85 is slightly different from that of the prism 80 so that the beams b1 and b1 are spatially separated.

In the embodiment of Fig. 11 a composite birefringent element 90, such as a Wollaston prism or a Rochon prism is used for spatially separating the mutually perpendicularly polarized components of the beam b. These beam components are reflected as beams b2 and b2 by a prism 92 towards the substrate W and the reference plate. A prism 93 analogous to the prism 92 and a birefringent element 91 analogous to the element 90 are arranged in the path of the reflected beams b1 and b1. Here again the elements differ to such an extent that the beams b1 and b1 leave the element 91 are spatially separated.

The devices according to Figs. 10 and 11 may also comprise a wideband radiation source and gratings and may also be provided with means for generating a dynamic focus error signal.

Fig. 12 shows a further alternative of the embodiment in which differently polarized beams are used as focus error detection beams and reference beams. A composite prism 100 comprising two sub-prisms of birefringent material separated by an interface 101 are arranged in the path of the beam emitted by the source S. The beam component having a first direction of polarization passes the interface 101 unhindered and is obliquely incident on the substrate W as focus detection beam b2. The beam component having the second direction of polarization is deflected at the interface 101 between the first sub-prism and the second sub-prism and is obliquely incident on the reference plate of the projection lens system as reference beam b2. After reflection by the substrate and the reference plate, the beams b2 and b2 are combined by a second composite prism 102 also comprising two birefringent sub-prisms and an interface 103 which operates in a way reverse
to that of prism 100. The prism 102 has a slightly different geometry than the prism 100 so that the beams $b_1$ and $b_4$ are spatially separated to a sufficient extent to be incident on the separate detectors $D_1$ and $D_2$. The use of a wideband source $S$ and gratings $G_1$ and $G_2$ is optional again, similarly as the generation of a dynamic focus error signal.

The concept of a focus detection device with a focus detection beam and a reference beam may also be realised with a single beam instead of with two separate beams, which single beam is successively reflected on the substrate and on the reference plate. Embodiments are shown in Figs. 13 and 14.

In the device of Fig. 13 the beam $b_5$ from the source $S$ is converged by an optical system 110 illustrated by means of an optical wedge and lenses and is deflected in such a way that it grazes the substrate $W$. The reflected beam $b_1^*$ reaches a reflector 112 and is reflected successively by the interfaces 113 and 114. This beam now functions as the reference beam $b_5$ which grazes the reference plate of the projection lens system PL. The reflected reference beam is deflected towards and converged on the detector $D_1$ by the optical system 110. If the distance between the reference plate and the substrate is correct, the optical path covered by the beam with which the source is imaged on the detector is such that this image is correctly positioned with respect to the detector $D_1$. When changing the distance between the plate $R$ and the substrate, said optical path length changes and said image is shifted with respect to the detector.

In the embodiment of Fig. 14 use is made of a prism 120 which comprises two sub-prisms of different birefringent material. The beam $b_5$ emitted by the source $S$ has such a direction of polarization and is incident on the interface 121 at such an angle that this beam is passed towards the substrate $W$. A second prism 122 analogous to the prism 120 is arranged in the path of the reflected beam $b_5^*$ which prism passes this beam towards a retroreflector 125, for example, comprising a lens 127 and a mirror 128 in its focal plane. The beam is now reflected along itself and is incident on the second prism in a direction opposite to that at the first passage. Then the beam is deflected towards the reference plate $R$ and functions as reference beam $b_5$. The beam $b_5^*$ reflected by the plate $R$ is then deflected by the prism 120 in such a way that it coincides with the original beam $b_5$. A beam-separating element $126$ couples a part of the beam $b_5^*$ towards the detector $D_1$ is arranged in the path of the coincident beams.

In the embodiments gratings $G_1$ and $G_2$ can again be used in combination with a beam having a large wavelength band. Then the elements 110 and 112 of Fig. 13 and the elements $L_1$, 120, 122 and $L_2$ of Fig. 14 must be satisfactorily corrected for the different wavelengths. A dynamic focus error can then again be generated in the way as described with reference to Figs. 3, 4 and 5.

For each field of the substrate on which a mask pattern must be projected a focus error can be measured at one point of this field with the aid of the devices described so far. The substrate as a whole may be wedge-shaped or may be arranged obliquely, or the substrate may have local unevennesses so that points of the field outside the point where the focus error is measured may remain defocused, resulting in an inaccurate image at these points. In an apparatus for repetitively imaging a mask pattern on a substrate it is therefore desirable to be able to determine the local tilt, or tilt per field and to correct this tilt, for example, by means of a number of height actuators for the substrate.

The grating concept can be used for realising the tilt. Its principle is shown in Fig. 15. The diverging beam $b_3$ supplied by the radiation source $S_1$ and passing through the grating $G_1$ is converted into a parallel beam by a lens system $L_1$. This beam is reflected by the substrate $W$ and subsequently converged by a second lens system $L_2$. The lens system $L_1$ and $L_2$ jointly form an image of the grating $G_1$ on the grating $G_2$. It has been ensured that in the case of a horizontal substrate surface the grating lines of the imaged gratings coincide with those of the grating $G_2$. Since the beam incident on the substrate $W$ is a parallel beam, the reflected beam $b_3'$ will acquire a different direction when the substrate is tilted, so that the image of $G_1$ shifts with respect to $G_2$ and the detector receives more, or less radiation.

As is shown in Fig. 15, use is preferably made of a reference beam $b_4$. With this beam a grating $G_4$ is imaged on a grating $G_2$ via reflection on the reference plate $R$, whereafter the beam $R$ is incident on a second detector $D_2$. The position of the image of the grating $G_1$ on the grating $G_2$, and hence the output signal of the detector $D_2$ is determined by the position of the reference plate $R$. The tilt of this plate can thus also be measured.

It is to be noted that there may be modifications of the embodiment of Fig. 15. For example, the two separate radiation sources may be replaced by one radiation source in combination with beam-splitting means.

A local tilt detection can be performed by performing a focus error measurement at three points of the field, as is diagrammatically shown in Fig. 16a. This Figure shows a substrate $W$ with a substrate field $W_0$ in which the points where the focus detection is performed are denoted by $a$, $b$, and $c$. For each focus measurement a separate focus detection device can be used in one of the above-described embodiments. By comparing the focus measuring signals $S_{ab}$ and $S_{bc}$ of the points $a$ and $b$, the tilt $\theta_a$ about the X axis can be determined and by comparing the focus measuring signal $S_{bc}$ of the point $c$ with $S_{bc}$ and/or $S_{ab}$, the tilt $\theta_b$ about the Y axis can be determined. The signals of the three measuring points, and possible further measuring points can also be combined in a different way and the measuring points may also have a different mutual positioning.

According to the invention, two focus detection devices in accordance with the principles described above
can be used for measuring the local tilt, which devices supply two focus detection beams each. With these beams it is possible to measure at a large number of points, namely four points, while the tilt detection device is not too complex. Fig. 16b shows the location of the measuring points a, b, c and d in the substrate field W. The squares S_{1d}, S_{1c}, S_{2d} and S_{2c} are the radiation spots formed by the four focus detection beams. These spots have a surface area of, for example, 2 x 2 mm². The radiation spots are located close to the edges of the substrate field so as to measure the tilt as accurately as possible. The angles γ₁ and γ₂ are, for example, 20° and 25°.

If the focus detection devices operate with wideband beams and gratings, the radiation spots S_{1d}, S_{1c}, S_{2d} and S_{2c} are larger than is shown in Figs. 16a and 16b. When a wideband less intensive radiation source is used, the beam cross-section and hence the exposed substrate surface must be larger so as to obtain sufficient radiation energy on the detector so that the device has a sufficient sensitivity. Because of this sensitivity, gratings are also used. To reduce the risk of reflection effects, the gratings should have a large number of grating lines, which means that the radiation spot on the substrate must be large.

Fig. 17 shows the principle of the tilt detection device comprising two double focus detection devices. The chief rays h₁ and h₂ of the first focus detection device are denoted by means of solid lines and the chief rays h₃ and h₄ of the second focus detection device are denoted by broken lines. The reference symbols a, b, c and d are the points where these chief rays are incident on the substrate W. The figure only shows a small part of this substrate. The elements which ensure that the focus detection beams graze the substrate are represented by the mirrors M₁ and M₂ for the sake of simplicity. Each double focus detection device is divided into three blocks: an illumination block B₁, an imaging block B₂ and a detection block B₃, which blocks will be described with reference to the following embodiment. Although this has not been shown for the sake of simplicity in Fig. 17, the tilt detection device comprises gratings and/or phase gratings which are reflected on the reference plate of the projection lens system, as will be described hereinafter.

An embodiment of the tilt detection device diagrammatically shown in Fig. 17 is shown in Figs. 18, 19 and 20, which figures show, in this order, the blocks B₁, B₂ and B₃ which are actually arranged one after the other. The figures indexed a are vertical cross-sections and those indexed b are horizontal cross-sections.

In Figs. 18a and 18b the reference numeral 130 denotes the radiation source, preferably the filament of a halogen lamp, which emits a continuous spectrum in the wavelength range of 725 nm to 1050 nm. The filament has dimensions of, for example, 3.6 x 1.8 mm². The beam b emitted by the lamp is captured by a condenser lens 131 which is, for example, an aspherical lens, and is converted into a parallel beam. Subsequently, the beam is converged by a second condenser lens 133 which is, for example, an aspherical lens. The lenses 131 and 133 combined form an image of the filament.

A blue filter may be arranged between the lenses 131 and 133 to prevent blue radiation emitted by the halogen lamp from reaching the substrate and to prevent such radiation from reaching other measuring systems of the projection apparatus, which systems operate with this short-wave radiation.

An optical fibre 134 is preferably used. The lamp can then be placed at a larger distance, for example, 1.5 m from the detection device so that this device cannot be heated by the thermal radiation of the lamp. Moreover, the fibre can adapt the width-height ratio of the filament to the grating dimensions. The entrance plane of the fibre 134 coincides with the filament image formed by the lens system 131, 133. In view of the requirements to be imposed further down the system, the fibre has a relatively small numerical aperture, for example, 0.22.

The fibre branches out in two fibre ends 135, 136, the first end supplying an illumination beam b₁ and the second end supplying an illumination beam b₂, intended to illuminate a measuring grating 157 and a reference grating 158, respectively. These gratings are arranged on the flat rear side of a transparent supporting plate 150. To image the exit plane of the fibre 135 on the grating 157, a lens system which is, for example, telecentric and which comprises a condenser lens 137 and a plano-convex lens 139 is used. To obtain a uniform illumination of the grating 157, the image of the fibre exit plane is formed slightly outside the plane of the grating. The exit plane of the fibre 136 is imaged on the grating 158 by means of a lens system 138, 140 which is identical to the system 137, 139.

In connection with the available space it may be necessary to deflect the optical axis of the illumination system, ensuring that the axis is perpendicular to the plane of the gratings. This deflection can be realised by means of the mirror 160 shown diagrammatically.

In the vertical plane the illumination beam b₄ must extend at a small angle of, for example, -6.5° to the optical axis, while the illumination beam b₃ must extend at an opposite angle of, for example, +6.5° to this axis. To this end, the front side of plate 150 has two oblique ends 152 and 153, making the plate ends wedge-shaped and deflecting the beams at the right angle. In the horizontal plane the illumination beams b₃ₘ and b₃ₜ are parallel to the optical axis.

Figs. 19a and 19b show how the gratings 157 and 158 are imaged on the substrate W and the reference plate of the projection lens system, respectively, by means of a telecentric system 170. This system, which is diagrammatically represented by the lens elements 171, 172, does not only form the grating images by means of the focus detection beam b₃ and the reference beam b₄, but also deflects this beam with respect to the optical axis at angles which are equally large but oppo-
site to the angles at which the wedge-shaped ends of the grating plate 150 deflect. The beams reflected by the substrate W and the reference plate RP traverse a second telecentric system 175 which is analogous to the system 170. The system 175 ensures a re-image of the image of the measuring grating and the reference grating formed on the substrate and the reference plate, respectively. These re-images are formed on a detection measuring grating 187 and a detection reference grating 188. These gratings are arranged on the flat front side 186 of a transparent support 180 and, in case of a 1-to-1 image, they have the same geometry as the gratings 157 and 158. The grating plate 180 has the same shape as the plate 150 but is rotated through 180° about an axis in the plane of the drawing and perpendicular to the optical axis so that the wedges deflect the beams away from the optical axis.

If necessary in view of the available space, a first and a second mirror 190 and 191 may be arranged in the path of the focus detection beam b2 for deflecting the beams towards the substrate and the reference plate and a third and a fourth mirror 192 and 193 for redetecting the beams from the substrate and the reference plate.

A birefringent plate 200 of, for example, quartz is arranged in front of the grating plate 180, which plate ensures that "ordinary" and "extraordinary" images of the gratings 157 and 158 are formed on the gratings 187 and 188, as has been explained with reference to Figs. 3 and 4, in which the extraordinary images are shifted over half a grating period with respect to the gratings 187 and 188. As has been shown in Figs. 3 and 4, the birefringent plate must be preceded by a polarizer. This polarizer may be formed by means of a polarization foil provided between two plane-parallel plates which jointly form one plate 205. The plates 200 and 205 must be perpendicular to the beams b2 and b3, so that each plate is divided into two parts 201 and 202 and 206 and 207, respectively, which are perpendicular to the associated beams.

Figs. 20a and 20b show the detection block of the double focus detection device in vertical and horizontal cross-sections. This block comprises a lens 210 and a lens 211 which jointly form a telecentric system imaging the gratings 187 and 188 on different parts of a detector 215. If desired, a mirror 212 may be provided, which mirror deflects the beams upwards (Z direction) and thus has a function reverse to that of the mirror 160 (Fig. 18).

A polarization modulator 220 switching the direction of polarization of the beams through 90° and an analyzer 225 passing only radiation of a given direction of polarization towards the detector 215 are arranged between the lenses 210 and 211. The modulator may be formed by a quartz crystal 221 with a λ/4 plate 222, 223 at both sides thereof. This modulator is preferably arranged in the pupil of the lens system 210, 211.

In Figs. 18, 19 and 20 it has been shown as if the focus detection beam and the reference beam are incident on different gratings 157, 158 and 187, 188, respectively. The gratings 157 and 158, and 187 and 188 are preferably two separate parts of a first composite grating and a second composite grating, respectively. Such a composite grating 230 arranged on the plate 150 is shown in Fig. 21. The grating on the plate 180 has the same geometry. As is shown in Fig. 21, the grating parts 157 and 158 may in their turn be divided into a left-hand part and a right-hand part so that there is a total number of four grating parts. The grating parts 231 and 232 cooperate with the focus detection beam and the grating parts 233 and 234 cooperate with the reference beam. The length 1 of the composite grating 230 is such that the length of the image thereof on the substrate is slightly smaller than the length of a substrate field, so that the grating parts are imaged as much as possible at the edges of this substrate field.

The detector 215 on which the grating parts of the first grating (157, 158) and of the second grating (187, 188) are imaged is then divided into four quadrants 240, 241, 242, 243 as is shown in Fig. 22. The tilt of the substrate about the X axis of Fig. 1 can be determined by comparing the signals of the detector parts 240 and 241, while the tilt of the reference plate RP about the X axis can be determined by comparing the signals of the detector parts 242 and 243. To determine the tilts of the substrate and of the reference plate about the Y axis, a second double focus detection device analogous to that shown in Figs. 18, 19 and 20 must be used. This second device is preferably arranged at an angle of 90° to the first device. A total number of four focus detection beams and two reference beams is then used instead of the four focus detection beams shown in Fig. 17. This Fig. 17 does not show any reference beams.

Due to changes of the ambient parameters such as air pressure, temperature and humidity the refractive index of the medium in which the elements of the projection lens system are present may change. As a result, the imaging qualities and the position of the image plane may vary. To compensate for these variations and to enable the operator of the apparatus to set said position, for example, with reference to experiments performed, the focus detection device may be provided with an adjustable compensation plate 250 (Fig. 19). This plate is arranged in the focus detection beam directly behind the first grating plate 150. The plate 250 is, for example, a glass plate and its thickness is also determined by that of the plates 200 and 205. By rotating the plate about an axis perpendicular to the plane of the drawing in Fig. 19a, the positions of the images of the left-hand and right-hand portions of the grating 157 can be shifted with respect to the detector portions, independent of the Z position of the substrate. The zero of the focus error signal derived from the detector signals can thus be set.

For the grating measuring system the range within which focus errors can be detected is determined by the period of the grating. For a grating period of, for example, 40 μm the capture range extends, for example, from
-20 µm to +20 µm.

To increase the capture range, each grating of the focus detection device or the tilt detection device, for example, each of the gratings 231-234 of Fig. 21 may be divided into two sub-gratings whose grating periods are, for example, 10% different. In an analogous way as described for an alignment system in the article "Automatic Alignment System for Optical Projection Printing" in IEEE Transactions on Electron Devices Vol. ED-26, No. 4, 1979, pp. 723-728, signals having, for example, a ten times larger period can then be obtained for a focus detection device and a tilt detection device, which signals make it possible to detect errors which are ten times larger.

The present invention provides a further possibility of increasing the capture range in which it is also possible to test and/or calibrate. To this end, the device according to the invention is provided with a second focus detection system which operates without gratings and with an extra beam, for example, a laser beam. With this beam an extra radiation spot is formed on the substrate, which spot is small in size and is therefore well suited for testing. This system will hereinafter be referred to as the auxiliary detection system. This system preferably also has a double construction with a first beam which is reflected by the substrate and a second beam which is projected by the reference plate of the projection lens system. The elements of the auxiliary detection system are shown in Figs. 18, 19 and 20, with Fig. 20b only showing the chief rays of the two auxiliary beams b1, b1, in dot-and-dash lines for the sake of clarity.

The first part of the auxiliary detection system comprises a radiation source 260, for example, a diode laser combined with a collimator lens. The auxiliary beam b1 is constricted by a telescopic lens system 261, 262 and is deflected by a wedge 263 towards the grating plate 150. This plate has a gap-shaped aperture for this beam, which aperture is denoted by 264 in Fig. 21. The aperture 264 is smaller than the beam cross-section in situ so that the aperture functions as a new radiation source. The width-height ratio of the gap-shaped aperture is chosen, for example, such that the image of this aperture on the substrate is square, as also holds for the gratings 157, 158 and their images on the substrate.

An extra wedge 154 may be provided on the grating plate so as to ensure that the beam from the aperture 264 is incident on the substrate W at a specific angle. On its way to the substrate the beam b1 meets the same elements 250, 170, 190, 191 as the focus detection beam b2. From the substrate to the second grating plate 180 the beam b1 meets the same elements 193, 192, 175, 205, 200 as the reflected focus detection beam b2'. The auxiliary beam b1 exits through a special aperture structure from the grating plate and is imaged on a detector 273 by a lens system 271, 272. An optical wedge 270 giving the beam the right direction is arranged in front of this lens system. A further wedge 184 which is comparable to the wedge 154 on the grating plate 150 may be arranged on the grating plate.

The special aperture structure for the beam b1', on the grating plate 180 is formed by two rectangular apertures 300 and 301, as shown in Fig. 23. The image of the aperture 264 formed thereon is denoted by 302. The radiation passed through each aperture is captured by a separate detector part of the detector 273. These detector parts 274 and 275 are shown by way of broken lines in Fig. 23. A focus error signal is obtained by comparing the signals of the detector parts 274 and 275. The detector 273 which is commonly referred to as a bi-cell detector is characterized in that the radiation-sensitive areas 274 and 275 are relatively large, whereas the distance between the strips is relatively small. The auxiliary detection system with said aperture structure on the grating plate 180 and with the bi-cell detector has the advantage that it is not necessary to impose stringent requirements on the tolerance or the stability of the elements.

The second part of the auxiliary detection system which operates with a beam b1, reflected by the reference plate of the projection lens system comprises the elements 280, 281, 282, 283, 155, 170, 175, 207, 202, 185, 290, 291, 292 and 293 which are identical to and fulfill the same functions as the elements 260, 261, 262, 263, 154, 170, 175, 206, 201, 270, 271, 272 and 273 of the first part of this system.

The distance between the substrate and the projection lens system can be determined by comparing the output signals of the two auxiliary detection systems.

The average focus error per substrate field can be determined in the tilt detection device of Figs. 19-20 by averaging the focus errors measured at the points a, b, c and d.

To supplement the schematic representation of an apparatus for repetitively imaging a mask pattern on a substrate of Fig. 1, Fig. 24 shows details of the mechanical construction of the focus and tilt detection device and the way in which this device is connected to the projection lens system PL. This system is secured in a plate PT in which holders H1 and H2 are arranged at the right and left for the illumination part and the detection part, respectively. The illumination part accommodates the fibre ends 135, 136 for the supply of the wideband beams, the lenses 137, 138, 139 and 140 for these beams, the diode lasers 260, 280, the lenses 261, 262, 281, 282 and the wedges 263, 283 for the diode laser beams. The telecentric lens system 170 (not shown), the grating plate 150, the folding mirror 160 and the mirrors 190 and 191 are present in a holder H3 which is secured to a mounting plate MP which in its turn is connected to the plate PT.

A similar holder H4 is arranged at the left and accommodates the mirrors 192 and 193, the telecentric lens system 175 (not shown), the grating plate 180 and the folding mirror 212. The holder H4, which is secured in the plate PT, accommodates the modulator 221, the analyser 225 and the detector for the wideband beam.
The wedges 270, 290, the lenses 271, 272, 291 and 292 and the detectors 273, 293 are present for the laser beams.

The apparatus comprises a second focus error and tilt detection device with a second set of four holders arranged in front of and behind the plane of the drawing in Fig. 24, preferably in a plane perpendicular to the plane of the drawing. Only a tilt of the substrate about the Y axis is to be measured with the second device. The holders of the second device need only accommodate the optical elements of Fig. 24 which are present in the path of the wideband beams.

In an apparatus for repetitively imaging a mask pattern on a substrate it can be ensured that constant circumstances prevail in the space between the projection lens system and the substrate. This can be realised by passing a constant, preferably laminar stream of air through this space. This is illustrated in Fig. 25. This figure diagrammatically shows a part of the projection lens system PL and the substrate support WC. The substrate support forms part of a substrate table WT which can move across a base plate BP via an air cushion AB under the control of an actuator system in a H configuration described in, for example, US Patent 4,665,594, whose components are denoted by MO1 and MO2 in Fig. 25. Fig. 25 again shows the holders H1 and H2 which are secured to the mounting plate MP, on which plate the interferometer system shown in Fig. 1 and illustrated in Fig. 25 only diagrammatically by means of IFS is preferably also secured. Said air stream is denoted by the arrows AF. This air stream is passed through an air stream conducting plate FGP. This plate may be dimensioned in such a way that the space above the substrate to be illuminated is covered so that the beams of the focus error and tilt detection device but also the substrate are present in a well-conditioned space.

Both the purity and the temperature of the supplied air can be controlled. This air, for example, of purity class 1 and its temperature is, for example, stable within 0.1 °C. The latter can be achieved by arranging a heat exchanger in the vicinity of the substrate support.

The invention has been described with reference to its use in an apparatus for repetitively imaging a mask pattern on a substrate, for the manufacture of, for example, integrated circuits (ICs), integrated optical systems or planar optical systems, guidance and detection patterns for magnetic domain memories or of a structure of liquid crystal display panels. Although in the first instance the invention is intended for these uses, it is not limited thereto. It can generally be used in optical measuring and inspection apparatuses in which the position of an imaging lens system or another reference and/or the tilt of this surface must be determined very accurately. These may be apparatuses for manufacturing patterns such as IC patterns, LCD patterns, etc. which operate with a laser beam or an electron beam, pattern projection apparatuses which operate with X-ray radiation, or accurate measuring apparatuses, for example, those used for measuring masks or substrates.

Claims

1. An imaging apparatus comprising an imaging system (PL) and an opto-electronic focus error detection system (FDS) for determining a deviation between the image plane of the imaging system and a second plane (WS) on which imaging is to take place, said focus detection system comprising a radiation source (S) for supplying a focus detection beam (b2s1), a radiation-sensitive detector (DE1) arranged at the same side of the second plane (WS) as the radiation source, and optical elements (L1, L2) for directing the focus detection beam onto the second plane (WS) at a small angle to said plane for changing the vergence, which means convergence or divergence, of said beam and of that of the beam (b2s1) reflected by the second plane and for directing the last-mentioned beam (b2s1) onto the detector, characterized in that the focus detection beam (b2s1) has a wide wavelength band and in that a first (G1) and a second (G2) are provided, the first grating being arranged in the radiation path between the radiation source (S) and the second plane (WS) and the second grating (G2) being arranged between said second plane and the detector DE whereby the grating period of the image of the first grating (G1) formed in the plane of the second grating (G2) is equal to that period of the second grating and the grating lines of said image extend in the same direction as the grating lines of the second grating.

2. An imaging apparatus as claimed in Claim 1, characterized in that means (61, 66, 67) are provided for periodically moving, with respect to each other, the image (G1*) of the first grating (G1) and the second grating (G2*) perceived by the detector DE.

3. An imaging apparatus as claimed in Claim 2, characterized in that an optical element (66) controlled by a periodical electric signal (V2s) is arranged in the path of the focus detection beam (b2s1), an optical property of said element varying periodically under the influence of the electric signal.

4. An imaging apparatus as claimed in Claim 3, characterized in that a polarization-sensitive element (61) is arranged in front of the second grating (G2) for splitting the focus detection beam (b2s1) into two sub-beams which form images of the first grating in the plane of the second grating, said images being shifted with respect to each other over a distance which is equal to half the grating period of the second grating, in that a polarization rotator (66) is arranged between the second grating (G2) and the de-
tector (DE), which rotator is controlled by a periodical signal \(V_3\) for periodically varying the direction of polarization of the sub-beams, and in that a polarization analyzer (67) is arranged between the polarization rotator and the detector, the periodical signal being also applied to an electronic circuit (70) for processing the output signal of the detector \(S_{DE1}\) to a focus control signal.

5. An imaging apparatus as claimed in Claim 1, 2, 3 or 4, characterized in that a retroreflector (RE) is arranged in the path of the focus detection beam \(b_2\) reflected a first time by the second plane (WS), which retroreflector reflects said beam along itself, and in that a beam-separating element (BS) is arranged between the second plane (WS) and the radiation source (S) in the path of the focus detection beam \(b_2^{**}\) reflected a second time by the second plane, said beam-separating element coupling out the twice-reflected beam \(b_2^{**}\) towards the second grating \(G_2\) and the detector (DE) arranged behind it.

6. An imaging apparatus comprising an imaging system (PL) and an opto-electronic focus error detection system (FDS) for determining a deviation between the image planes of the imaging system and a second plane (WS) on which imaging is to take place, said focus error detection system comprising a radiation source (S) for supplying a focus detection beam \(b_2\), a radiation-sensitive detector \(DE_1\) arranged at the same side of the second plane (WS) as the radiation source, and optical elements \(L_1, L_2\) for directing the focus detection beam onto the second plane at a small angle to said plane for changing the vergence, which means convergence or divergence, of said beam and of that of the beam reflected by the second plane and for directing the last-mentioned beam onto the detector, characterized in that a reference beam \(b_4\) is provided which is directed onto a surface (R) of the imaging system (PL) located opposite the second plane (WS) and extends at a small angle to said surface, and a second detector \(DE_2\) arranged in the path of the reference beam \(b_2^{**}\) reflected by the surface (R), a first \(G_1\) and a second grating \(G_2\) being arranged in the path of the reference beam \(b_4\), and the optical means \(L_1, L_2\) arranged between the first grating and the second grating for directing and changing the vergence being common for the two beams \(b_2, b_4\) whereby the grating period of the image of the first grating \(G_1\) formed in the plane of the second grating \(G_2\) is equal to that period of the second grating and the grating lines of said image extend in the same direction as the grating lines of the second grating.

7. An imaging apparatus as claimed in Claim 6, characterized in that means \(61,66,67\) are provided for the focus detection beam \(b_2\) and the reference beam \(b_4\) for periodically moving, with respect to each other, the image \(G_1\) of the first grating \(G_1\) and the second grating \(G_2\), which are perceived by the detector \(DE_1, DE_2\) for the relevant beam.

8. An imaging apparatus as claimed in Claim 7, characterized in that an optical element \(66\) controlled by a periodical electric signal \(V_3\) is arranged in the paths of the focus detection beam \(b_2\) and the reference beam \(b_4\), an optical property of said element \(66\) varying periodically under the influence of the electric signal \(V_3\).

9. An imaging apparatus as claimed in Claim 8, characterized in that a polarization-sensitive element \(61\) is arranged in front of the second grating \(G_2\) in the paths of the focus detection beam \(b_2\) and the reference beam \(b_4\) for splitting each \(b_2, b_4\) focus detection beam and reference beam into two sub-beams which form images of the first grating \(G_1\) in the plane of the second grating \(G_2\), said images being shifted with respect to each other over a distance which is equal to half the grating period of the second grating, in that a polarization rotator \(66\) is arranged between a second grating \(G_2\) and a detector \(DE_1, DE_2\) for periodically varying the direction of polarization of the sub-beams, and in that a polarization analyzer (67) is arranged between the polarization rotator \(66\) and the detector \(DE_1, DE_2\), the periodical signal \(V_3\) being also applied to an electronic circuit (70) for processing the output signal of the detectors to a focus error signal.

10. An imaging apparatus as claimed in Claim 6, 7, 8 or 9, characterized in that a separate radiation source \(S_3\) for supplying the reference beam \(b_4\) is provided, in that a first beam-deflecting element \(WO_1\) is arranged between the radiation sources \(S_1, S_3\) and the second plane (WS) in the path of the focus detection beam \(b_2\) as well as of the reference beam \(b_4\) for directing said beams onto the second plane and the surface (R), respectively, of the imaging system (PL), and in that a second beam-deflecting element \(WO_2\) is arranged between the second plane (WS) and the two detectors \(DE_1, DE_2\) in the path of the focus detection beam as well as of the reference beam for directing said beams onto the first and the second detector, respectively.

11. An imaging apparatus as claimed in Claim 6, 7, 8 or 9, characterized in that a separate radiation source is provided for supplying the reference beam \(b_4\), in that a beam-deflecting element \(WO\) is arranged between the radiation sources \(S_1, S_2\) and the second plane (WS) in the path of the focus de-
tection beam (b₂) as well as of the reference beam (b₁), in that a retroreflector (RE) is arranged in the path of the focus detection beam (b₂) reflected a first time by the second plane (WS) and of the reference beam (b₁) reflected a first time by the surface (RP) of the imaging system (PL), and in that a first beam-separating element (77) for coupling out the focus detection beam (b₂) towards the first detector (DE₁) is arranged in the path of said beam reflected a second time by the second plane (WS), while a second beam-separating element (78) for coupling out the reference beam (b₁) towards the second detector (DE₂) is arranged in the path of said beam reflected a second time by the surface (RP) of the imaging system (PL).

12. An imaging apparatus as claimed in Claim 6, 7, 8 or 9, characterized in that a first birefringent element (80; 90; 100) is arranged in the path of the beam (b₂) supplied by the radiation source (S) for splitting said beam into a focus detection beam (b₂) having a first direction of polarization and a reference beam (b₁) having a second direction of polarization and for directing said beams onto the second plane (WS) and the surface (RP) of the imaging system (PL), respectively, and in that a second birefringent element (85; 91; 102) is arranged in the paths of the beams (b₂', b₁') reflected by the second plane (WS) and the surface (RP) of the imaging system, respectively, for deflecting the two beams towards each other and for directing the beams onto the first detector (DE₁) and the second detector (DE₂), respectively (Figs. 10, 11, 12).

13. An imaging apparatus as claimed in Claim 6, 7, 8 or 9, characterized in that a composite reflector (112) is arranged in the path of the focus detection beam (b₂') reflected by the second plane (WS), in that the reference beam (b₁') is formed by the beam reflected by the reflector and directed onto the surface (RP) of the imaging system and in that the first and the second detector are combined in one detector, (DE) (Fig. 13).

14. An imaging apparatus as claimed in Claim 13, characterized in that a beam-deflecting element (110) is arranged in the common path of the beam (b₂) supplied by the radiation source and the beam reflected (b₁) by the surface (RP) of the imaging system for deflecting the first-mentioned beam (b₂) towards the second plane (WS) and for deflecting the last-mentioned beam (b₁) towards the detector (DE).

15. An imaging apparatus as claimed in Claim 6, 7, 8 or 9, characterized in that a first birefringent element (120) is arranged in the path of the beam (b₂) supplied by the radiation source (S), which element passes said beam as a focus detection beam towards the second plane (WS), in that a second birefringent element (122) is arranged in the path of the beam (b₂') reflected by said plane, which element passes the reflected beam, in that a retroreflector (125) reflecting the beam towards the second birefringent element (122) is arranged in the path of the passed beam, which element (122) deflects the beam as a reference beam (b₁) towards the surface (RP) of the imaging system (PL), and in that the first birefringent element (120) deflects the beam (b₁') reflected by said surface (RP) into the direction of the beam supplied by the radiation source (Fig. 14).

16. An imaging apparatus as claimed in Claim 5, 6, 7, 8 or 9, characterized in that the focus detection beam (b₂) has a wide wavelength band, in that a first grating (G₁) is arranged in the radiation path of the focus detection beam (b₂) as well as of the reference beam (b₁) between the source (S₁, S₂) supplying the relevant beam and the plane (WS, RP) on which said beam is reflected for the first time, and in that a second grating (G₂) is arranged between the detector (DE₁, DE₂) for the relevant beam and a plane reflecting said beam towards the detector.

17. An imaging apparatus as claimed in Claim 10, characterized in that the radiation source (S₁, S₂) supplies a beam having a wide wavelength band and in that a first grating (G₁) is arranged between said source (S₁, S₂) and the first deflection element (WD₁) and a second grating (G₂) is arranged between the second deflection element (WD₂) and the detector (DE₁, DE₂).

18. An imaging apparatus as claimed in Claim 11, characterized in that the focus detection beam (S) has a wide wavelength band, in that a first grating (G₁) is arranged between the radiation sources (S₁, S₂) and the deflection element (WO₁), in that a second grating (G₂) is arranged between the beam-deflecting element (WO₂) and the first detector (DE₁) in the radiation path of the reflected focus detection beam (b₂) and in that a third grating (G₃) is arranged between the beam-deflecting element and the second detector (DE₂) in the radiation path of the reflected reference beam (b₁).

19. An imaging apparatus as claimed in Claim 12, characterized in that the radiation source (S) supplies a beam having (b₁) a wide wavelength band, and in that a first grating (G₁) is arranged between the radiation source (S) and the first birefringent element (80; 90; 100) and a second grating (G₂) is arranged between the second birefringent element (85; 91; 102) and the detectors (DE₁, DE₂).

20. An imaging apparatus as claimed in Claim 13 or 14,
characterized in that the radiation source (S) supplies a beam having a wide wavelength band and in that a first grating (G₁) is arranged between the radiation source and the second plane (WS) in the radiation path of said beam and a second grating (G₂) is arranged between the surface (Rp) of the imaging system (PL) and the detector (DE).

21. An imaging apparatus as claimed in Claim 15, characterized in that the radiation source (S) supplies a beam having a wide wavelength band and in that a first grating (G₁) is arranged between the source (S) and the first birefringent element (120) in the radiation path of said beam and a second grating (G₂) is arranged between said element (120) and the detector (DE).

22. An imaging apparatus as claimed in Claim 1 or 6, characterized in that an adjustable optical element (250) is arranged in front of the second plane (WS) in the radiation path of the focus detection beam (bᵣ) for displacing, independently of a focus error, the radiation spot (Sp) formed in the second plane for changing the zero of the generated focus error signal.

23. An imaging apparatus as claimed in Claim 1, 2 or 3, characterized in that it comprises a first and a second detection unit for determining tilts of the second plane about two mutually perpendicular X and Y axes, each detection unit comprising a radiation source (S₁), a first and a second grating (G₁, G₂) and a detector (DE₁), the optical axis of the first unit being located in the XZ plane and the optical axis of the second unit being located in the YZ plane, and in that in each unit a first lens (L₁) system is arranged between the first grating (G₁) and the second plane (WS) for converting the beam (bᵣ) from the grating into a parallel beam, while a second lens system (L₂) is arranged between the second plane (WS) and the second grating (G₂) for converting the parallel beam into a converging beam (b₂ᵣ).

24. An imaging apparatus as claimed in Claim 23, characterized in that each detection unit comprises means (S₂) for forming a reference beam (b₂) which is directed onto a surface (R₀) of the imaging system (PL), located opposite the second plane (WS) and extends at a small angle to said surface, and a second detector (DE₂) which is arranged in the path of the reference beam (b₂₁) reflected by the surface of the imaging system.

25. An imaging apparatus as claimed in Claim 1 or 6, characterized in that means (B₁,B₂) for supplying at least two extra focus detection beams (h₂,h₃,h₄) similar to said focus detection beam (h₁,bᵣ) are provided for detecting tilts of the second plane (WS) about two mutually perpendicular X and Y axes of the image plane, in that each focus detection beam is directed onto a separate point (a,b,c,d) of the second plane, at least two points taking up different X positions and at least two points taking up different Y positions.

26. An imaging apparatus as claimed in Claim 25, characterized by two separate focus detection units (B₁₁,B₁₋₁,B₂₋₄) with two focus detection beams (h₁,h₂,h₃,h₄) each, the detector signals of the two focus detection units jointly comprising information about the tilt of the second plane about the X axis and the Y axis.

27. An imaging apparatus as claimed in Claim 1, 6, 23, 24, 25 or 26, characterized in that each grating (G₁, G₂, 157, 158, 187, 188) is divided into two sub-gratings which have different grating periods.

28. An imaging apparatus as claimed in Claim 1, 6, 23, 24, 25 or 26, in which the focus detection beams have wide bands and traverse gratings, characterized in that an additional, bright radiation source (260) is provided for supplying an extra, monochromatic, focus detection beam (b₁) for forming an extra radiation spot in the second plane (WS).

29. An imaging apparatus as claimed in Claim 28, characterized by an additional, bright, monochromatic, reference beam (b₁₋₄) for forming an extra radiation spot on the surface (R₀) of the imaging system (PL).

30. An imaging apparatus as claimed in Claim 23, 24, 25, 26, 27, 28 or 29, characterized in that in each detection unit the optical elements (250, 170, 190, 191, 193, 192, 75, 205, 200) in the radiation path between the gratings (157, 158, 187, 188) are common for all focus detection beams (bₘ₋₄,b₄) and reference beams (bₘ₋₁,b₁₋₁).

31. An imaging apparatus as claimed in Claim 28, 29 or 30, characterized in that the wavelength of the monochromatic focus detection beam (b₁) and reference beam (b₁₋₄) is located in the wavelength band of the other focus detection beams (bₘ₋₄) and reference beams (bₘ₋₁).

32. An imaging apparatus as claimed in Claim 25, 26, 27, 28, 29, 30 or 31, characterized in that within a focus detection unit two focusing beams are formed by one beam (bₘ₋₄) two parts of which are incident on two different grating parts (231,232).

33. An imaging apparatus as claimed in any one of Claims 28 to 32, characterized in that two grating parts (231,232) of the first grating (157) and of the second grating (187) are arranged on a first grating
plate (150) and on a second grating plate (180), respectively, and in that the first grating plate has one first aperture (264) for the monochromatic beam (b₁) and the second grating plate has two second apertures (300, 301) for said beam, said second apertures being located symmetrically with respect to the first aperture (264).

34. A projection apparatus for repetitively imaging a mask pattern (C) on a substrate (W), comprising an imaging apparatus as claimed in Claim 1, 6, 23, 25, 27 or 28, in which the imaging lens system is formed by an optical projection lens (PL) system with which the pattern is projected onto the substrate, and the second plane is formed by the surface (WS) of a substrate layer to be exposed, the signals of the focus detection system (FDS) being used for setting the distance between the substrate (W) and the projection lens system (PL) and/or the angle between the image plane of said lens system and said surface.

Patentansprüche

1. Abbildungsgerät mit einem Abbildungssystem (PL) und einem optoelektronischen Fokusfehlerdetektionssystem (FDS) zum Bestimmen einer Abweichung zwischen der Bildebene des Abbildungssystems und einer zweiten Ebene (WS), auf der Abbildungen erfolgen soll, wobei das genannte Fokusdetektionssystem eine Strahlungsquelle (S) zum Liefern eines Fokusdetektionsstrahlbündels (b₂, b₆) umfaßt, einen an der gleichen Seite der zweiten Ebene (WS) wie die Strahlungsquelle angeordneten strahlungsempfindlichen Detektor (DE₁) sowie optische Elemente (L₁, L₂) zum Richten des Fokusdetektionsstrahlbündels auf die zweite Ebene (WS) unter einem kleinen Winkel zu der genannten Ebene, um die Vergenz, d.h. Konvergenz oder Divergenz, des genannten Strahlbündels und der des an der zweiten Ebene reflektierten Strahlbündels (b₂') zu ändern, und zum Richten des letztgenannten Strahlbündels (b₂') auf den Detektor, dadurch gekennzeichnet, daß das Fokusdetektionsstrahlbündel (b₂, b₆) ein breites Wellenlängenband hat und daß ein erstes Gitter (G₁) und ein zweites Gitter (G₂) vorgesehen sind, wobei das erste Gitter im Strahlungsweg zwischen der Strahlungsquelle (S) und der zweiten Ebene (WS) und das zweite Gitter (G₂) zwischen der genannten zweiten Ebene und dem Detektor DE angeordnet ist, wodurch die Gitterperiode des Bildes des in der Ebene des zweiten Gitters (G₂) gebildeten ersten Gitters (G₁) gleich der Periode des zweiten Gitters ist und die Gitterlinien des genannten Bildes in gleicher Richtung verlaufen wie die Gitterlinien des zweiten Bildes.

2. Abbildungsgerät nach Anspruch 1, dadurch gekennzeichnet, daß Mittel (61, 62, 67) vorgesehen sind, um das vom Detektor DE wahrgenommene Bild (G₁) des ersten Gitters (G₁) und des zweiten Gitters (G₂) periodisch zueinander zu bewegen.

3. Abbildungsgerät nach Anspruch 2, dadurch gekennzeichnet, daß ein von einem periodischen elektrischen Signal (Vₚ) gesteuertes optisches Element (66) im Weg des Fokusdetektionsstrahlbündels (b₂') angeordnet ist, wobei eine optische Eigenschaft des genannten Elements sich unter dem Einfluß des elektrischen Signals periodisch verändert.

4. Abbildungsgerät nach Anspruch 3, dadurch gekennzeichnet, daß ein polarisationsempfindliches Element (61) vor dem zweiten Gitter (G₂) angeordnet ist zum Aufteilen des Fokusdetektionsstrahlbündels (b₂') in zwei Teilstrahlenbündel, die Bilder des ersten Gitters in der Ebene des zweiten Gitters bilden, wobei die genannten Bilder zueinander um einen Abstand verschoben sind, der gleich der halben Gitterperiode des zweiten Gitters ist, daß ein Polarisationsdrehglied (66) zwischen dem zweiten Gitter (G₂) und dem Detektor (DE) angeordnet ist, welches Drehglied von einem periodischen Signal (Vₚ) zum periodischen Verändern der Polarisierungsrichtung der Teilstrahlenbündel gesteuert wird, und daß ein Polarisationsanalyserator (67) zwischen dem Polarisationsdrehglied und dem Detektor angeordnet ist, wobei das periodische Signal einer elektronischen Schaltung (70) zugeführt wird zum Verarbeiten des Ausgangssignals des Detektors (S₀) zu einem Fokussteuerungssignal.

5. Abbildungsgerät nach Anspruch 1, 2, 3 oder 4, dadurch gekennzeichnet, daß ein Retroreflektor (RF) im Weg des ein erstes Mal an der zweiten Ebene (WS) reflektierten Fokusdetektionsstrahlbündels (b₂') angeordnet ist, welcher Retroreflektor das genannte Strahlbündel entlang sich selbst reflektiert, und daß ein Strahlbündel trennendes Element (BS) zwischen der zweiten Ebene (WS) und der Strahlungsquelle im Weg des ein zweites Mal an der zweiten Ebene reflektierten Fokusdetektionsstrahlbündels (b₂') angeordnet ist, wobei das genannte Strahlbündel trennende Element das zweifach reflektierte Strahlbündel (b₂') zum zweiten Gitter (G₂) und dem dahinter angeordneten Detektor (DE) auskoppelt.

6. Abbildungsgerät mit einem Abbildungssystem (PL) und einem optoelektronischen Fokusfehlerdetektionssystem (FDS) zum Bestimmen einer Abweichung zwischen der Bildebene des Abbildungssystems und einer zweiten Ebene (WS), auf der Abbildungen erfolgen soll, wobei das genannte Fokusfehl-
erdetektionssystem eine Strahlungsquelle (S) zum Liefern eines Fokudetektionsstrahlenbündels (b₂) umfaßt, einen an der gleichen Seite der zweiten Ebene (WS) wie die Strahlungsquelle angeordneten strahlungsempfindlichen Detektor (DE₁) sowie optische Elemente (L₁, L₂) zum Fichten des Fokudetektionsstrahlenbündels auf die zweite Ebene unter einem kleinen Winkel zu der genannten Ebene, um die Vergenz, d.h. Konvergenz oder Divergenz, des genannten Strahlenbündels und der des an der zweiten Ebene reflektierten Strahlenbündels zu ändern, und zum Fichten des letztgenannten Strahlenbündels auf den Detektor, dadurch gekennzeichnet, daß ein Bezugsstrahlenbündel (b₃) vorgesehen ist, das auf eine gegenüber der zweiten Ebene (WS) liegende Oberfläche (Rp) des Abbildungssystems (PL) gerichtet ist und unter einem kleinen Winkel zu der genannten Oberfläche verläuft, und ein im Weg des an der Oberfläche (Rp) reflektierten Bezugsstrahlenbündels (b₅) angeordneter zweiter Detektor (DE₂), wobei ein erstes (G₁) und ein zweites Gitter (G₂) im Weg des Bezugsstrahlenbündels (b₅) angeordnet sind und wobei die zwischen dem ersten Gitter und dem zweiten Gitter zum Richtten und Ändern der Vergenz angeordneten optischen Mittel (L₁, L₂) den beiden Strahlenbündeln (b₃, b₅) gemeinsam sind, wodurch die Gitterperiode des Bildes des in der Ebene des zweiten Gitters (G₂) gebildeten ersten Gitters (G₁) gleich der Periode des zweiten Gitters ist und die Gitterlinien des genannten Bildes in gleicher Richtung verlaufen wie die Gitterlinien des zweiten Bildes.

7. Abbildungsgerät nach Anspruch 6, dadurch gekennzeichnet, daß für das Fokudetektionsstrahlenbündel (b₃) und das Bezugsstrahlenbündel (b₅) Mittel (61, 66, 67) vorgesehen sind, um das vom Detektor (DE₁, DE₂) für das betreffende Strahlenbündel wahrgenommene Bild (G₁) des ersten Gitters (G₁) und des zweiten Gitters (G₂) periodisch zueinander zu bewegen.

8. Abbildungsgerät nach Anspruch 7, dadurch gekennzeichnet, daß ein von einem periodischen elektrischen Signal (Vₚ) gesteuertes optisches Element (66) im Weg des Fokudetektionsstrahlenbündels (b₅) und des Bezugsstrahlenbündels (b₅) angeordnet ist, wobei eine optische Eigenschaft des genannten Elements (66) sich unter dem Einfluß des elektrischen Signals (Vₚ) periodisch verändert.

9. Abbildungsgerät nach Anspruch 8, dadurch gekennzeichnet, daß ein polarisationsempfindliches Element (61) vor dem zweiten Gitter (G₂) im Weg des Fokudetektionsstrahlenbündels (b₃) und des Bezugsstrahlenbündels (b₅) angeordnet ist zum Aufteilen jedes (b₅) Fokudetektionsstrahlenbündels und Bezugsstrahlenbündels in zwei Teilstreifenbündel, die Bilder des ersten Gitters (G₁) in der Ebene des zweiten Gitters (G₂) bilden, wobei die genannten Bilder zueinander um einen Abstand verschoben sind, der gleich der halben Gitterperiode des zweiten Gitters ist, daß ein Polarisationsdrehglied (66) zwischen dem zweiten Gitter (G₂) und einem Detektor (DE₁, DE₂) zum periodischen Verändern der Polarisationsrichtung der Teilstreifenbündel angeordnet ist, und daß ein Polarisationsdrehglied (66) und dem Detektor (DE₁, DE₂) angeordnet ist, wobei das periodische Signal auch einer elektronischen Schaltung (70) zugeführt wird zum Verarbeiten des Ausgangssignals des Detektors zu einem Fokusfehlersignal.

10. Abbildungsgerät nach Anspruch 6, 7, 8 oder 9, dadurch gekennzeichnet, daß eine gesonderte Strahlungsquelle (S₂) zum Liefern des Bezugsstrahlenbündels (b₅) vorgesehen ist, daß ein erstes Strahlenbündel ablenkendes Element (WO₁) zwischen den Strahlungsquellen (S₁, S₂) und der zweiten Ebene (WS) soeben im Weg des Fokudetektionsstrahlenbündels (b₅) als auch des Bezugsstrahlenbündels (b₃) angeordnet ist zum Fichten der genannten Strahlenbündel auf die zweite Ebene bzw. die Oberfläche (Rp) des Abbildungssystems (PL) und daß ein zweites ein Strahlenbündel ablenkendes Element (WO₂) zwischen der zweiten Ebene (WS) und den beiden Detektoren (DE₁, DE₂) soeben im Weg des Fokudetektionsstrahlenbündels als auch des Bezugsstrahlenbündels angeordnet ist zum Fichten der genannten Strahlenbündel auf die ersten bzw. den zweiten Detektor.

11. Abbildungsgerät nach Anspruch 6, 7, 8 oder 9, dadurch gekennzeichnet, daß eine gesonderte Strahlungsquelle zum Liefern des Bezugsstrahlenbündels (b₅) vorgesehen ist, daß ein Strahlenbündel ablenkendes Element (WO₁) zwischen den Strahlungsquellen (S₁, S₂) und der zweiten Ebene (WS) sowohl im Weg des Fokudetektionsstrahlenbündels (b₅) als auch des Bezugsstrahlenbündels (b₅) angeordnet ist, daß ein Retoreffektor (RE) im Weg des ein erstes Mal an der zweiten Ebene (WS) reflektierten Fokudetektionsstrahlenbündels (b₅) und des ein erstes Mal an der Oberfläche (Rp) des Abbildungssystems (PL) reflektierten Bezugsstrahlenbündels (b₅) angeordnet ist, daß ein erstes Strahlenbündel trennendes Element (77) zum Auskoppeln des Fokudetektionsstrahlenbündels (b₅) zum ersten Detektor (DE₁) im Weg des ein zweites Mal an der zweiten Ebene (WS) reflektierten genannten Strahlenbündels angeordnet ist, während ein zweites Strahlenbündel trennendes Element (78) zum Auskoppeln des Bezugsstrahlenbündels (b₅) zum zweiten Detektor (DE₂) im Weg des ein
zweites Mal an der Oberfläche (Rp) des Abbildungssystems (PL) reflektierten genannten Strahlenbündels angeordnet ist.

12. Abbildungsgerät nach Anspruch 6, 7, 8 oder 9, dadurch gekennzeichnet, daß ein erstes doppeltbrechendes Element (80; 90; 100) im Weg des von der Strahlungsquelle (S) gelieferten Strahlenbündels (b₁) angeordnet ist, zum Auffetten des genannten Strahlenbündels in ein Fokuskotektionsstrahlenbündel (b₂) mit einer ersten Polarisationsrichtung und ein Bezugstrahlenbündel (b₃) mit einer zweiten Polarisationsrichtung und zum Richten der genannten Strahlenbündel auf die zweite Ebene (WS) bzw. die Oberfläche (Rp) des Abbildungssystems (PL) und daß ein zweites doppeltbrechendes Element (85; 91; 102) in den Wegen der an der zweiten Ebene (WS) bzw. der Oberfläche (Rp) des Abbildungssystems reflektierten Strahlenbündels (b₁', b₃') zum Ablenenken der beiden Strahlenbündel zueinander und zum Richten der Strahlenbündel auf den ersten Detektor (DE₁) bzw. den zweiten Detektor (DE₂) angeordnet ist (Fig. 10, 11, 12).

13. Abbildungsgerät nach Anspruch 6, 7, 8 oder 9, dadurch gekennzeichnet, daß ein zusammengesetzter Reflektor (112) im Weg des an der zweiten Ebene (WS) reflektierten Fokusdetektionsstrahlenbündels (b₂') angeordnet ist, daß das Bezugstrahlenbündel (b₃) von dem am Reflektor reflektierten und auf die Oberfläche des Abbildungssystems gerichteten Strahlenbündel gebildet wird und daß der erste und der zweite Detektor in einem einzigen Detektor (DE) kombiniert sind (Fig. 13).

14. Abbildungsgerät nach Anspruch 13, dadurch gekennzeichnet, daß ein ein Strahlenbündel ablenkendes Element (110) in dem gemeinsamen Weg des von der Strahlungsquelle gelieferten Strahlenbündels (b₂) und des an der Oberfläche (Rp) des Abbildungssystems reflektierten Strahlenbündels (b₁') angeordnet ist zum Ablennen des erstgenannnten Strahlenbündels (b₂') zur zweiten Ebene (WS) und zum Ablenenken des letztgenannten Strahlenbündels (b₃) zum Detektor (DE).

15. Abbildungsgerät nach Anspruch 6, 7, 8 oder 9, dadurch gekennzeichnet, daß ein erstes doppeltbrechendes Element (120) im Weg des von der Strahlungsquelle (S) gelieferten Strahlenbündels angeordnet ist, welches Element das genannte Strahlenbündel als Fokusdetektionsstrahlenbündel zur zweiten Ebene (WS) durchläuft, daß ein zweites doppeltbrechendes Element (122) im Weg des an der genannten Ebene reflektierten Strahlenbündels (b₁') angeordnet ist, welches Element das reflektierte Strahlenbündel durchläuft, daß ein das Strahlenbündel zum zweiten doppeltbrechenden Element (122) reflektierender Retroreflektor (125) im Weg des durchgeleissten Strahlenbündels angeordnet ist, welches Element (122) das Strahlenbündel als ein Bezugstrahlenbündel (b₃) zur Oberfläche (Rp) des Abbildungssystems (PL) ablenkt, und daß das erste doppeltbrechende Element (120) das an der genannten Oberfläche (Rp) reflektierte Strahlenbündel (b₂') in Richtung des von der Strahlungsquelle gelieferten Strahlenbündels ablenkt (Fig. 14).

16. Abbildungsgerät nach Anspruch 5, 6, 7, 8 oder 9, dadurch gekennzeichnet, daß das Fokusdetektionsstrahlenbündel (b₂') ein breiter Wellenlängenband hat, daß im Strahlungsweg sowohl des Fokusdetektionsstrahlenbündels (b₂') als auch des Bezugstrahlenbündels (b₃) ein erstes Gitter (G₁) zwischen der das betreffende Strahlenbündel liefernden Quelle (S₁, S₂) und der Ebene (WS, Rp), an der das genannte Strahlenbündel das erste Mal reflektiert wird, angeordnet ist und daß ein zweites Gitter (G₂) zwischen dem Detektor (DE₁, DE₂) für das betreffende Strahlenbündel und einer das genannte Strahlenbündel zum Detektor reflektierenden Ebene angeordnet ist.

17. Abbildungsgerät nach Anspruch 10, dadurch gekennzeichnet, daß die Strahlungsquelle (S₁, S₂) ein Strahlenbündel mit einem breiten Wellenlängenband liefert und daß ein erstes Gitter (G₁) zwischen der genannten Quelle (S₁, S₂) und dem ersten Ablenkelement (WD₁) und ein zweites Gitter (G₂) zwischen dem zweitem Ablenkelement (WD₂) und dem Detektor (DE₁, DE₂) angeordnet ist.

18. Abbildungsgerät nach Anspruch 11, dadurch gekennzeichnet, daß das Fokusdetektionsstrahlenbündel (b₂') ein breiter Wellenlängenband hat, daß ein erstes Gitter (G₁) zwischen den Strahlungsquellen (S₁, S₂) und dem Ablenkelement (WO) angeordnet ist, daß ein zweites Gitter (G₂, G₂) im Strahlungsweg des reflektierten Fokusdetektionsstrahlenbündels (b₂') zwischen dem ein Strahlenbündel ablenkenden Element (WD₂) und dem ersten Detektor (DE₁) angeordnet ist und daß ein drittes Gitter (G₂, G₂) im Strahlungsweg des reflektierten Bezugstrahlenbündels (b₃) zwischen dem ein Strahlenbündel ablenkenden Element und dem zweiten Detektor (DE₂) angeordnet ist.

19. Abbildungsgerät nach Anspruch 12, dadurch gekennzeichnet, daß die Strahlungsquelle (S) ein Strahlenbündel (b₂') mit einem breiten Wellenlängenband liefert, und daß ein erstes Gitter (G₁) zwischen der Strahlungsquelle (S) und dem ersten doppeltbrechenden Element (80; 90; 100) angeordnet ist und ein zweites Gitter (G₂) zwischen dem zweiten doppeltbrechenden Element (85; 91; 102) und dem Detektor (DE₁, DE₂) angeordnet ist.
20. Abbildungsgerät nach Anspruch 13 oder 14, dadurch gekennzeichnet, daß die Strahlungsquelle (S) ein Strahlbündel mit einem breiten Wellenlängenband liefert und daß ein erstes Gitter (G1) in dem Strahlungsweg des genannten Strahlbündels zwischen der Strahlungsquelle und der zweiten Ebene (WS) und ein zweites Gitter (G2) zwischen der Oberfläche (Ro) des Abbildungssystems (PL) und dem Detektor (DE) angeordnet ist.

21. Abbildungsgerät nach Anspruch 15, dadurch gekennzeichnet, daß die Strahlungsquelle (S) ein Strahlbündel mit einem breiten Wellenlängenband liefert und daß ein erstes Gitter (G1) in dem Strahlungsweg des genannten Strahlbündels zwischen der Quelle (S) und dem ersten doppelbrechenden Element (120) und ein zweites Gitter (G2) zwischen dem genannten Element (120) und dem Detektor (DE) angeordnet ist.

22. Abbildungsgerät nach Anspruch 1 oder 6, dadurch gekennzeichnet, daß ein einstellbares optisches Element (250) vor der zweiten Ebene (WS) im Strahlungsweg des Fokuseduktionsstrahlbündels (b5) angeordnet ist zum Verlagern, unabhängig von einem Fokusfehler, des in der zweiten Ebene gebildeten Strahlungsflecks (Sp) zum Ändern des Nullpunkts des generierten Fokusfehlersignals.

23. Abbildungsgerät nach Anspruch 1, 2 oder 3, dadurch gekennzeichnet, daß es eine erste und eine zweite Detektionseinheit umfaßt zum Bestimmen von Verkantungen der zweiten Ebene um zwei zueinander senkrechte X- und Y-Achsen, wobei jede Detektionseinheit eine Strahlungsquelle (Sp1), ein erstes und ein zweites Gitter (G1, G2) und einen Detektor (DE1) umfaßt, wobei die optische Achse der ersten Ebene in der YZ-Ebene und die optische Achse der zweiten Ebene in der YZ-Ebene liegt, und daß in jeder Ebene ein erstes Linsensystem (L15) zwischen dem ersten Gitter (G1) und der zweiten Ebene (WS) angeordnet ist zum Umsetzen des vom Gitter kommenden Strahlbündels (b5) zu einem parallelen Strahlbündel, während zwischen der zweiten Ebene (WS) und dem zweiten Gitter (G2) ein zweites Linsensystem (L16) zum Umsetzen des parallelen Strahlbündels in ein konvergierendes Strahlbündel (b5') angeordnet ist.

24. Abbildungsgerät nach Anspruch 23, dadurch gekennzeichnet, daß jede Detektionseinheit Mittel (Sp2) zum Bilden eines Bezugsstrahlbündels (b7) umfaßt, das auf eine gegenüber der zweiten Ebene (WS) liegende Oberfläche (Rp) des Abbildungssystems (PL) gerichtet ist und mit der genannten Oberfläche einen kleinen Winkel bildet, und einen zweiten Detektor (DE2), der im Weg des an der Oberfläche des Abbildungssystems reflektierten Bezugsstrahlbündels (b7) angeordnet ist.

25. Abbildungsgerät nach Anspruch 1 oder 6, dadurch gekennzeichnet, daß Mittel (B1, B2') zum Liefern von zumindest zwei zusätzlichen Fokuseduktionsstrahlbündeln (h2, h3, h4) ähnlich dem genannten Fokuseduktionsstrahlbündel (h1, b5) vorgesehen sind, zum Detektieren von Verkantungen der zweiten Ebene (WS) um zwei zueinander senkrechte X- und Y-Achsen der Bildebene, daß jedes Fokuseduktionsstrahlbündel auf einen gesonderten Punkt (a, b, c, d) der zweiten Ebene gerichtet ist, wobei zumindest zwei Punkte verschiedene X-Positionen und zumindest zwei Punkte verschiedene Y-Positionen einnehmen.

26. Abbildungsgerät nach Anspruch 25, gekennzeichnet durch zwei gesonderte FokuseduktionsEinheiten (B1, B2, B3, B4) mit jeweils zwei Fokuseduktionsstrahlbündeln (h1, h2, h3, h4) wobei die Detektorsignale der beiden FokuseduktionsEinheiten zusammen Informationen über die Verkantung der zweiten Ebene um die X-Achse der Drehachse enthalten.

27. Abbildungsgerät nach Anspruch 1, 6, 23, 24, 25 oder 26, dadurch gekennzeichnet, daß jedes Gitter (G1, G2; 157, 158, 187, 188) in zwei Teilgitter unterteilt ist, die unterschiedliche Gitterperioden haben.

28. Abbildungsgerät nach Anspruch 1, 6, 23, 24, 25 oder 26, in dem die Fokuseduktionsstrahlbündel breitbandig sind und Gitter durchlaufen, dadurch gekennzeichnet, daß eine zusätzliche halbe Strahlungsquelle (Sp2) zum Liefern eines zusätzlichen, monochromatischen Fokuseduktionsstrahlbündels (b7) zum Bilden eines zusätzlichen Strahlungsflecks in der zweiten Ebene (WS) vorgesehen ist.

29. Abbildungsgerät nach Anspruch 28, gekennzeichnet durch ein zusätzliches, helles, monochromatisches Bezugsstrahlbündel (B1, b7) zum Bilden eines zusätzlichen Strahlungsflecks auf der Oberfläche (Rp) des Abbildungssystems (PL).

30. Abbildungsgerät nach Anspruch 23, 24, 25, 26, 27, 28 oder 29, dadurch gekennzeichnet, daß die Drehachse die optischen Elemente (250, 1270, 190, 191, 193, 192, 75, 205, 200) in dem Strahlungsweg zwischen den Gittern (157, 158, 187, 188) allen Fokuseduktionsstrahlbündeln (b7, b1, b7, b1) und Bezugsstrahlbündeln (b7, b1, b7, b1) gemeinsam sind.

31. Abbildungsgerät nach Anspruch 28, 29 oder 30, dadurch gekennzeichnet, daß die Wellenlänge des monochromatischen Fokuseduktionsstrahlbündels (b1, b1) im Wel-
lentillegenband der anderen Fokusdetektionsstrahlbündel ($b_{m,n}$) und Bezugstrahlbündel ($b_{i,j}$) liegt.

32. Abbildungsgerät nach Anspruch 25, 26, 27, 28, 29, 30 oder 31, dadurch gekennzeichnet, daß innerhalb einer Fokusdetektionseinheit von einem einzigen Strahlbündel ($b_{m,n}$) von dem zwei Teile auf zwei verschiedene Gitterteile (231, 232) einfallen, zwei Fokussierungsstrahlbündel gebildet werden.

33. Abbildungsgerät nach einem der Ansprüche 28 bis 32, dadurch gekennzeichnet, daß zwei Gitterteile (231, 232) des ersten Gitters (157) und des zweiten Gitters (187) auf einer ersten Gitterplatte (150) bzw. auf einer zweiten Gitterplatte (180) angeordnet sind und daß die erste Gitterplatte eine einzige erste Öffnung (264) für das monochromatische Strahlbündel ($b_{1}$) und die zweite Gitterplatte zwei zweite Öffnungen (300, 301) für das genannte Strahlbündel hat, wobei die genannten zweiten Öffnungen in bezug auf die erste Öffnung (264) symmetrisch liegen.

34. Projektionsgerät zum wiederholten Abbilden eines Maskenmusters auf einem Substrat (W), mit einem Abbildungsgerät nach Anspruch 1, 6, 23, 25, 27 oder 28, in dem das abbildende Linsensystem von einem optischen Projektionslinsensystem (PL) gebildet wird, mit dem das Muster auf das Substrat projiziert wird, und die zweite Ebene von einer Oberfläche (WS) einer zu belichtenden Substratschicht gebildet wird, wobei die Signale des Fokusdetektionsystems (FDS) zum Einstellen des Abstandes zwischen dem Substrat (W) und dem Projektionslinsensystem (PL) und/oder des Winkels zwischen der Bildebene des genannten Linsensystems und der genannten Oberfläche verwendet werden.

Revendications

1. Dispositif de reproduction comprenant un système de reproduction (PL) et un système optoélectronique de détection d'erreur de focalisation (FDS) pour déterminer un écart entre le plan de l'image du système de reproduction et un deuxième plan (WS) sur lequel l'image doit être reproduite, ledit système de détection de la focalisation comprenant une source de rayonnement (S) pour amener un faisceau de détection de la focalisation ($b_{2}$, $b_{2}'$), un détecteur sensible au rayonnement ($DE_{1}$) disposé du même côté du deuxième plan (WS) que la source de rayonnement et des éléments optiques ($L_{1}$, $L_{2}$) pour orienter le faisceau de détection de la focalisation sur le deuxième plan (WS) dans un angle minime par rapport audit plan pour modifier la vergence, autrement dit la convergence ou la divergence, du-
dit faisceau et celle du faisceau ($b_{2}'$) réfléchi par le deuxième plan et pour orienter ce dernier faisceau ($b_{2}'$) sur le détecteur, caractérisé en ce que le faisceau de détection de la focalisation ($b_{2}$, $b_{2}'$) possède une large gamme de longueurs d'onde et en ce qu'un premier ($G_{1}$) et un deuxième ($G_{2}$) réseau sont prévus, le premier réseau étant disposé dans le trajet du rayonnement entre la source du rayonnement (S) et le deuxième plan (WS) et le deuxième réseau ($G_{2}$) étant disposé entre ledit deuxième plan et le détecteur DE, la période de réseau de l'image du premier réseau ($G_{1}$) formée dans le plan du deuxième réseau ($G_{2}$) étant égale à la période du deuxième réseau et les lignes de réseau de ladite image s'étendant dans la même direction que les lignes de réseau du deuxième réseau.

2. Dispositif de reproduction selon la revendication 1, caractérisé en ce que des moyens (61, 66, 67) sont prévus pour déplacer périodiquement l'un par rapport à l'autre l'image ($G_{1}'$) du premier réseau ($G_{1}$) et le deuxième réseau ($G_{2}'$) perçu par le détecteur DE.

3. Dispositif de reproduction selon la revendication 2, caractérisé en ce qu'un élément optique (66) contrôlé par un signal électrique périodique ($V_{h}$) est disposé dans le trajet du faisceau de détection de la focalisation ($b_{2}'$), une propriété optique dudit élément variant périodiquement sous l'influence du signal électrique.

4. Dispositif de reproduction selon la revendication 3, caractérisé en ce qu'un élément sensible à la polarisation (61) est disposé à l'avant du deuxième réseau ($G_{2}$) pour fractionner le faisceau de détection de la focalisation ($b_{2}'$) en deux sous-faisceaux qui forment des images du premier réseau dans le plan du deuxième réseau, lesdites images étant décalées l'une par rapport à l'autre sur une distance égale à la moitié de la période de réseau du deuxième réseau, en ce qu'un dispositif de rotation de la polarisation (66) est disposé entre le deuxième réseau ($G_{2}$) et le détecteur (DE), lequel dispositif de rotation est commandé par un signal périodique ($V_{h}$) pour faire varier périodiquement la direction de la polarisation des sous-faisceaux et en ce qu'un analyseur de polarisation (67) est disposé entre le dispositif de rotation de la polarisation et le détecteur, le signal périodique étant également appliqué à un circuit électronique (70) pour traiter le signal de sortie du détecteur ($S_{DE}$) en un signal de contrôle de la focalisation.

5. Dispositif de reproduction selon l'une des revendications 1, 2, 3 ou 4, caractérisé en ce qu'un rétro-réflecteur (RE) est disposé sur le trajet du faisceau de détection de la focalisation ($b_{2}'$) réfléchi une pre-
mière fois par le deuxième plan (WS), lequel rétro-réflecteur réfléchit le faisceau le long de lui-même et en ce qu'un élément séparateur de faisceau (B₃) est disposé entre le deuxième plan (WS) et la source de rayonnement (S) sur le trajet du faisceau de détection de la focalisation (b₂) réfléchi une deuxième fois par le deuxième plan, ledit élément séparateur de faisceau coupant le faisceau réfléchi deux fois (b₂) vers le deuxième réseau (G₂) et le détecteur (DE) disposé derrière lui.

6. Dispositif de reproduction comprenant un système de reproduction (PL) et un système optoelectronique de détection d'erreur de focalisation (FD5) pour déterminer un écart entre le plan d'image du système de reproduction et un deuxième plan (WS) sur lequel l'image doit être formée, ledit système de détection d'erreur de focalisation comprenant une source de rayonnement (S) pour amener un faisceau de détection de la focalisation (b₂), un détecteur sensible au rayonnement (DE₁) disposé du même côté du deuxième plan (WS) que la source de rayonnement et des éléments optiques (L₁, L₂) pour diriger le faisceau de détection de la focalisation sur le deuxième plan dans un angle minime par rapport à l'audit plan pour modifier la vergence, autrement dit la convergence ou la divergence, dudit faisceau et celle du faisceau réfléchi par le deuxième plan et pour diriger ce dernier faisceau sur le détecteur, caractérisé en ce qu'un faisceau de référence (b₁) est prévu et orienté sur une surface (Rp) du système de reproduction (PL) situé à l'opposé du deuxième plan (WS) et s'étend dans un angle minime par rapport à ladite surface et un deuxième détecteur (DE₂) disposé sur le trajet du faisceau de référence (b₁) réfléchi par la surface (Rp), un premier (G₁) et un deuxième (G₂) réseaux étant disposés dans le trajet du faisceau de référence (b₁) et les moyens optiques (L₁, L₂) disposés entre le premier et deuxième réseaux pour diriger et modifier la vergence étant communs aux deux faisceaux (b₁, b₂), la période de réseau de l'image du premier réseau (G₁) formée dans le plan du deuxième réseau (G₂) étant égale à cette période du deuxième réseau et les lignes du réseau de ladite image s'étendant dans la même direction que les lignes du réseau du deuxième réseau.

7. Dispositif de reproduction selon la revendication 6, caractérisé en ce que des moyens (61, 66, 67) sont prévus pour le faisceau de détection de la focalisation (b₂) et le faisceau de référence (b₁) pour déplacer périodiquement l'un par rapport à l'autre l'image (G₁) du premier réseau (G₁) et le deuxième réseau (G₂) qui sont perçus par le détecteur (DE₁, DE₂) pour le faisceau correspondant.

8. Dispositif de reproduction selon la revendication 7, caractérisé en ce qu'un élément optique (66) contrôlé par un signal électrique périodique (V₆) est disposé dans les trajets du faisceau de détection de la focalisation (b₂) et du faisceau de référence (b₁), une propriété optique dudit élément (66) variant périodiquement sous l'influence du signal électrique (V₆).

9. Dispositif de reproduction selon la revendication 6, caractérisé en ce qu'un élément sensible à la polarisation (61) est disposé à l'avant du deuxième réseau (G₂) dans les trajets du faisceau de détection de la focalisation (b₂) du faisceau de référence (b₁) pour fractionner chaque faisceau de détection de la focalisation (b₂) et faisceau de référence en deux sous-faisceaux qui forment des images du premier réseau (G₁) dans le plan du deuxième réseau (G₂), lesdites images étant décalées l'une par rapport à l'autre sur une distance égale à la moitié de la période de réseau du deuxième réseau, en ce qu'un dispositif de rotation de la polarisation (66) est disposé entre un deuxième réseau (G₂) et un détecteur (DE₁, DE₂) pour faire varier périodiquement la direction de la polarisation des sous-faisceaux et en ce qu'un analyseur de polarisation (67) est disposé entre le dispositif de rotation de la polarisation (66) et le détecteur (DE₁, DE₂), le signal périodique (V₆) étant également appliqué à un circuit électronique (70) pour traiter le signal de sortie des détecteurs en un signal d'erreur de focalisation.

10. Dispositif de reproduction selon l'une des revendications 6, 7 ou 9, caractérisé en ce qu'une source de rayonnement séparée (S₂) pour amener le faisceau de référence (b₁) est prévue, en ce qu'un premier élément déflecteur de faisceau (W₀₁) est disposé entre les sources de rayonnement (S₁, S₂) et le deuxième plan (WS) sur le trajet du faisceau de détection de la focalisation (b₂) ainsi que du faisceau de référence (b₁) pour orienter respectivement lesdits faisceaux sur le deuxième plan et la surface (Rp) du système de reproduction (PL) et en ce qu'un deuxième élément déflecteur de faisceau (W₀₂) est disposé entre le deuxième plan (WS) et les deux détecteurs (DE₁, DE₂) sur le trajet du faisceau de détection de la focalisation ainsi que du faisceau de référence pour orienter lesdits faisceaux respectivement sur les premier et deuxième détecteurs.

11. Dispositif de reproduction selon l'une des revendications 6, 7 ou 9, caractérisé en ce qu'une source de rayonnement séparée est prévue pour alimenter le faisceau de référence (b₁), en ce qu'un élément déflecteur de faisceau (W₀) est disposé entre les sources de rayonnement (S₁, S₂) et le deuxième plan (WS) sur le trajet du faisceau de détection de la focalisation (b₁), en ce qu'un rétro-réflecteur (RE) est disposé.
sur le trajet du faisceau de détection de la focalisation \((b_2)\) réfléchi une première fois par le deuxième plan (WS) et du faisceau de référence \((b_0)\) réfléchi une première fois par la surface \((R_p)\) du système de reproduction \((P_L)\) et en ce qu'un premier élément séparateur de faisceau \((77)\) pour coupler le faisceau de détection de la focalisation \((b_2)\) vers le premier détecteur \((D_{E_1})\) est disposé sur le trajet dudit faisceau réfléchi une deuxième fois par le deuxième plan (WS) tandis qu'un deuxième élément séparateur de faisceau \((78)\) pour coupler le faisceau de référence \((b_0)\) vers le deuxième détecteur \((D_{E_2})\) est disposé sur le trajet dudit faisceau réfléchi une deuxième fois par la surface \((R_p)\) du système de reproduction \((P_L)\).

12. Dispositif de reproduction selon l'une des revendications 6, 7, 8 ou 9, caractérisé en ce qu'un premier élément biréfringent \((80; 90; 100)\) est disposé sur le trajet du faisceau \((b_0)\) alimenté par la source de rayonnement \((S)\) pour fractionner ledit faisceau en un faisceau de détection de la focalisation \((b_2)\) possédant une première direction de polarisation et un faisceau de référence \((b_0)\) possédant une deuxième direction de polarisation et pour diriger respectivement lesdits faisceaux sur le deuxième plan (WS) et la surface \((R_p)\) du système de reproduction \((P_L)\) et en ce qu'un deuxième élément biréfringent \((85; 91; 102)\) est disposé sur les trajets des faisceaux \((b'_1, b'_2)\) réfléchis respectivement par le deuxième plan (WS) et la surface \((R_p)\) du système de reproduction pour dévier les deux faisceaux l'un vers l'autre et pour diriger respectivement les faisceaux sur le premier détecteur \((D_{E_1})\) et le deuxième détecteur \((D_{E_2})\) (Fig. 10, 11, 12).

13. Dispositif de reproduction selon l'une des revendications 6, 7, 8 ou 9, caractérisé en ce qu'un réflecteur composite \((112)\) est disposé sur le trajet du faisceau de détection de la focalisation \((b'_2)\) réfléchi par le deuxième plan (WS), en ce que le faisceau de référence \((b_0)\) est formé par le faisceau réfléchi par le réflecteur et dirigé sur la surface \((R_p)\) du système de reproduction et en ce que les premiers et deuxième détecteurs sont combinés en un seul détecteur \((D_E)\) (Fig. 13).

14. Dispositif de reproduction selon la revendication 13, caractérisé en qu'un élément défecteur de faisceau \((110)\) est disposé sur le trajet commun du faisceau \((b_0)\) amené par la source de rayonnement et du faisceau \((b'_2)\) réfléchi par la surface \((R_p)\) du système de reproduction pour dévier le premier faisceau \((b_0)\) vers le deuxième plan (WS) et dévier le dernier faisceau \((b'_2)\) vers le détecteur \((D_E)\).

15. Dispositif de reproduction selon l'une des revendications 6, 7, 8 ou 9, caractérisé en ce qu'un premier élément biréfringent \((120)\) est disposé sur le trajet du faisceau \((b_0)\) amené par la source de rayonnement \((S)\), lequel élément fait passer ledit faisceau comme un faisceau de détection de la focalisation vers le deuxième plan (WS), en ce qu'un deuxième élément biréfringent \((122)\) est disposé dans le trajet du faisceau \((b'_2)\) réfléchi par ledit plan, lequel élément fait passer le faisceau réfléchi, en ce qu'un rétrodéflecteur \((125)\) réfléchissant le faisceau vers le deuxième élément biréfringent \((122)\) est disposé sur le trajet du faisceau passé, lequel élément \((122)\) dévie le faisceau comme un faisceau de référence \((b_0)\) vers la surface \((R_p)\) du système de reproduction \((P_L)\) et en ce que le premier élément biréfringent \((120)\) dévie le faisceau \((b'_2)\) réfléchi par ladite surface \((R_p)\) dans la direction du faisceau fourni par la source de rayonnement (Fig. 14).

16. Dispositif de reproduction selon l'une des revendications 5, 6, 7, 8 ou 9 caractérisé en ce que le faisceau de détection de la focalisation \((b_0)\) a une large gamme de longueurs d'ondes, en ce qu'un premier réseaux \((G_1)\) est disposé sur le trajet du rayonnement du faisceau de détection de la focalisation \((b_2)\) ainsi que du faisceau de référence \((b_0)\) entre la source \((S_1, S_2)\) alimentant le faisceau correspondant et le plan (WS, R_p) sur lequel ledit faisceau est réfléchi pour la première fois et en ce qu'un deuxième réseaux \((G_2)\) est disposé entre le détecteur \((D_{E_1}, D_{E_2})\) pour le faisceau correspondant et un plan réfléchissant ledit faisceau vers le détecteur.

17. Dispositif de reproduction selon la revendication 10, caractérisé en ce que la source de rayonnement \((S_1, S_2)\) alimente un faisceau possédant une large gamme de longueurs d'ondes et en ce qu'un premier réseaux \((G_1)\) est disposé entre ladite source \((S_1, S_2)\) et le premier élément défecteur \((W_{D_1})\) et un deuxième réseaux \((G_2)\) est disposé entre le deuxième élément défecteur \((W_{D_2})\) et le détecteur \((D_{E_1}, D_{E_2})\).

18. Dispositif de reproduction selon la revendication 11, caractérisé en ce que le faisceau de détection de la focalisation \((S_0)\) a une large bande de longueurs d'ondes, en ce qu'un premier réseaux \((G_1)\) est disposé entre les sources de rayonnement \((S_1, S_2)\) et l'élément défecteur \((W_0)\), en ce qu'un deuxième réseaux \((G_{2,1})\) est disposé entre l'élément défecteur de faisceau \((W_{D_1})\) et le premier détecteur \((D_{E_1})\) sur le trajet de rayonnement du faisceau de détection de la focalisation réfléchi \((b_0)\) et ce qu'un troisième réseaux \((G_{2,2})\) est disposé entre l'élément défecteur de faisceau et le deuxième détecteur \((D_{E_2})\) dans le trajet du rayonnement du faisceau de référence réfléchi \((b_0)\).

19. Dispositif de reproduction selon la revendication 12,
caractérisé en ce que la source de rayonnement (S) alimente un faisceau (b₂) possédant une large gamme de longueurs d'ondes et en ce qu'un premier réseau (G₁) est disposé entre la source de rayonnement (S) et le premier élément biréfringent (50; 90; 100) et un deuxième réseau (G₂) est disposé entre le deuxième élément biréfringent (65; 91; 102) et les détecteurs (DE₁, DE₂).

20. Dispositif de reproduction selon l'une des revendications 13 ou 14, caractérisé en ce que la source de rayonnement (S) alimente un faisceau possédant une large gamme de longueurs d'ondes et en ce qu'un premier réseau (G₁) est disposé entre la source de rayonnement et le deuxième plan (WS) dans le trajet de rayonnement dudit faisceau et un deuxième réseau (G₂) est disposé entre la surface (Rp) du système de reproduction (PL) et du détecteur (DE).

21. Dispositif de reproduction selon la revendication 15, caractérisé en ce que la source de rayonnement (S) alimente un faisceau possédant une large gamme de longueurs d'ondes et en ce qu'un premier réseau (G₁) est disposé entre la source (S) et le premier élément biréfringent (120) dans le trajet du rayonnement dudit faisceau et un deuxième réseau (G₂) est disposé entre ledit élément (120) et le détecteur (DE).

22. Dispositif de reproduction selon l'une des revendications 1 ou 6, caractérisé en ce qu'un élément optique réglable (250) est disposé à l'avant du deuxième plan (WS) sur le trajet de rayonnement du faisceau de détection de la focalisation (b₂) pour déplacer, indépendamment d'une erreur de focalisation, le point de rayonnement (Sp) formé dans le deuxième plan pour modifier le zéro du signal d'erreur de focalisation généré.

23. Dispositif de reproduction selon l'une des revendications 1, 2 ou 3, caractérisé en ce qu'il comprend des première et deuxième unités de détection pour déterminer les inclinaisons du deuxième plan autour de deux axes X et Y réciproquement perpendiculaires, chaque unité de détection comprenant une source de rayonnement (S₁), des premiers et deuxième réseaux (G₁, G₂) et un détecteur (DE₁), l'axe optique de la première unité étant situé dans le plan XZ et l'axe optique de la deuxième unité étant situé dans le plan YZ et en ce que, dans chaque unité, est disposé un premier système à lentille (L₁₁) entre le premier réseau (G₁₁) et le deuxième plan (WS) pour convertir le faisceau (b₁) du réseau en un faisceau parallèle tandis qu'un deuxième système à lentille (L₁₂) est disposé entre le deuxième plan (WS) et le deuxième réseau (G₂) pour convertir le faisceau parallèle en un faisceau convergent (b₂).

24. Dispositif de reproduction selon la revendication 23, caractérisé en ce que chaque unité de détection comprend des moyens (S₂₂) pour former un faisceau de référence (b₂) qui est orienté sur une surface (Rp) du système de reproduction (PL) situé à l'opposé du deuxième plan (WS) et s'étend dans un angle minime par rapport à ladite surface et un deuxième détecteur (DE₂) qui est disposé dans le trajet du faisceau de référence (b₁) réfléchi par la surface du système de reproduction.

25. Dispositif de reproduction selon l'une des revendications 1 ou 6, caractérisé en ce que des moyens (B₁, B₂) pour alimenter au moins deux faisceaux de détection de la focalisation supplémentaire (h₂, h₃, h₄) similaires à celui de détection de la focalisation (h₁, b₁) sont prévus pour déterminer les inclinaisons du deuxième plan (WS) autour de deux axes X et Y réciproquement perpendiculaires du plan d'image, en ce que chaque faisceau de détection de la focalisation est dirigé sur un point séparé (a, b, c, d) du deuxième plan, au moins deux points adoptant X positions différentes et au moins deux points adoptant Y positions différentes.

26. Dispositif de reproduction selon la revendication 25, caractérisé par deux unités de détection de la focalisation séparées (B₁, B₂; B₁', B₂') avec deux faisceaux de détection de la focalisation (h₁, h₂, h₃, h₄) chacun, les signaux de détecteur des deux unités de détection de la focalisation comprenant conjointement des informations sur l'inclinaison du deuxième plan autour des axes X et Y.

27. Dispositif de reproduction selon l'une des revendications 1, 6, 23, 24, 25 ou 26, caractérisé en ce que chaque réseau (G₁, G₂; 157, 158, 157, 188) est divisé en deux sous-réseaux qui ont des périodes de réseau différentes.

28. Dispositif de reproduction selon l'une des revendications 1, 6, 23, 24, 25 ou 26, dans lequel les faisceaux de détection de la focalisation ont des larges gammes de longueurs d'onde et traversent des réseaux, caractérisé en ce qu'une source de rayonnement brillant supplémentaire (260) est prévue pour alimenter un faisceau de détection de la focalisation monochromatique supplémentaire (b₁) afin de former un point de rayonnement supplémentaire dans le deuxième plan (WS).

29. Dispositif de reproduction selon la revendication 28, caractérisé par un faisceau de référence monochromatique brillant supplémentaire (b₁₁) pour former un point de rayonnement supplémentaire sur la surface (Rp) du système de reproduction (PL).
30. Dispositif de reproduction selon l'une des revendications 23, 24, 25, 26, 27, 28 ou 29, caractérisé en ce que, dans chaque unité de détection, les éléments optiques (250, 170, 190, 191, 192, 75, 205, 200) dans le trajet du rayonnement entre les réseaux (157, 158, 187, 188) sont communs pour tous les faisceaux de détection de la focalisation (b_{im}, b_1) et les faisceaux de référence (b_{ir}, b_{1r}).

31. Dispositif de reproduction selon l'une des revendications 28, 29 ou 30, caractérisé en ce que la longueur d'onde du faisceau de détection de la focalisation monochromatique (b_1) et le faisceau de référence (b_{1r}) est située dans la gamme de longueurs d'ondes des autres faisceaux de détection de la focalisation (b_{im}) et des faisceaux de référence (b_{ir}).

32. Dispositif de reproduction selon l'une des revendications 25, 26, 27, 28, 29, 30 ou 31, caractérisé en ce que, dans une unité de détection de la focalisation, deux faisceaux de focalisation sont formés par un faisceau (b_{im}) dont les deux parties sont incinérentes sur deux parties différentes du réseau (231, 232).

33. Dispositif de reproduction selon l'une quelconque des revendications 28 à 32, caractérisé en ce que deux parties de réseau (231, 232) du premier réseau (157) et du deuxième réseau (187) sont disposées respectivement sur une première plaque de réseau (150) et une deuxième plaque de réseau (180) et en ce que la première plaque de réseau comporte une première ouverture (264) pour le faisceau monochromatique (b_1) et la deuxième plaque de réseau comporte deux deuxième ouvertures (300, 301) pour l'édit faisceau, lesdites deuxième ouvertures étant disposées symétriquement par rapport à la première ouverture (264).

34. Dispositif de projection pour la reproduction répétée d'un dessin de masque (C) sur un substrat (W), comprenant un dispositif de reproduction selon l'une quelconque des revendications 1, 6, 23, 25, 27 ou 28, dans lequel le système à lentille de reproduction est formé par un système à lentille de projection optique (PL) avec lequel le dessin est projeté sur le substrat et le deuxième plan est formé par la surface (WS) d'une couche de substrat à exposer, les signaux du système de détection de la focalisation (FDS) étant utilisés pour régler la distance entre le substrat (W) et le système à lentille de projection (PL) et/ou l'angle entre le plan d'image dudit système à lentille et de ladite surface.